

Lecture 1: Dynamical Systems and Their Orbits

The Basic Problem of Dynamical Systems: Given a map $T: X \rightarrow X$ and a point $x \in X$ ("initial condition"), describe the long term behavior of the forward orbit of x

$$(x, T(x), T^2(x), T^3(x), \dots), \quad \begin{aligned} T^0 &= \text{id} \\ T^n &= \underbrace{T \circ \dots \circ T}_n \end{aligned}$$

Motivating Example: Equation of Motion ($F = ma$)

$$\begin{cases} m \frac{d^2 \vec{x}}{dt^2} = \vec{F}(\vec{x}) \\ \vec{x}(0) = \vec{x}_0, \vec{x}'(0) = \vec{y}_0 \end{cases}$$

Bring to 1st-order form by introducing $y = \dot{x}$:

$$(*) \quad \begin{cases} \frac{d\vec{x}}{dt} = y \\ \frac{dy}{dt} = \vec{F}(\vec{x})/m \end{cases}; \quad \begin{pmatrix} \vec{x}(0) \\ \vec{y}(0) \end{pmatrix} = \begin{pmatrix} \vec{x}_0 \\ \vec{y}_0 \end{pmatrix}$$

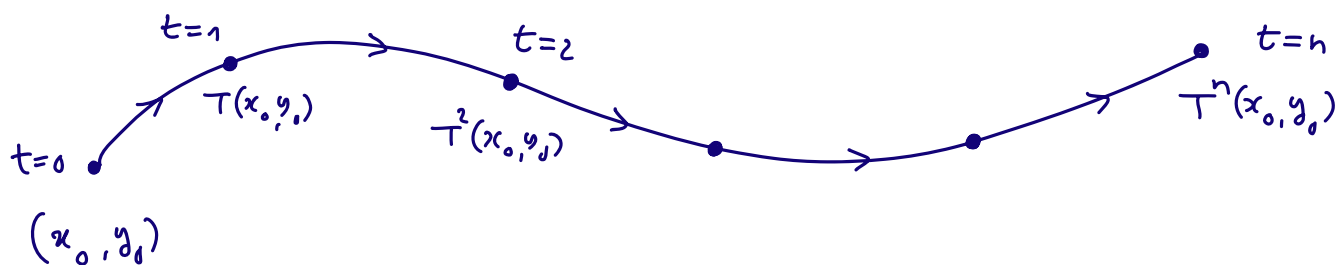
Existence & Uniqueness Thm: Suppose $\vec{F}(\cdot)$ is continuously differentiable and $\|\vec{F}(\vec{x})\| \leq \text{const}$, then $(*)$ has a unique solution defined for all $t \in \mathbb{R}$.

Let

- $X =$ set of all possible pairs (x_0, y_0)

- $T: X \rightarrow X$ the map

$$T((x_0, y_0)) = \begin{pmatrix} (x(1), y(1)) \text{ for the unique solution } (x(t), y(t)) \\ \text{of } (*) \text{ with initial condition } (x_0, y_0) \end{pmatrix}$$



Then $T^n(x_0, y_0) = \left(\begin{array}{l} \text{state of the} \\ \text{system at time } n \end{array} \right)$.

We'd like to know what happens as $n \rightarrow \infty$.

Variations on the Basic Problem: A semi-group action

is a collection of maps $T_g: X \rightarrow X$ ($g \in G$), where G is a semi-group, s.t. $T_g \circ T_h = T_{gh}$.

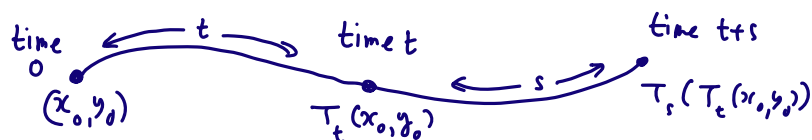
The orbit of $x \in X$ is $\langle T_g(x) : g \in G \rangle$.

(1) "Map" ($G = \mathbb{N}_0$): $T_n = T_0 \circ \dots \circ T$ for some function $T: X \rightarrow X$

(2) "Flow" ($G = \mathbb{R}^+, \mathbb{R}$): $T_t(x)$, $T_{t+s} = T_t \circ T_s$

E.g. $T_t(x_0, y_0) = (x(t), y(t))$ where $(x(t), y(t))$

solves (*)



(3) " \mathbb{Z}^d -action": $T_1, \dots, T_d: X \rightarrow X$ invertible and commuting ($T_i \circ T_j = T_j \circ T_i$), and

$$T_{(n_1, \dots, n_d)} = T_1^{n_1} \circ T_2^{n_2} \circ \dots \circ T_d^{n_d} \quad (\underline{n} \in \mathbb{Z}^d)$$

etc.

The Main Difficulty in Dynamical Systems: Calculating orbits is often intractable:

(1) Often, there's no explicit formula for T (e.g. when it's a solution of an ODE)

(2) Even if a formula exists, the formulas for T^n can "explode". Example:

$$\cdot T(z) = z^2 + 1 \quad (\text{deg} = 2)$$

$$\cdot T^2(z) = (z^2 + 1)^2 + 1 \quad (\text{deg} = 4)$$

$$\cdot T^3(z) = ((z^2 + 1)^2 + 1)^2 + 1 \quad (\text{deg} = 8)$$

...

$$\cdot T^n(z) = \text{polynomial of degree } 2^n$$

(3) Numerical Instabilities: Often, to predict $T^n(z)$ up to precision ε , must know z up to precision $e^{-\alpha^n} \varepsilon$. This is not realistic, even for small n .

Example: $T^n(z) = z^{2^n} + \text{lower order terms}$

Modern Approach to Dynamical Systems: Soft methods* for describing the orbits of "many" or "some" initial conditions, but without knowing the explicit coordinates of the initial conditions we talk about.

* topology, functional analysis, probability theory etc.

Behavior of Orbits

Setup: Let $T: X \rightarrow X$ be a continuous map of a metric space (X, d) , possibly non-invertible.

(1) The forward orbit closure of x is $\overline{\{x, T(x), T^2(x), \dots\}}$

(2) The ω -limit set of x is

$$\omega(x) := \{y \in X : \exists n_k \rightarrow \infty \ (T^{n_k}(x) \rightarrow y)\}$$

(3) In invertible cases we also define

- The (full) orbit closure $\overline{\{T^n(x) : n \in \mathbb{Z}\}}$
- The α -limit set

$$\alpha(x) = \{y \in X : \exists n_k \rightarrow \infty \ (T^{-n_k}(x) \rightarrow y)\}$$

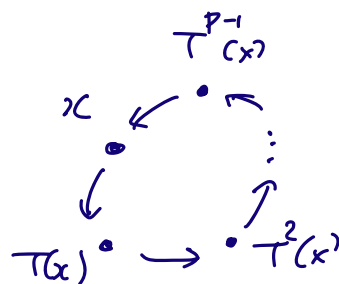
("I am the alpha and omega, the beginning and end")

The Basic Idea : $\left(\begin{array}{l} \text{large orbit closure} \\ \text{or } \omega\text{-limit set} \end{array} \right) \leftrightarrow \left(\begin{array}{l} \text{complicated} \\ \text{behavior} \end{array} \right)$

Simple Behavior:

- fixed point: $T(x) = x$.

- periodic point: $T^p(x) = x$



- forward asymptotic to fixed/periodic point

$$d(T^n(x), T^n(y)) \xrightarrow{n \rightarrow \infty} 0, \quad T^p(y) = y$$

Example: $T: \mathbb{C} \rightarrow \mathbb{C}; T(z) = z^2. \quad T^n(z) = z^{2^n}$

- Fixed Points: $z^2 = z \quad z = 0, 1$

- Periodic Points: $z^{2^p} = z$ (many solutions, all at zero or on the unit circle)

- $|z| < 1$: $T^n(z) \rightarrow 0$

Thus $\omega(z) = \{0\}$ for all $|z| < 1$

- $|z| > 1$: $T^n(z) \rightarrow \infty, \quad \omega(z) = \emptyset$

But we'll soon see that some z on the unit circle have much more complicated behavior.

Orbits with Complicated Behavior: For our example, all such orbits must lie on $S^1 = \{z \in \mathbb{C} : |z| = 1\}$.

Symbolic Dynamics: A "change of coordinates" which simplifies the dynamics.

In our example, it's convenient to represent $z \in \mathbb{C}, |z|=1$ by the binary expansion $(\omega_1, \omega_2, \omega_3, \dots) \in \{0,1\}^{\mathbb{N}}$ of $\frac{1}{2\pi} \text{Arg}(z)$:

$$z = \pi(\omega_1, \omega_2, \omega_3, \dots) := \exp \left(2\pi i \sum_{i=1}^{\infty} \frac{\omega_i}{2^i} \right) \quad \frac{1}{2\pi} \text{Arg}(z)$$

In these coordinates, T acts by the left shift map

$$\sigma(\omega_1, \omega_2, \omega_3, \dots) = (\omega_2, \omega_3, \omega_4, \dots), \quad \text{because}$$

$$\begin{aligned} T(\pi(\underline{\omega})) &= \left[\exp \left(2\pi i \sum_{i=1}^{\infty} \frac{\omega_i}{2^i} \right) \right]^2 = \exp \left(2\pi i \cdot 2 \sum_{i=1}^{\infty} \frac{\omega_i}{2^i} \right) \\ &= \exp \left(2\pi i \left(\omega_1 + \sum_{i=1}^{\infty} \frac{\omega_{i+1}}{2^i} \right) \right) = \exp \left(2\pi i \sum_{i=1}^{\infty} \frac{\omega_{i+1}}{2^i} \right) = \pi(\sigma(\underline{\omega})) \end{aligned}$$

Thus $T^n(\pi(\underline{\omega})) = \pi(\sigma^n(\underline{\omega}))$. The gain: $\sigma^n(\underline{\omega})$ is easy to find,
 $\sigma^n(\underline{\omega}) = (\omega_{n+1}, \omega_{n+2}, \dots)$.

In summary: Let

- $\Sigma^+ = \{(\omega_1, \omega_2, \omega_3, \dots) : \omega_i = 0 \text{ or } 1\}$ with the metric
 $d(\underline{\omega}, \underline{\omega}') = \exp(-\min\{n : \omega_n \neq \omega'_n\})$ or zero if $\underline{\omega} = \underline{\omega}'$
- $\pi : \Sigma^+ \rightarrow \{z : |z|=1\}$, $\pi(\underline{\omega}) = \exp \left[2\pi i \sum_{n=0}^{\infty} \frac{\omega_{n+1}}{2^n} \right]$

Note that π is continuous.

- $\sigma : \Sigma^+ \rightarrow \Sigma^+$ the left shift map: $\sigma(\omega_0, \omega_1, \dots) = (\omega_1, \omega_2, \dots)$

Then the diagram

$$\begin{array}{ccc} \Sigma^+ & \xrightarrow{\sigma} & \Sigma^+ \\ \pi \downarrow & & \downarrow \pi \\ S^1 & \xrightarrow{z^2} & S^1 \end{array} \quad \text{commutes.}$$

(1) "Anything Is Possible:" Suppose we divide

$$S^1 = A \cup B, \quad A = \{z \in S^1: \text{Arg}(z) \in [0, \pi)\}$$

$$B = \{z \in S^1: \text{Arg}(z) \in [\pi, 2\pi)\}$$

Given $z \in S^1$, let's mark the arc visited by $T^n(z)$:

A, A, B, A, B, B,

Is there any regularity whatsoever in the sequence we get? No! \longrightarrow "unpredictable behavior"

Fact. Any sequence of A's and B's which doesn't terminate in A^∞ or B^∞ is realized by some z .

Proof. Take any sequence $\underline{\omega} \in \Sigma^+$ which does not end with A^∞ or B^∞ . Let $z = \pi(\underline{\omega})$. Then

$$T^n(z) = \pi(\sigma^n(\underline{\omega})) = \pi(\omega_{n+1}, \omega_{n+2}, \dots) \in \begin{cases} A & \omega_{n+1} = 0 \\ B & \omega_{n+1} = 1 \end{cases}.$$

Exercise: Which sequences ending in A^∞ or B^∞ are realized?

(2) Construction of z with ω -limit set S^1 :

Let $\underline{w}_1, \underline{w}_2, \underline{w}_3, \dots$ be a list of all finite words with letters 0, 1:

0, 1, 00, 01, 10, 11, 000, 001, \dots

Let $\underline{\omega}^0 = (\underline{w}_1, \underline{w}_2, \underline{w}_3, \dots)$.

Lemma: $\{\sigma^n(\underline{\omega}^0) : n \geq 0\}$ is dense in Σ^+ :

Proof: Suppose $\underline{x} = (x_0, x_1, \dots) \in \Sigma^+$. Take n_k s.t. $\underline{w}_{n_k} = (x_0, \dots, x_k)$. By construction, $\exists m_k$ s.t.

$$\sigma^{m_k}(\underline{\omega}^0) = (\underline{w}_{n_k}, \underline{w}_{n_k+1}, \dots)$$

Then $d(\sigma^{m_k}(\underline{\omega}^0), \underline{x}) \leq \frac{1}{2^k} \rightarrow 0$.

Corollary: Let $z_0 := \pi(\underline{\omega}^0)$. Then $\{T^n(z_0) : n \geq 0\}$ is dense in S^1 .

Proof. For each $z \in S^1$, write $z = e^{2\pi i \alpha}$ and

let $\underline{x} =$ binary expansion of α .

Choose $m_k \rightarrow \infty$ s.t. $\sigma^{m_k}(\underline{\omega}^0) \rightarrow \underline{x}$ in Σ^+ .

Since π is continuous, $\pi(\sigma^{m_k}(\underline{\omega}^0)) \rightarrow \pi(\underline{x}) = z$.

By the commutation relation $\pi \circ \sigma^{m_k} = T^{m_k} \pi$,

$$T^{m_k}(z) = T^{m_k}(\pi(\underline{\omega}^0)) = \pi(\sigma^{m_k}(\underline{\omega}^0))$$

Since $\sigma^{m_k}(\underline{\omega}^0) \rightarrow \underline{x}$ and π is continuous,

$$T^{m_k}(z) \longrightarrow \pi(\underline{x}) \equiv z. \quad \square$$

(3) Orbits with Fractal ω -limit sets : Let

$\underline{w}_1, \underline{w}_2, \underline{w}_3, \dots$ be a list of concatenations of 00 and 11:
 00, 11, 0000, 0011, 1100, 1111, \dots . Let $\underline{\omega}^0 = (\underline{w}_1, \underline{w}_2, \underline{w}_3, \dots)$

The ω -limit set of $\underline{\omega}^0$ in Σ^+ is $F = A \cup \sigma(A)$

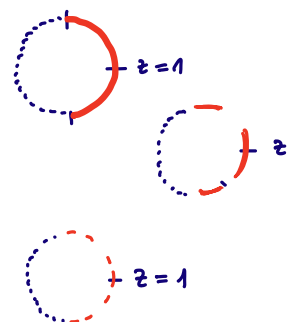
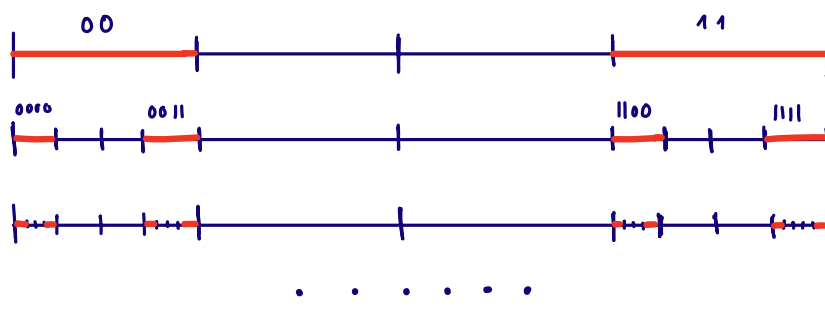
where A = all infinite concatenations of 01, 11

The ω -limit set of $z_0 = \pi(\underline{\omega}^0)$ is $\boxed{\omega(z_0) = \pi(F)}$ (exercise)

Observe that $F = A \cup \{(0\underline{y}) : \underline{y} \in A\} \cup \{(1\underline{y}) : \underline{y} \in A\}$.

Each of these sets is a Cantor set:

$\pi(A)$



Topological Dynamics

The previous examples show that the behavior of orbits of specific initial conditions is often intractable

"Modern Approach to Dynamical Systems": Use soft methods to understand the behavior of "many" or "some" initial conditions, at the following price — no explicit info on these initial conditions.

We'll see two examples:

- existence of recurrent orbits (today)
 - existence of dense orbits
 - applications to combinatorics
- } future

Existence of Recurrent Orbits

Defⁿ. Let $T: X \rightarrow X$ be a continuous map on a metric space. A point $x \in X$ is called **recurrent** if $\exists n_k \rightarrow \infty$ s.t. $T^{n_k}(x) \xrightarrow{k \rightarrow \infty} x$.

We will show:

Birkhoff's Thm: Every continuous map on a compact metric space has at least one recurrent orbit.

(But the proof will not tell us how to find it.)

Preparations to the Proof:

Defⁿ. A **minimal set** is a closed nonempty set F s.t. $T(F) \subseteq F$, and so that there is no $G \subsetneq F$ closed non-empty s.t. $T(G) \subseteq G$.

Exercise: Suppose F is a minimal set of a continuous map $T: X \rightarrow X$ on a metric space X . Then

(a) $\forall x \in F, \quad \overline{\{T^n(x) : n \geq 1\}} = F$; Therefore

(b) every $x \in F$ is recurrent.

Propⁿ. Any continuous map T on a compact metric space X admits at least one minimal set

Proof. The proof uses Zorn's Lemma (see below).

Let $\mathcal{F} := \{A \subseteq X : A \text{ is closed, non-empty, and } T(A) \subseteq A\}$.

\mathcal{F} is not empty, because $X \in \mathcal{F}$.

Put a partial order \leq on \mathcal{F} by declaring

$$A \leq B \iff A \supseteq B.$$

This is a **partial order**: It's **reflexive** ($A \leq A$); **antisymmetric** ($A \leq B$ and $B \leq A \Rightarrow A = B$); and **transitive** ($A \leq B, B \leq C \Rightarrow A \leq C$).

But it's not a total order: some A, B are not comparable.

Terminology:

- A **chain** is a collection of sets $\mathcal{C} \subseteq \mathcal{F}$ s.t.
 $\forall C_1, C_2 \in \mathcal{C}$, either $C_1 \leq C_2$ or $C_2 \leq C_1$.
- An **upper bound** of a chain \mathcal{C} is an element B s.t. $B \geq A$ for all $A \in \mathcal{C}$.

Claim: In (\mathcal{F}, \leq) , every chain has at least one upper bound.

Proof. Suppose \mathcal{C} is a chain and let

$$B := \bigcap_{A \in \mathcal{C}} A = \{x : x \in A \text{ for each } A \in \mathcal{C}\}.$$

Clearly $B \geq A$ (i.e. $B \subseteq A$) for all $A \in \mathcal{C}$.

To see that B is an upper bound, we just need to see that $B \in \mathcal{F}$.

(1) B is closed (any intersection of closed sets is closed)

$$(2) \quad \underline{T(B)} \subseteq B : T(B) \subseteq \bigcap_{A \in \mathcal{C}} T(A) \subseteq \bigcap_{\substack{A \in \mathcal{F} \\ A \geq B}} A = B$$

(3) $B \neq \emptyset$: Proof below.

To show that $B \neq \emptyset$, we first show that \mathcal{C} has the **finite intersection property (FIP)**:

$$*) \quad \forall A_1, \dots, A_n \in \mathcal{C} \quad \left(\bigcap_{i=1}^n A_i \neq \emptyset \right).$$

Indeed, since \mathcal{C} is a chain one can show by induction that \exists permutation of $(1, \dots, n)$ s.t.

$$A_{i_1} \supseteq A_{i_2} \supseteq \dots \supseteq A_{i_n}$$

and so $A_{i_1} \supseteq \dots \supseteq A_{i_n}$, whence $\bigcap_{i=1}^n A_i = A_{i_n} \neq \emptyset$.

Cantor's Theorem: Any family of closed subsets of a compact space with FIP has non-empty intersection.*

It follows that $B = \bigcap_{A \in \mathcal{C}} A \neq \emptyset$. So $B \in \mathcal{K}$

Clearly, this is an upper bound for \mathcal{C} .

The claim is proved.

* **Proof**: Assume by contradiction that $\bigcap_{A \in \mathcal{C}} A = \emptyset$. Then

$\bigcup_{A \in \mathcal{C}} A^c = X$, so $\{A^c : A \in \mathcal{C}\}$ is an open cover of X .

By compactness, \exists finite sub cover $\bigcup_{i=1}^n A_i^c = X$. But this implies that $\bigcap_{i=1}^n A_i = \emptyset$, in contradiction to FIP.

Having proved the claim, we now invoke

Zorn's Lemma: Suppose (\mathcal{F}, \leq) is a partially ordered set with the property that any chain has an upper bound. Then \mathcal{F} contains at least one **maximal element** (i.e. $M \in \mathcal{F}$ s.t. there are no $A \in \mathcal{F}$ s.t. $A \geq M, A \neq M$.)

If M is such a "maximal element", then M is a minimal set, because

- $M \neq \emptyset$
 - $\overline{M} = M$
 - $T(M) \subseteq M$
 - No $M' \subsetneq M$ with these properties (by maximality). \square
- } because $M \in \mathcal{F}$

Proof of Birkhoff's Thm: By the propⁿ, $T: X \rightarrow X$

has a minimal set $M \neq \emptyset$. By the exercise, $\forall x \in M$

- $\overline{\{T^n(x) : n \geq 1\}} = M$, and therefore
- $\forall x \in M \exists n_k \rightarrow \infty$ s.t. $T^{n_k}(x) \xrightarrow[k \rightarrow \infty]{} x$.

So every $x \in M$ is recurrent. \square

Exercises for Lecture 1

(not for submission)

(1) Consider the map $T(z) = z^N$ on $S^1 = \{z: |z|=1\}$, where $N \geq 2$ is an integer. Show that there exists z_0 with orbit closure S^1 .

(2) Give an example of a continuous map on a (non-compact) metric space without any recurrent orbits.

(3) Arnol'd's "Cat Map" is the map

$$T: \mathbb{R}^2 / \mathbb{Z}^2 \rightarrow \mathbb{R}^2 / \mathbb{Z}^2$$

$$T\left[\begin{pmatrix} x \\ y \end{pmatrix} + \mathbb{Z}^2\right] = \begin{pmatrix} 2 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} + \mathbb{Z}^2$$

(a) Show that T is well defined.

(b) Show that T is invertible

(c) Show that every $\begin{pmatrix} x \\ y \end{pmatrix} + \mathbb{Z}^2$ with $x, y \in \mathbb{Q}$ is T -periodic

(d) Show that to know $T^N\left[\begin{pmatrix} x \\ y \end{pmatrix} + \mathbb{Z}^2\right]$ up to precision ϵ , we must know $\begin{pmatrix} x \\ y \end{pmatrix} + \mathbb{Z}^2$ up to precision $\epsilon e^{-\lambda n}$. What is λ ?