

# Lecture 4: Lyapunov Exponents

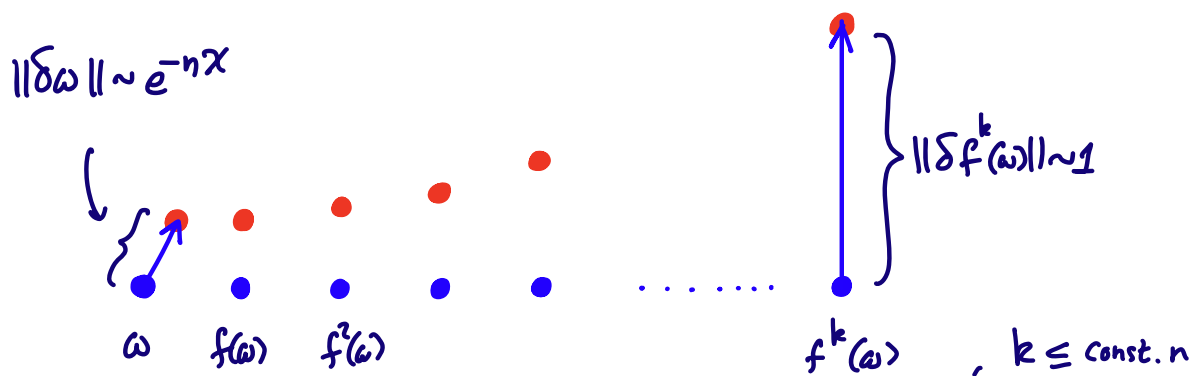
## Overview & Spoilers

Last time, we found a necessary & sufficient condition for the ability of a prob. preserving map  $f$  to produce a purely random (= Bernoulli) time series: Positive entropy

Today, we ask: What dynamical mechanisms produce positive entropy?

The Answer (volume preserving case) **Exponential sensitivity to initial conditions**:

"exponentially small perturbations in some directions grow to order one after linear number of iterations"



The precise statement is infinitesimal, so we begin with a review of some definitions from calculus on manifolds.

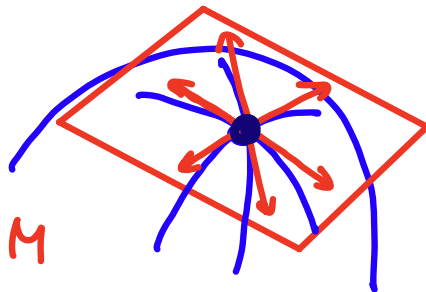
## Review of Differential Calculus on Manifolds

Setup:  $M$  is a compact smooth Riemannian manifold of dimension  $d$ , and embedded in  $\mathbb{R}^N$ ;  $f: M \rightarrow M$  differentiable

## Tangent Space at $p \in M$ :

$$T_p M := \left\{ \dot{\gamma}(0) : \begin{array}{l} \gamma: (-\epsilon, \epsilon) \rightarrow M \text{ is a smooth} \\ \text{curve s.t. } \gamma(0) = p \end{array} \right\}$$

Fact:  $T_p M$  is a linear vector space of dim  $d$

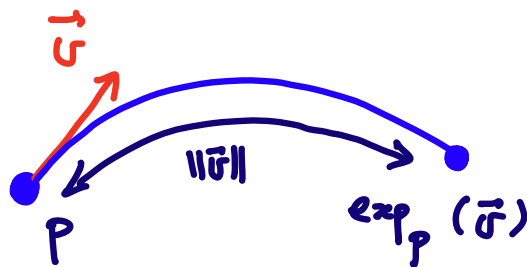


Exponential Map:  $\exp_p: T_p M \rightarrow M$

$$\exp_p(\vec{v}) = g_{\vec{v}}(\|\vec{v}\|), \text{ where } g_{\vec{v}}(t) = \text{geodesic from } p \text{ in direction } \vec{v}/\|\vec{v}\|.$$

Fact: There is  $r > 0$  s.t.

$\exp_p: \{\vec{v} : \|\vec{v}\| < r\} \rightarrow \text{image}$   
is smooth and invertible.



("radius of injectivity")

Corollary: Suppose  $f: M \rightarrow M$  is smooth, then the following map is well-defined on a neigh of the origin

$$\underbrace{\exp_{f(p)}^{-1} \circ f \circ \exp_p}_{\text{non-linear}} : \underbrace{T_p M}_{\text{linear vector space}} \longrightarrow \underbrace{T_{f(p)} M}_{\text{linear vector space}}$$

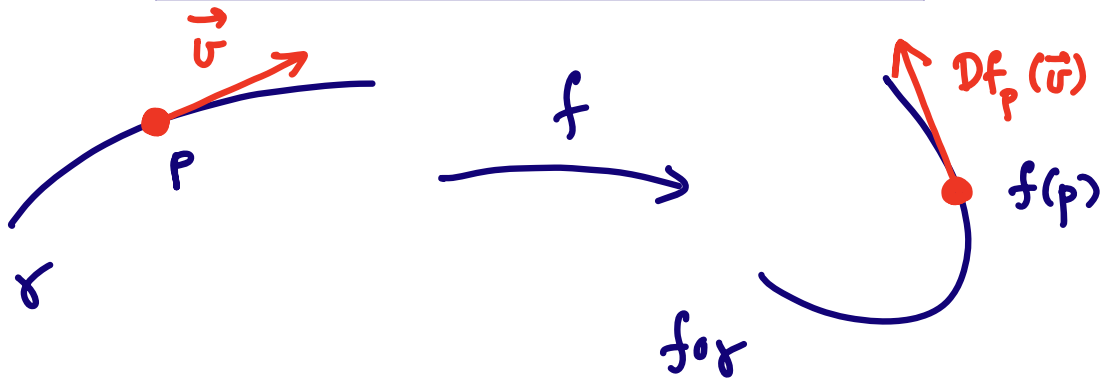
The Differential of  $f$  at  $p$ :  $Df_p: T_p M \rightarrow T_{f(p)} M$

Def 1: The linearization of  $\exp_{f(p)}^{-1} \circ f \circ \exp_p: T_p M \rightarrow T_{f(p)} M$  at  $\vec{0} \in T_p M$ , i.e. the linear map s.t.

$$(\exp_{f(p)}^{-1} \circ f \circ \exp_p)(\vec{0} + t\vec{v}) = (\exp_{f(p)}^{-1} \circ f \circ \exp_p)(\vec{0}) + t \cdot Df_p(\vec{v}) + O(t^2)$$

Def<sup>n</sup> 2 (coordinate-free formula): Every  $\vec{v} \in T_p M$  is the velocity vector  $\dot{\gamma}_{\vec{v}}(0)$  of some curve  $\gamma_{\vec{v}}(t)$  on  $M$  s.t.  $\gamma_{\vec{v}}(0) = p$ .

$$Df_p(\vec{v}) = (f \circ \gamma) \dot{\phantom{\gamma}}(0)$$



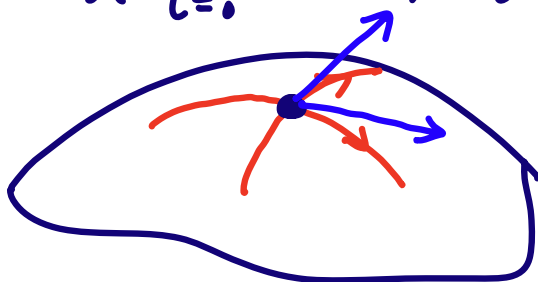
Def<sup>n</sup> 3 (formula in coordinates): Fix  $p \in M$  and two coordinate charts on neighborhoods of  $p, f(p)$ :

- $(x^1, \dots, x^d)$  near  $p$ ,  $p = (x_0^1, \dots, x_0^d)$
- $(y^1, \dots, y^d)$  near  $f(p)$ ,  $f(p) = (y_0^1, \dots, y_0^d)$

We have the following natural bases for  $T_p M, T_{f(p)} M$ :

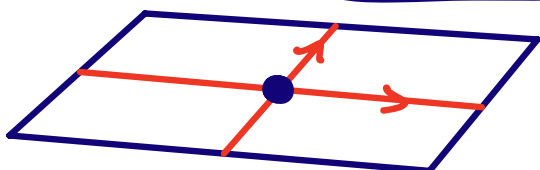
- $\vec{e}_i^p := \frac{d}{dt} \Big|_{t=0} c_i^p(t)$ ,  $c_i^p(t) = \vec{x}_0 + t \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \leftarrow i$  in coord.
- $\vec{e}_i^{f(p)} := \frac{d}{dt} \Big|_{t=0} c_i^{f(p)}(t)$ ,  $c_i^{f(p)}(t) = \vec{y}_0 + t \begin{pmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{pmatrix} \leftarrow i$  in coord

manifold



$p$

Coord chart



$$\vec{x}_0 = (x_0^1, \dots, x_0^d)$$

Represent  $f: \begin{pmatrix} \text{neigh} \\ \text{of } p \end{pmatrix} \rightarrow \begin{pmatrix} \text{neigh} \\ \text{of } f(p) \end{pmatrix}$  in coordinates

$$f(x^1, \dots, x^d) = \begin{pmatrix} y^1(x^1, \dots, x^d) \\ \vdots \\ y^d(x^1, \dots, x^d) \end{pmatrix}$$

Then  $(Df_p) \left( \sum_{i=1}^d \alpha_i \vec{e}_i^p \right) = \sum_{i=1}^d \beta_i \vec{e}_i^{f(p)}$ , where

$$\begin{pmatrix} \beta_1 \\ \vdots \\ \beta_d \end{pmatrix} = \begin{pmatrix} \frac{\partial y_i}{\partial x_j} (x_0^1, \dots, x_0^d) \\ \vdots \\ \frac{\partial y_d}{\partial x_j} (x_0^1, \dots, x_0^d) \end{pmatrix}_{d \times d} \begin{pmatrix} \alpha_1 \\ \vdots \\ \alpha_d \end{pmatrix}$$

Chain Rule:

$$Df_p^n = Df_{f^{n-1}(p)} \circ \dots \circ Df_{f(p)} \circ Df_p$$

$C^2$ -Diffeomorphism: An invertible map  $f: M \rightarrow M$   
s.t.  $f$  and  $f^{-1}$  are continuously differentiable twice,  
in coordinates.

# Lyapunov Exponents

Oseledec's Thm (part 1): Suppose  $f: M \rightarrow M$  is a diffeomorphism on a compact manifold  $M$  of  $\dim d$ , and  $\mu$  is an invariant prob measure. Then for  $\mu$ -a.e.  $p \in M$

(1) The following limit exists for all non-zero  $\vec{v} \in T_p M$ :

$$\chi_p(\vec{v}) = \lim_{n \rightarrow \pm\infty} \frac{1}{n} \log \|Df_p^n \vec{v}\|$$

(2) There are finitely many possible values

(for each  $p$ ):  $\chi_1(p) \neq \dots \neq \chi_{s(p)}(p)$  s.t.

$$\forall \vec{v} \in T_p M \setminus \{0\}, \quad \chi_p(\vec{v}) \in \{\chi_1(p), \dots, \chi_{s(p)}(p)\}$$

(3) Invariance:  $\chi_i(f(p)) = \chi_i(p)$ ,  $s(f(p)) = s(p)$

If  $\mu$  is ergodic, then  $\chi_i(p)$ ,  $s(p)$  are a.e. const.

Terminology:  $\chi_p(\vec{v})$  is called the Lyapunov exponent at  $p$  in direction  $\vec{v}$ .

Observe: If  $\chi_p(\vec{v}) > 0$ , then we have exponential sensitivity to initial conditions at  $p$ :

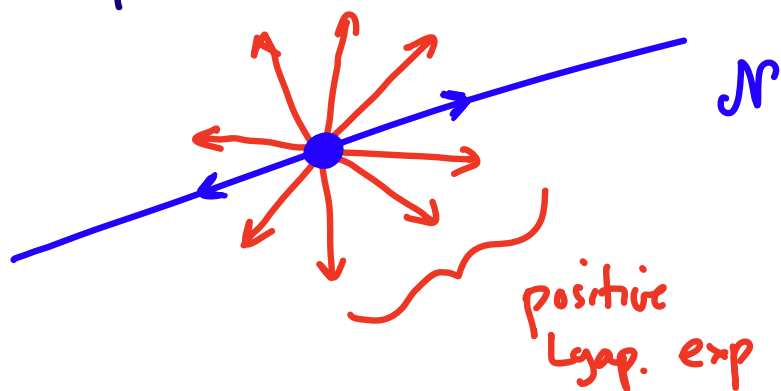
$$f^k \left( \exp_p \left( \vec{v} + e^{-n\chi/2} \vec{v} \right) \right) \approx \exp_{f(p)} \left( e^{-n\chi/2} Df_p^k(\vec{v}) \right)$$

exp. small part. of  $p$

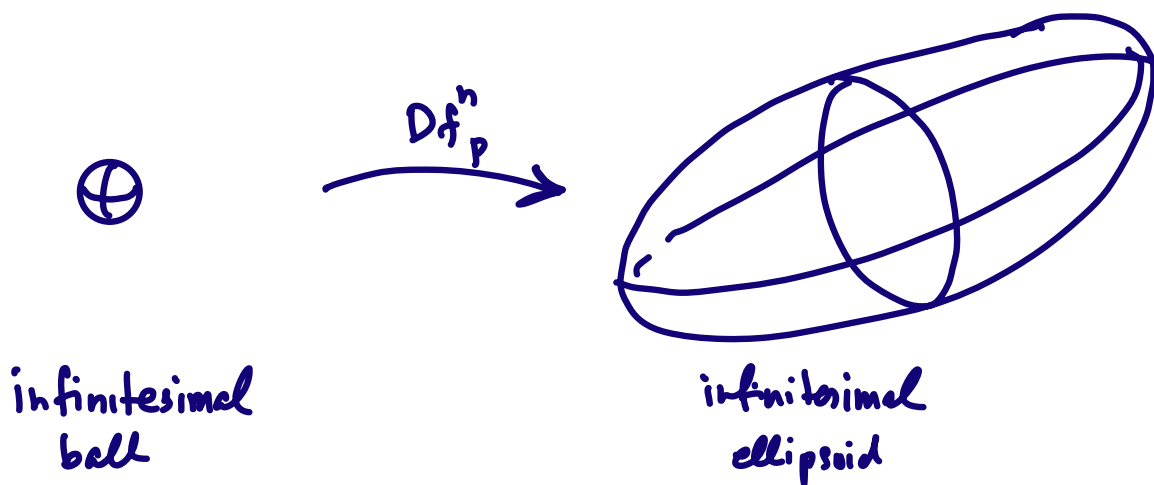
size  $e^{(k-n\chi/2)\chi}$  will be big for some  $1 \leq k \leq n$ .

Remark: If  $\chi_p(\vec{v}) > 0$  for some  $\vec{v} \in T_p M$ , then  $\chi_p(\vec{v}) > 0$  for "most"  $\vec{v} \in T_p M$ .

Indeed,  $\mathcal{N} = \{ \vec{u} \in T_p M \mid \chi_p(\vec{u}) \leq 0 \} \cup \{ \vec{0} \}$  is a linear vector space (exercise), of dimension  $\leq \dim T_p M$  (because it's  $\neq T_p M$ ).



Remark 2: In the volume preserving case, if there is a  $\vec{v}$  with positive Lyap exponent, then there must also be a  $\vec{v}$  with a negative Lyap. exp. Otherwise,  $f^n$  expands the volume exponentially, which is impossible, since  $M$  is compact.



## Multiplicities of Lyapunov Exponents

Suppose the Lyapunov exponents at  $p$  are  $\chi_1 \geq \dots \geq \chi_s$ . In general,  $s \neq d$ , so we feel that some  $\chi_i$  must appear with a "multiplicity". How to define it?

Attempt 1 (fails):  $m_i \stackrel{?}{=} \dim \{ \vec{v} \in T_p M : \chi_p(\vec{v}) = \chi_i \} \cup \{ \vec{0} \}$

This fails, because  $\{ \vec{v} : \chi_p(\vec{v}) = \chi_i \}$  is not a vector space. Choose  $\vec{v}_1, \vec{v}_2$  s.t.  $\chi_p(\vec{v}_1) < \chi_p(\vec{v}_2)$ .

Let  $u_{\pm} = \vec{v}_2 \pm \vec{v}_1$

$$\bullet \chi_p(u_{\pm}) = \lim_{n \rightarrow \infty} \frac{1}{n} \log \| Df^n(\vec{v}_2) \pm Df^n(\vec{v}_1) \| = \chi_p(\vec{v}_2)$$

$e^{n\chi_2} \Rightarrow e^{n\chi_1}$

$$\bullet \chi_p(u_+ - u_-) = \chi_p(2\vec{v}_1) = \chi_p(\vec{v}_1)$$

So  $u_+, u_- \in \{ \vec{v} : \chi_p(\vec{v}) = \chi_i \}$ , but  $u_+ - u_- \notin \{ \vec{v} : \chi_p(\vec{v}) = \chi_i \}$ .

Attempt 2 (succeeds): Define

$$V_{\chi_i} = \{ \vec{u} \in T_p M : \chi(\vec{u}) \leq \chi_i \} \cup \{ \vec{0} \}$$

These are linear spaces (check!), and

$$(*) \{ \vec{0} \} \subsetneq V_{\chi_s} \subsetneq V_{\chi_{s-1}} \subsetneq \dots \subsetneq V_{\chi_1} = T_p M$$

Def<sup>n</sup>. (\*) is called the Lyapunov filtration.

The multiplicity of  $\chi_i$  is defined to be

$$m_i := \dim V_{\chi_i} - \dim V_{\chi_{i-1}}$$

# Lyapunov Exponents and Entropy

Thm (Ruelle's Inequality): Suppose  $f: M \rightarrow M$  is a diffeomorphism on a compact manifold, which preserves a finite invariant measure  $\mu$ . Let  $\chi_1(p) \geq \dots \geq \chi_{s(p)}(p)$  be the Lyapunov exponents, and let  $m_1(p), \dots, m_{s(p)}(p)$  be their multiplicities. Then

$$h_\mu(f) \leq \int_M \sum_{i: \chi_i(p) > 0} m_i(p) \chi_i(p) d\mu$$

Corollary: If  $\mu$  is ergodic, and  $h_\mu(f) > 0$ , then  $f$  has exponential sensitivity to initial conditions  $\mu$ -a.e.

Thm (Pesin Entropy Formula): Under the above conditions, if  $\mu$  is smooth (i.e.  $\mu = \text{density} \times \text{volume measure}$ ), then

$$h_\mu(f) = \int_M \sum_{i: \chi_i(p) > 0} m_i(p) \chi_i(p) d\mu$$

Corollary: In the volume preserving case, the entropy is positive if and only if there is exponential sensitivity to initial conditions on a set with positive volume.



# The Oseledets Decomposition

Oseledets Thm (Part 2): Let  $f$  be a diffeomorphism on a compact smooth manifold  $M$ , and suppose  $\mu$  is an invariant prob. measure. Let  $\chi_1(p) \geq \dots \geq \chi_{s(p)}(p)$  denote the Lyapunov exponents, and let  $m_1(p), \dots, m_{s(p)}(p)$  be their multiplicities. For  $\mu$ -a.e.  $p \in M$  we can decompose

$$T_p M = H_{\chi_1}(p) \oplus \dots \oplus H_{\chi_{s(p)}}(p) \quad \text{s.t.}$$

(1)  $H_{\chi_i}(p)$  are linear vector spaces of dim  $m_i(p)$

(2)  $\chi_p(\vec{v}) = \chi_i(p)$  on  $H_{\chi_i}(p) \setminus \{0\}$

(3) Invariance:  $Df_p[H_{\chi_i}(p)] = H_{\chi_i}(f(p))$

(4)  $\lim_{n \rightarrow \infty} \frac{1}{n} \log | \angle(H_{\chi_i}(f^n(p)), H_{\chi_j}(f^n(p))) | = 0 \quad (i \neq j)$

Application 1: For each  $\vec{v}_i \in H_{\chi_i} \setminus \{0\}$ ,  $\chi_p(\vec{v}_i) = \chi_i$

$$\Rightarrow \|Df_p^n(\vec{v}_i)\| = e^{n\chi_i + o(n)} \|\vec{v}_i\|.$$

Thus, the Oseledets Decomposition  $\vec{v} = \vec{v}_{\chi_1} + \dots + \vec{v}_{\chi_s}$

splits  $\vec{v}$  into components with different exp rates of growth

## Application 2: "Diagonalization" of $Df_p^n$ .

For simplicity, suppose  $\dim M = 2$ , and assume  $\mu$  is ergodic, with positive entropy.

- By Ruelle's inequality, some Lyap. exp. is positive
- Also, some Lyap exp. is negative:

$h_\mu(f^{-1}) \equiv h_\mu(f) > 0$ , so by Ruelle's inequality  
check!

for  $\mu$ -a.e.  $p$ ,  $\exists \vec{v} \in T_p M$  s.t.

$$\begin{aligned} 0 < \chi_p(f^{-1}, \vec{v}) &= \lim_{n \rightarrow \pm\infty} \frac{1}{n} \log \| Df_p^{-n} \vec{v} \| \\ &= \lim_{n \rightarrow \pm\infty} \frac{1}{-n} \log \| Df_p^{+n} \vec{v} \| = -\chi_p(f, \vec{v}) \end{aligned}$$

$$\Rightarrow \chi_p(f, \vec{v}) < 0.$$

Thus we must have two different Lyapunov exponents, one  $\chi^u$  positive, and one  $\chi^s$  negative.

Necessarily, in the Oseledec's decompos<sup>n</sup>

$$T_p M = H_{\chi^u}(p) \oplus H_{\chi^s}(p)$$

$H_{\chi^u}(p)$  and  $H_{\chi^s}(p)$  are one-dimensional.

Choose unit vectors  $\underbrace{\vec{e}^u(p) \in H_{\chi^u}(p)}_{\text{"unstable" direction}}, \underbrace{\vec{e}^s(p) \in H_{\chi^s}(p)}_{\text{"stable" direction}}.$

By the invariance property  $Df_p(H_{\chi_i}(p)) = H_{\chi_i}(f(p))$ ,  
 $Df_p[\text{Span}\{\vec{e}^t(p)\}] = \text{Span}\{\vec{e}^t(f(p))\}$  ( $t=u,s$ )

Therefore

$$(Df_p)(\vec{e}^u(p)) = \pm \|Df_p \vec{e}^u(p)\| \cdot \vec{e}^u(f(p))$$

$$(Df_p)(\vec{e}^s(p)) = \pm \|Df_p \vec{e}^s(p)\| \cdot \vec{e}^s(f(p))$$

Define  $C_p: \mathbb{R}^2 \rightarrow T_p M$  by

$C_p \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \alpha(p) \vec{e}^s(p), \quad C_p \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \beta(p) \vec{e}^u(p)$   
 ( $\alpha(\cdot), \beta(\cdot)$  to be determined later). Then

$$\begin{aligned} \begin{pmatrix} 1 \\ 0 \end{pmatrix} &\xrightarrow{C_p} \alpha(p) \vec{e}^s(p) \xrightarrow{Df_p} \alpha(p) \|Df_p \vec{e}^s(p)\| \vec{e}^s(f(p)) \\ &\xrightarrow{C_{f(p)}^{-1}} \pm \frac{\alpha(p)}{\alpha(f(p))} \|Df_p \vec{e}^s(p)\| \begin{pmatrix} 1 \\ 0 \end{pmatrix} \end{aligned}$$

We obtained:

$$\left( C_{f(p)}^{-1} \circ Df_p \circ C_p \right) \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \pm \frac{\alpha(p)}{\alpha(f(p))} \| Df_p e^s(p) \| \cdot \begin{pmatrix} 1 \\ 0 \end{pmatrix}$$

Similarly,

$$\left( C_{f(p)}^{-1} \circ Df_p \circ C_p \right) \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \pm \frac{\beta(p)}{\beta(f(p))} \| Df_p e^s(p) \| \cdot \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

In summary

$$C_{f(p)}^{-1} \circ Df_p \circ C_p = \begin{pmatrix} \lambda^u(p) & 0 \\ 0 & \lambda^s(p) \end{pmatrix}$$

where  $\lambda^u(p) = \pm \frac{\alpha(p)}{\alpha(f(p))} \| Df_p \bar{e}^s(p) \|$

$$\lambda^s(p) = \pm \frac{\beta(p)}{\beta(f(p))} \| Df_p \bar{e}^u(p) \|^2$$

A "good choice" of  $\alpha(p), \beta(p)$  gives:

Oseledec - Pesin Reduction: Can construct  $C_p: \mathbb{R}^2 \rightarrow \mathbb{T}^n$

so that

$$C_{f(p)}^{-1} \circ Df_p \circ C_p = \begin{pmatrix} \lambda^u(p) & 0 \\ 0 & \lambda^s(p) \end{pmatrix}, \quad \begin{aligned} |\lambda^u(p)| &> e^{\chi_u - \varepsilon} > 1 \\ |\lambda^s(p)| &< e^{\chi_s + \varepsilon} < 1 \end{aligned}$$

In higher dim, the Oseledec-Pesin Reduction says that for some family of  $C_P$ ,

$$C_{f(p)}^{-1} Df_P^n C_P = \begin{pmatrix} B_{\chi_1}^{(n)} & & 0 \\ & \ddots & \\ 0 & & B_{\chi_s}^{(n)} \end{pmatrix}$$

where  $B_{\chi_i}^{(n)}$  are  $m_i \times m_i$  blocks ( $m_i = \text{mult. of } \chi_i$ ) s.t.

$$\|B_{\chi_i}^{(n)} \vec{v}\| = e^{n(\chi_i \pm \varepsilon)} \|\vec{v}\| \quad \text{on } \mathbb{R}^{m_i}.$$

Summary: The Oseledec Thm allows to choose bases  $\{C_P \begin{pmatrix} 1 \\ \vdots \\ 0 \end{pmatrix}, \dots, C_P \begin{pmatrix} 0 \\ \vdots \\ 1 \end{pmatrix}\}$  for  $T_P M$  in such a way that  $C_{f(p)}^{-1} \circ Df_P^n \circ C_P$  have diagonal block form.

In the two-dimensional, positive entropy, case, the resulting form is a **hyperbolic diagonal matrix**

$$C_{f(p)}^{-1} \circ Df_P^n \circ C_P = \begin{pmatrix} \lambda_u^{(n)} & 0 \\ 0 & \lambda_s^{(n)} \end{pmatrix}, \quad \begin{array}{l} |\lambda_u^{(n)}| > e^{n(\lambda_u - \varepsilon)} \gg 1 \\ |\lambda_s^{(n)}| < e^{n(\lambda_s + \varepsilon)} \ll 1 \end{array}$$