# Lovász Local Lemma [Erdős & Lovász 1975]

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$$\mathcal{A} = \{A_1, ..., A_n\}$$

(1) 
$$Pr[A_i] \leq P$$
,  $\forall A_i$ 

 $\bigcirc$  Each event depends on at most  $\underline{d}$  other events.

LLL: 
$$e \cdot P \cdot (d+1) < 1$$
, then  $Pr[\Lambda \bar{A}_i] > 0$ 

LLL can be seen as generalizing a local property to a global one:

"If there is positive probability that no bad event occurs in each neighborhood, then there is positive prob. no bad event happens globally."

#### Example 1: (2-Coloring hypergraphs)

 $e_1, \ldots, e_m$ 

k-uniform hypergraph

Every edge intersects ≤d other edges.

<u>LLL</u>: If  $e(d+1) < 2^{k-1}$ ,  $\exists 2$  coloring of the vertices of the hypergraph s.t. no edge is monochromatic.

#### Example 2: k-CNF

n vars, m clauses.

- clause has k vars.

- Every var in  $\leq \frac{2^k}{ke}$  clauses.

$$(\underbrace{X_1 \vee X_2 \vee X_3}_{C_1}) \wedge (\underbrace{X_2 \vee X_3 \vee X_4}_{C_2}) \dots$$

LLL: 3 satisfying assignment.

# Constructive LLL (Moser & Tardos 2010)

$$X = \{X_1, ..., X_m\}$$
: indep. discrete r.v.'s  $A = \{A_1, ..., A_n\}$ : events  $Vrb(A_i) \subseteq X$ 

 $A_i$  and  $A_i$  are dep. if  $vrb(A_i) \cap vrb(A_i) \neq \emptyset$ .

Goal: Find a good assignment to Xis s.t. no bad event happens.

Dep graph 
$$G_A$$
:  $(A,E)$   
 $E = \{ (A_i,A_j) \mid \text{vrb}(A_i) \cap \text{vrb}(A_j) \neq \emptyset \}$ 

$$max-deg \leq d$$

$$Pr[A_i] \leq P$$

$$e \cdot P(d+1) < 1 - E$$

=> By LLL, we know a construction exists, but how do we find it?

# MT Algorithm centralized algorithm

- 1) Initialize Xi's with random assignment.
- 2) While 3bad event:

Pick one bad event (arbitrarily) and resample all its variables.

#### Witness tree

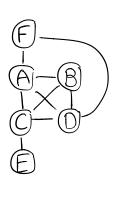
Witness tree Tj: (j'th resampling step)

Root Aii

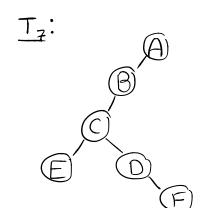
For every 
$$A \in \{A_{i,j-1},...,A_{i,1}\}$$
:

Add A as the child of its deepest neighbor in  $T_j$ .

### A, B, C, D, E, F



 $F, D, E, C, E, B, \underline{A}, D$ 



Lemma:  $\forall i < j T_i \neq T_j$ .

Pf: If the two trees have the same root then  $T_i$  must be a (strict) sub-tree of  $T_j$ .  $\square$ 

Fix tree T. |T|=S.

What is the probability that T occurs in MT execution?

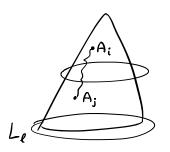
Lemma: Pr[Toccurs] ≤ ps.

#### Pf:

Obs: If A; and A; are in the same level, then they are independent.

The fact that  $A_j$  is a descendent of  $A_i$  does not increase the probability of  $A_i$ , because we use fresh randomness.





Lemma: E[#trees occurring in MT execution) = O(n)

Pf:  $T_s$ : collection of all trees of size s.

# trees of size-s 
$$\leq$$
 n·  $\binom{S(d+1)}{S-1}$ 

Can represent each tree by a binary string of length S(d+1)

with exactly s-1 1 bits.

$$n \cdot {S(d+1) \choose s-1} \le n ((d+1)e)^s$$

$${Q \choose b} \le {eQ \choose b}^b$$

 $\mathbb{E}[\# \text{ witness trees}] = \sum_{s=1}^{\infty} \sum_{T \in \mathcal{T}_s} \Pr[T \text{ occurs}]$ 

$$\leq \sum_{s=1}^{\infty} n \cdot ((d+1)e)^s \cdot p^s$$

$$= n \sum_{s=1}^{\infty} \left( \underbrace{(d+1)eP}^{s} \right)^{s} = O(n)$$

Thm: W.h.p. there is no tree of size  $S = c \cdot \log_{\frac{1}{eP(d+1)}} n$ 

$$Pf$$
:  $E$ [# trees of size s] =  $|T_s| \cdot P^s$ 

$$\leq (eP(d+1))^{S} = \frac{1}{n^{c}}.$$

## Distributed LLL

Communication graph: dep. graph

$$A = \{A_1, ..., A_n\}, X = \{X_1, ..., X_m\}$$

Node vi: event Ai

Pr[Ai] < P

LLL: P.e. (d+1) ≤ 1-E

Goal: Find good assignment.

#### Example: Defective Coloring

\* Graph G = (V, E), max-deg =  $\Delta$ ,  $f \ge 60 \ln \Delta$ 

\* Vertex has  $\lceil \frac{2\Delta}{f} \rceil$  colors.

Goal: each vertex has at most f neighbors with the same color.

- bad event : > f neighbors with same color.
- → Dep. graph: vertices that share a neighbor (i.e., distance = 2).

Thm 1: there is a distributed LLL algorithm that runs in  $O(T_{MIS} \cdot \log_{\frac{1}{p \cdot c(u+n)}} n)$  rounds, w.h.p.

Thm 2: [Chung, Pettie, Su]: LLL in  $O(\log_{\frac{1}{ped^2}} n)$ .

#### Distributed LLL

- 1) Initialize with random assignment.
- 2) While bad event:

B := bad event

M = MIS(G[B])

Resample all vars in M.

Want to show: Step 2 repeats  $O(\log_{\frac{1}{epoin}} n)$  iterations.

<u>Lemma</u>: W.h.p.  $O(\log_{\frac{1}{eP(d+1)}})$  resampling phases.

 $\underbrace{M_1, M_2, \ldots, M_\ell}_{v_1, \ldots, v_k}$ 

Obs:  $u \in M_i$  it holds that  $T_u$  has depth  $\geq i-1$ .

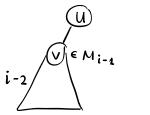
Pf: i=1: easy.

step: N+(u) AMi-1 + p, why? ->

If u is bad in  $\underline{i-1}$   $\vee$ 

If u is good in  $\underline{i-1}$ , we must have resampled a neighbor.

=) we are done by induction.



The obs completes the proof of the lemma (using arguments from centralized alg).

#### Improved Distributed LLL

LLL: ped² ≤ 1-E.

1) Initialize with random assignment.

2) While bad event:

B := bad event

Resample all vars in I.

Remark: I can be much smaller than MIS. Consider the path graph.

2-Witness tree

$$I_1, \ldots, I_{\ell}$$

step j:

Root Aij

For every  $A \in \{A_{ij-1}, ..., A_{i1}\}$ :

Connect A to its deepest node in  $N^{+2}(u)$  in the tree.

- 2 Witness tree of size S: ps
- # trees of size S:  $n \cdot {s(d^2+1) \choose s-1} \approx n(e(d^2+1))^s$
- w.h.p. no 2-witness tree of size  $S=O(\log_{\frac{1}{ped^2}}n)$

Lemma:  $u \in I_{j}$  has 2-witness tree of depth  $\geqslant j-1$ Pf:  $N^{+2}(u) \cap I_{j-4}$ \* u is good in j-1\*  $u \in I_{j-4}$ V < u, v is bad ve N(u)Ve  $I_{j-4}$ U is good in j but bad in j-1  $v \in I_{j-4}$   $v \in I_{j-4}$   $v \in I_{j-4}$   $v \in I_{j-4}$ 

$$\geqslant j^{-2} \qquad \qquad \forall \in I_{j-1} \qquad \forall \in \mathbb{N}^{+2}(u) \cap I_{j-1}$$