

LASSO-BASED FAST RESIDUAL RECOVERY FOR MODULO SAMPLING

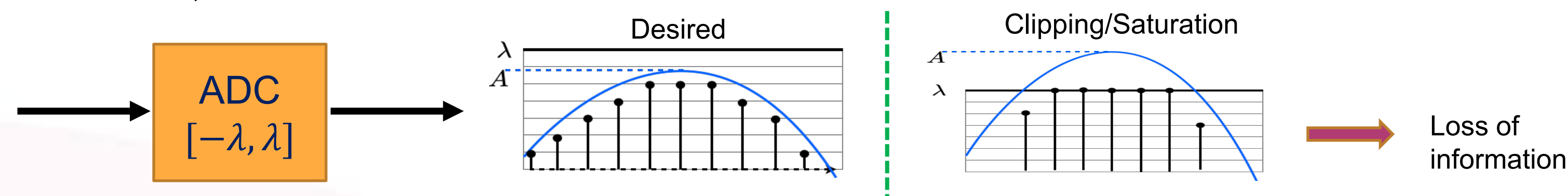
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1. Motivation and Contributions

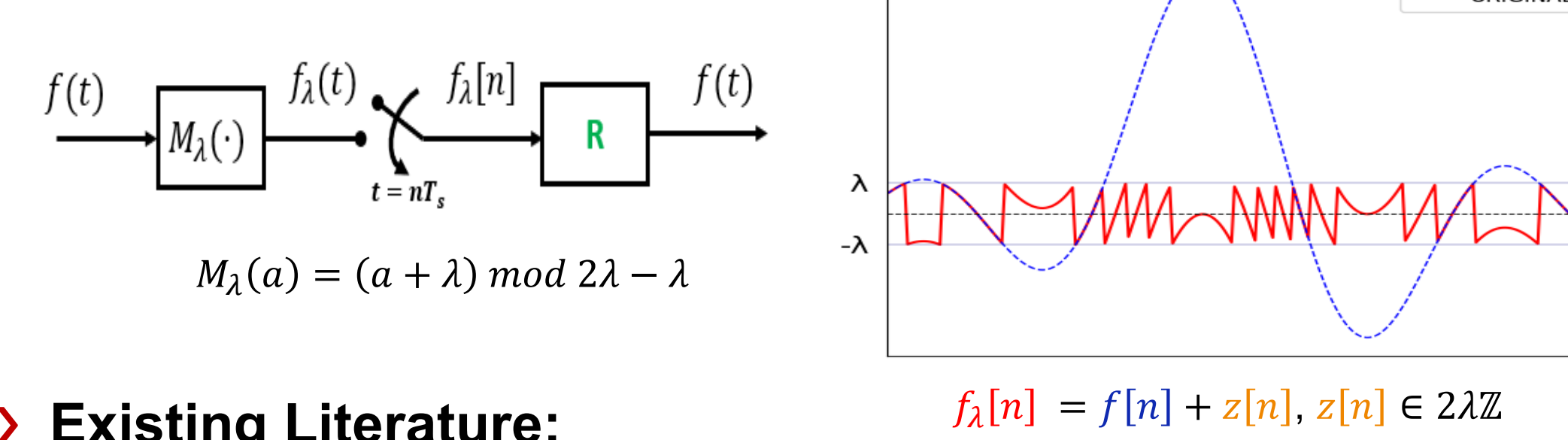
- > Analog-to-digital-converters (ADCs) play a vital role in modern information processing systems
- > Ideally, the dynamic range (DR) of an ADC should be greater than the DR of the input signal, otherwise, it leads to loss of information



- > Sampling is an important building block in an ADC. Typically, a band-limited signal is sampled at Nyquist rate, which is greater than twice the signal's maximum frequency component
- > High sampling rate \rightarrow Expensive and power consuming ADCs
- > **Desirable:** High-DR-ADCs that operate at lower sampling rate
- > This paper addresses the high DR issue of an ADC using the non-linear modulo operator
- > We propose a fast and robust algorithm called LASSO- B^2R^2 for recovering bandlimited true samples from folding samples
- > We show that the first-order difference of the residual samples is sparse and can be recovered from its partial Fourier measurements by formulating a sparse recovery problem
- > We demonstrate that the proposed algorithm is robust to noise and computationally efficient compared to the existing methods

2. Problem Statement

> **Modulo Sampling:**



> **Existing Literature:**

- > **Higher-Order Differences (HODs) Based** [1]: Sensitive to noise and requires a sampling rate of $2\pi e$ times Nyquist rate
- > **Prediction-Based** [2]: Improved upon HODs and required a sampling rate that is greater than Nyquist rate
- > **Beyond Bandwidth Residual Recovery (B^2R^2)** [3]: Improved upon prediction-based; requires a sampling rate slightly higher than Nyquist. Computationally expensive and not fast enough

[1] A. Bhandari et al. IEEE TSP 2020. [2] E. Romanov et al. IEEE SPL 2019. [3] E. Azar et al. ICASSP 2022.

R: Robust, fast, and operates at low sampling rate

3. Properties of Finite-Energy BL Signals

$$f(t) \in L^2(\mathbb{R}) \cap B_{w_m}: \text{Finite-energy band-limited signal}$$

$$f_\lambda(t) = f(t) + z(t) \rightarrow f_\lambda[n] = f[n] + z[n], z[n] \in 2\lambda Z$$

> **Time-Domain Separation:**

Riemann-Lebesgue Lemma: $\lim_{|t| \rightarrow \infty} f(t) = 0$

- $T = NT_s$: Covers 98 – 99% of energy of $f(t)$
- $T_\lambda = N_\lambda T_s$: $f_\lambda(t) = f(t), \forall t > T_\lambda$ and $f_\lambda[n] = f[n], \forall n > N_\lambda$

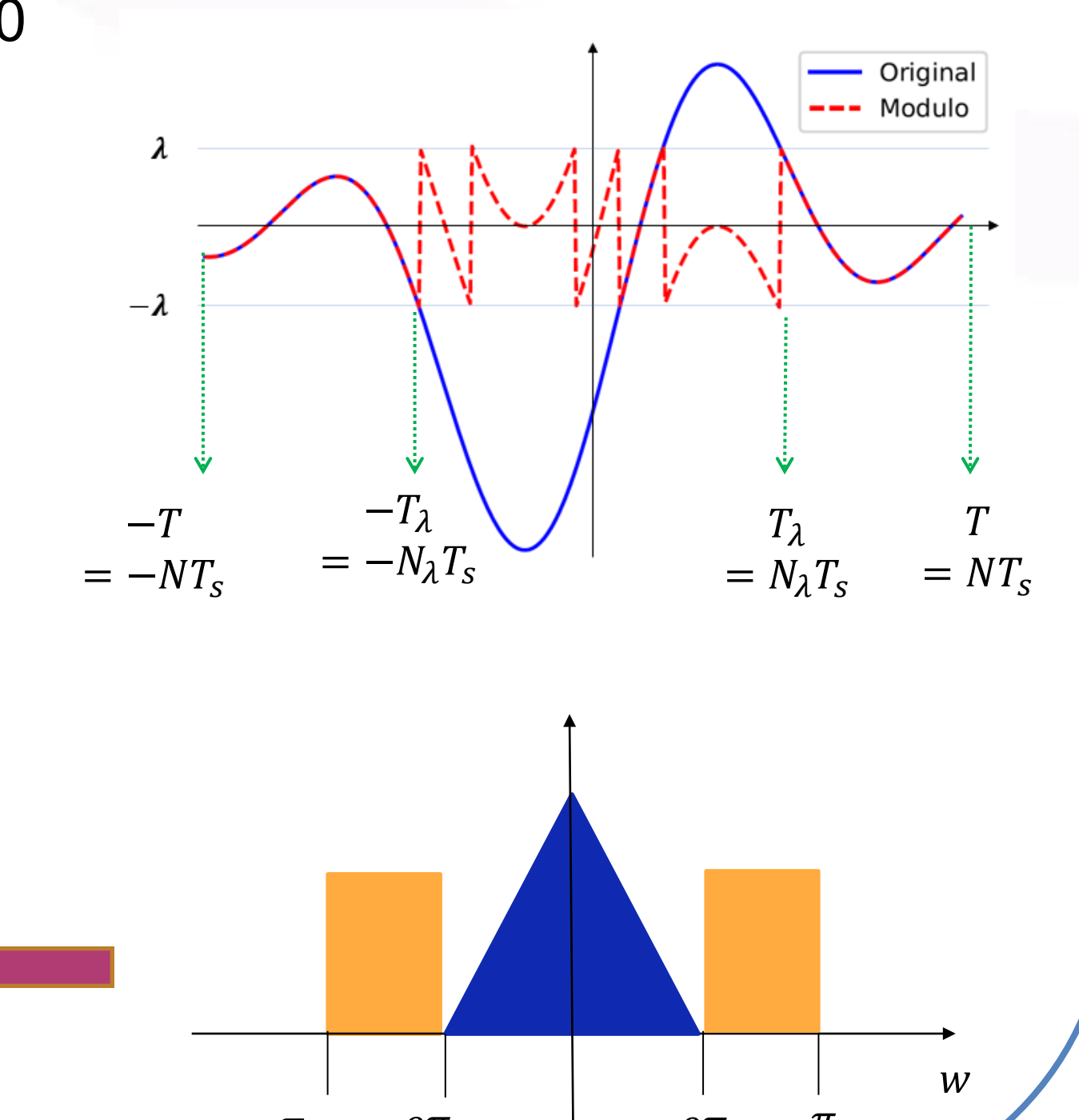
$z(t)/z[n]$: Finite T -duration/ N -length signal

> **Frequency-Domain Separation:**

$$Z(e^{jw}) = F_\lambda(e^{jw}), \forall \rho\pi < |w| < \pi$$

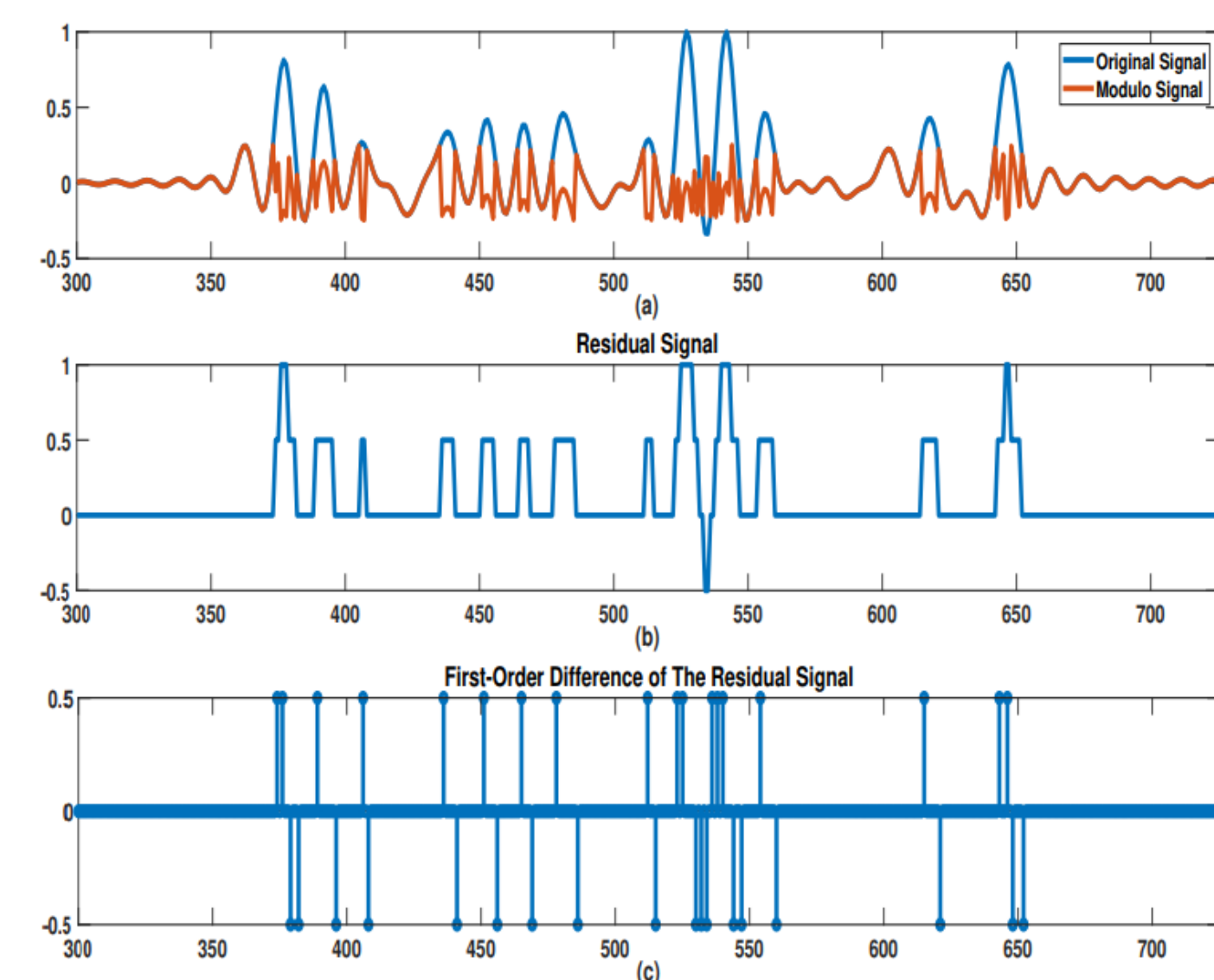
$$\text{where } \rho = \frac{2w_m}{w_s} = \frac{1}{OF}$$

OF : Over-sampling Factor



4. Observation

$$\hat{f}_\lambda[n] = \hat{f}[n] + \hat{z}[n], \hat{z}[n] = \Delta z[n] \text{ is sparse}$$



$$L \leq \min \left(4K + 4K \left\lfloor \frac{\|f(t)\|_\infty - \lambda}{2\lambda} \right\rfloor, N \right), K = \left\lfloor \frac{N}{2OF} \right\rfloor$$

λ	OF = 4		OF = 6		OF = 8	
	2K	Upper bound on L	2K	Upper bound on L	2K	Upper bound on L
0.75	256	512	170	340	128	256
0.5	256	512	170	340	128	256
0.25	256	1024	170	680	128	512
0.05	256	1024	170	1024	128	1024

> In practice, the actual L value is far less than its upper bound

λ decreases \rightarrow L increases

5. LASSO- B^2R^2

> **Time-Domain Separation**

$\hat{z}[n]$ is a finite N -length signal

> **Fourier-Domain Separation:**

$$\hat{F}_\lambda \left(e^{j\frac{2\pi k}{N}} \right) = \sum_{n=0}^{N-1} \hat{z}(n) e^{-j\frac{2\pi kn}{N}}, \frac{2\pi k}{N} \in (\rho\pi, 2\pi - \rho\pi)$$

$$\hat{F}_\lambda = [V]_{M \times 1} = [V]_{M \times N} [\hat{z}]_{N \times 1}$$

> **Observation**

$\hat{z}[n]$ is a sparse signal

LASSO- B^2R^2 :

$$\min_{\hat{z}} \frac{1}{2} \|\hat{F}_\lambda - V\hat{z}\|_2^2 + \gamma \|\hat{z}\|_1 \rightarrow \hat{z}^{(t+1)} = S_{\gamma\tau} \left(\hat{z}^{(t)} - \tau V^H (V\hat{z}^{(t)} - \hat{F}_\lambda) \right)$$

Algorithm 1 LASSO- B^2R^2 Algorithm

- 1: **Input:** $f_\lambda(n), \lambda, \rho, \max\text{Iter}$ \triangleright $\max\text{Iter}$ denotes the maximum number of iterations
- 2: Compute N
- 3: Construct $[V]_{M \times N}$ using (4)
- 4: Compute $\hat{F}_\lambda(e^{j\frac{2\pi k}{N}}), \forall k \in \mathbb{Z}$ and $\frac{2\pi k}{N} \in (\rho\pi, 2\pi - \rho\pi)$
- 5: **Initialize:** $\gamma = 0.1 \|V^H \hat{F}_\lambda\|_\infty, \tau = \frac{1}{\|V\|_2^2}, \max\text{Iter} = 1000$, and $\hat{z}^{(0)} \in \mathcal{N}(0, 1)$
- 6: **for** $i = 0 : \max\text{Iter}$ **do**
- 7: $\hat{z}^{(i+1)} = S_{\gamma\tau} \left(\hat{z}^{(i)} - \tau V^H (V\hat{z}^{(i)} - \hat{F}_\lambda) \right)$
- 8: **if** $\|\hat{z}^{(i+1)} - \hat{z}^{(i)}\|_2 < 10^{-4}$ **then**
- 9: $\hat{z} = \hat{z}^{(i+1)}$
- 10: **exit**
- 11: **end if**
- 12: **end for**
- 13: $\hat{z} \leftarrow \left\lceil \frac{\hat{z}}{2} \right\rceil$ \triangleright Rounding the residual to $2\lambda Z$
- 14: $\hat{z} \leftarrow \text{cumsum}(\hat{z})$ \triangleright Cumulative summation operator on \hat{z}
- 15: $f(n) \leftarrow f_\lambda(n) - z(n)$
- 16: **Output:** $f(n)$

ISTA Algorithm:

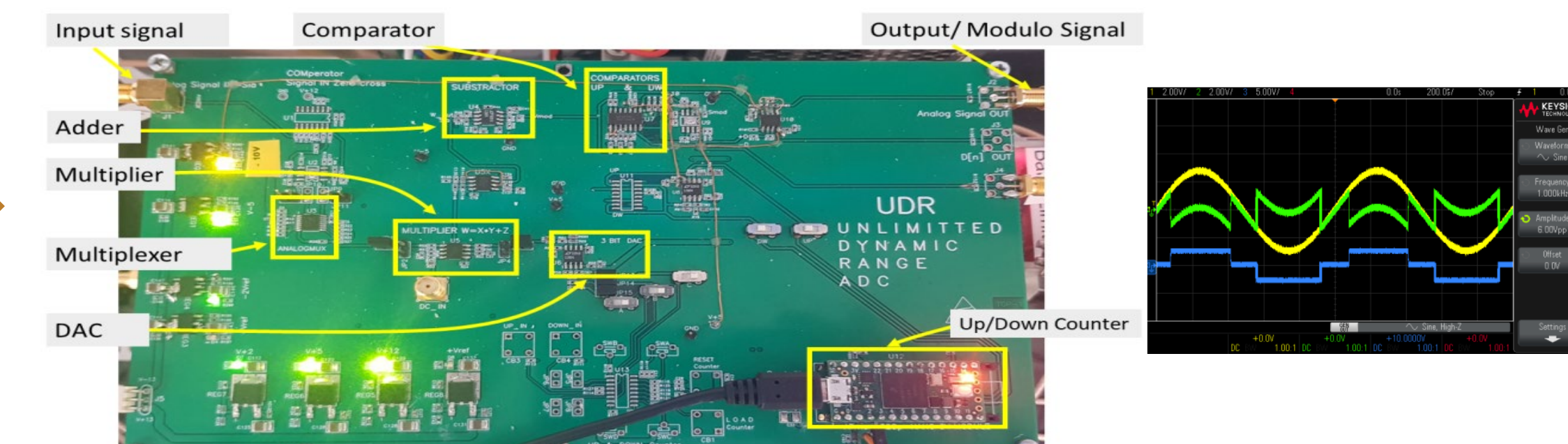
$$\hat{z}^{(t+1)} = S_{\gamma\tau} \left(\hat{z}^{(t)} - \tau V^H (V\hat{z}^{(t)} - \hat{F}_\lambda) \right)$$

where $S_{\gamma\tau}(x) = \text{sign}(x) \max(|x| - \gamma\tau, 0)$

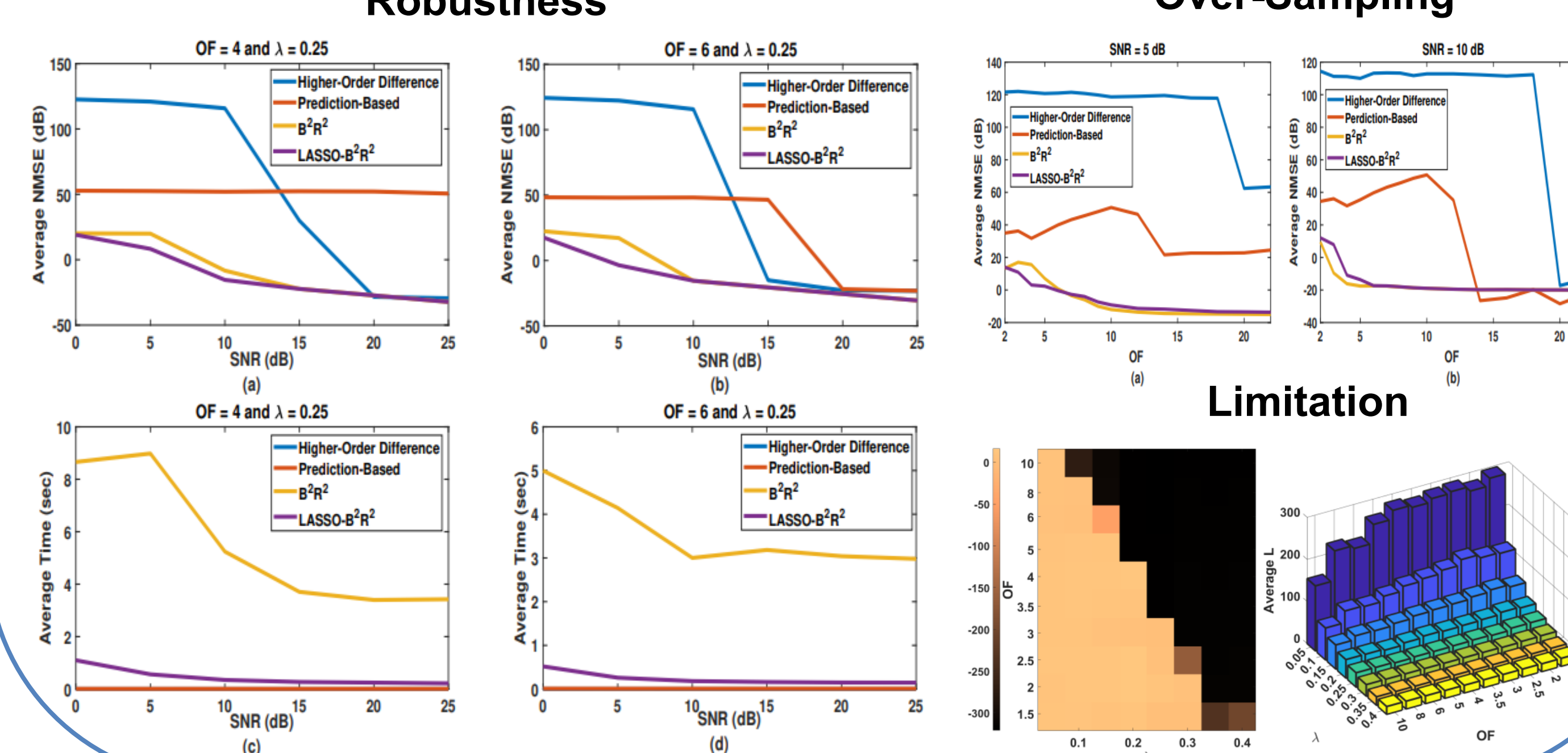
6. Results

Modulo Hardware Board

[4] S. Mulleti et al. IET 2023



Simulation:



7. Conclusions

- > We proposed a fast and robust algorithm to recover the residual signal in modulo sampling
- > We showed that the residual signal's first-order difference is a sparse vector
- > Then, the problem of recovering the residual signal is formulated as a sparse recovery problem
- > Through simulations, we demonstrated that the proposed algorithm is fast and robust compared to existing methods