

MEAN-FIELD GAP EQUATION

In this supplement we will obtain the self-consistent mean-field gap equation for the case in-which the gap function depends on frequency. To obtain the mean-field gap equation we consider a system of fermions Fermions with an attractive interaction g (see tutorial #4) and decouple it using the HS transformation into the BCS channel

$$\begin{aligned}
 S_{HS} &= \int \frac{d\tau d^d x}{(2\pi)^{d+1}} \left[\sum_{s=\uparrow, \downarrow} \bar{\psi}_s(\mathbf{x}, \tau) \left(\partial_\tau - \frac{\nabla^2}{2m} - \mu \right) \psi_s(\mathbf{x}, \tau) \right. \\
 &\quad \left. + \Delta(\mathbf{x}, \tau) \bar{\psi}_\uparrow(\mathbf{x}, \tau) \bar{\psi}_\downarrow(\mathbf{x}, \tau) + \bar{\Delta}(\mathbf{x}, \tau) \psi_\downarrow(\mathbf{x}, \tau) \psi_\uparrow(\mathbf{x}, \tau) - \frac{|\Delta(\mathbf{x}, \tau)|^2}{g} \right] \\
 &= \int \frac{d\tau d^d x}{(2\pi)^{d+1}} \left[\bar{\Psi}(\mathbf{x}, \tau) \mathcal{G}^{-1} \Psi(\mathbf{x}, \tau) - \frac{|\Delta(\mathbf{x}, \tau)|^2}{g} + const \right]
 \end{aligned} \tag{1}$$

where $\bar{\Psi} = (\bar{\psi}_\uparrow, \psi_\downarrow)$ and

$$\mathcal{G}^{-1} = \begin{pmatrix} \partial_\tau - \frac{\nabla^2}{2m} - \mu & \Delta(\mathbf{x}, \tau) \\ \bar{\Delta}(\mathbf{x}, \tau) & \partial_\tau + \frac{\nabla^2}{2m} + \mu \end{pmatrix}$$

The mean-field solution of this action is equivalent to seeking it's saddle point, which essentially means neglecting all of the quantum fluctuation effects. To find the saddle point solution for $\Delta(\mathbf{x}, \tau)$ we take a variation of the action with respect to $\bar{\Delta}(\mathbf{x}, \tau)$ and average over Fermi feilds.

$$\frac{\delta S_{HS}}{\delta \bar{\Delta}} = -\frac{1}{g} \Delta(\mathbf{x}, \tau) + \langle \psi_\uparrow(\mathbf{x}, \tau) \psi_\downarrow(\mathbf{x}, \tau) \rangle = 0$$

which gives

$$\Delta(\mathbf{x}, \tau) = g(\tau) \langle \psi_\uparrow(\mathbf{x}, \tau) \psi_\downarrow(\mathbf{x}, \tau) \rangle = g(\tau) F(\mathbf{x}, \tau) \tag{2}$$

where the expectation value, which we have denoted by F , is known as the anomalous Green's function. To obtain an expression for F let's look at the definition of the Green's function

$$\mathcal{G}(\mathbf{x}, \tau) = \begin{pmatrix} G^e(\mathbf{x}, \tau) & F(\mathbf{x}, \tau) \\ \bar{F}(\mathbf{x}, \tau) & G^h(\mathbf{x}, \tau) \end{pmatrix} = \begin{pmatrix} \langle \bar{\psi}_\uparrow \psi_\uparrow \rangle & \langle \psi_\uparrow \psi_\downarrow \rangle \\ \langle \psi_\downarrow \bar{\psi}_\uparrow \rangle & \langle \psi_\downarrow \psi_\downarrow \rangle \end{pmatrix}$$

which is defined by the operatorial relation $\mathcal{G}^{-1} \mathcal{G} = \mathbf{1}$ or more explicitly

$$\begin{pmatrix} \partial_\tau - \frac{\nabla^2}{2m} - \mu & \Delta(\mathbf{x}, \tau) \\ \bar{\Delta}(\mathbf{x}, \tau) & \partial_\tau + \frac{\nabla^2}{2m} + \mu \end{pmatrix} \begin{pmatrix} G^e(\mathbf{x}, \tau) & F(\mathbf{x}, \tau) \\ \bar{F}(\mathbf{x}, \tau) & G^h(\mathbf{x}, \tau) \end{pmatrix} = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix} \tag{3}$$

To shorten notations we will from now on omit the \mathbf{x} and τ indices (Keep in mind that the multiplications in this matrix equation are matrix multiplications in the space of τ and \mathbf{x}). The equation above gives us the identities

$$\left(\partial_\tau - \frac{\nabla^2}{2m} - \mu \right) F + \Delta G^h = 0 \tag{4}$$

$$\bar{\Delta} F + \left(\partial_\tau + \frac{\nabla^2}{2m} + \mu \right) G^h = 1 \tag{5}$$

Solving for F we obtain

$$\left[\bar{\Delta} - \left(\partial_\tau + \frac{\nabla^2}{2m} + \mu \right) \Delta^{-1} \left(\partial_\tau - \frac{\nabla^2}{2m} - \mu \right) \right] F = 1 \rightarrow \tag{6}$$

$$F = \left[|\Delta|^2 - \Delta \left(\partial_\tau + \frac{\nabla^2}{2m} + \mu \right) \Delta^{-1} \left(\partial_\tau - \frac{\nabla^2}{2m} - \mu \right) \right]^{-1} \Delta$$

Using (2) we obtain the desired result, a closed equation for the gap

$$\Delta = g \left[|\Delta|^2 - \Delta \left(\partial_\tau + \frac{\nabla^2}{2m} + \mu \right) \Delta^{-1} \left(\partial_\tau - \frac{\nabla^2}{2m} - \mu \right) \right]^{-1} \Delta \tag{7}$$

Generally, this equation is hard to solve. However, it can greatly simplify if Δ is rather flat for times longer than $t_D \sim 1/\omega_D$ and varies slowly in space. In this case we can neglect the spatial and temporal dependence of Δ in the denominator. The idea is that $\Delta \ll \omega_D$ such that for frequencies of the order of ω_D the gap Δ is just a small correction, and thus it can be substituted by Δ_0 which is its value at $\omega = 0$. Equation (7) assumes the form

$$\Delta(\mathbf{x}, \tau) = g(\tau) \frac{1}{|\Delta_0|^2 - (\partial_\tau + \frac{\nabla^2}{2m} + \mu) (\partial_\tau - \frac{\nabla^2}{2m} - \mu)} \Delta(\mathbf{x}, \tau) \quad (8)$$

To solve, we transform to Matsubara frequencies and momentum space

$$\Delta(\omega) = -\frac{1}{\beta\Omega} \sum_{\omega} \sum_{\mathbf{k}} \frac{g(\omega - \nu)\Delta(\nu)}{\nu^2 + \xi_{\mathbf{k}}^2 + |\Delta_0|^2} \quad (9)$$

where ν and ω are bosonic and fermionic Matsubara frequencies, $\xi = k^2/2m - \mu$, Ω is the volume of the system and we have used the convolution theorem. Notice that we have taken g (and also Δ) to be a function of time but independent on space. This mimics a local interaction with retardation. We will demonstrate the retardation effect in the exercise.
