Abstract—We investigate the worst-case robust beamforming for simultaneous wireless information and power transfer in a multiuser beamspace massive multiple-input multiple-output (MIMO) system. The objective is to minimize the transmit power of the base station subject to the individual signal-to-interference-plus-noise ratio and the energy-harvesting constraints under imperfect channel state information. Instead of directly resorting to semi-definite relaxation, we convert the initial non-convex optimization to a power allocation problem, which greatly reduces the computational complexity. The beamforming vectors are proven to be scaled versions of the estimated channels. The optimal scaling factors are then derived in closed-form. The simulations demonstrate that the proposed robust beamforming method achieves the globally optimal point for the initial design when the channel estimation errors are small while leads to satisfactory performance when the channel estimation errors are large.

Index Terms—Simultaneous wireless information and power transfer (SWIPT), robust beamforming, massive MIMO, beamspace, non-convex optimization.

I. INTRODUCTION

SIMULTANEOUS wireless information and power transfer (SWIPT) [1] has received considerable interest recently, since it can offer unlimited supplies to energy-constrained wireless networks. Many prominent works have studied the fundamental performance of SWIPT systems. For example, the rate-energy regions of multiple-input multiple-output (MIMO) channels with separate and co-located SWIPT receivers were characterized in [2]. An orthogonal frequency division multiplexing (OFDM)-based wireless powered communication system was investigated in [3]. The energy beamforming vector and time split parameter were designed for a power beacon assisted two-way relaying network [4]. An artificial noise (AN) assisted interference alignment (IA) scheme with wireless power transfer was proposed in [5]. Moreover, SWIPT has been studied under different channel setups, i.e., multiple fading channels [6], relay channels [7], [8], and multiple-input single-output (MISO) channels [9].

Most existing SWIPT works assume perfect channel state information (CSI) is available at the base station (BS). However, it is often difficult to obtain perfect CSI in practice because of channel estimation and quantization errors, which greatly degrade system performance. The authors in [10] proposed a robust secure beamformer for multiuser MISO SWIPT systems, with imperfect CSI of potential eavesdroppers. In [11], a probabilistic robust SWIPT algorithm was designed, where rank-one beamforming solutions were derived with convex relaxations. Two robust joint beamforming and power splitting algorithms for MISO SWIPT systems were investigated in [12]. The authors in [13], [14] presented various semidefinite relaxation (SDR) methods to solve the robust beamforming problem. Unfortunately, only suboptimal solutions were derived while globally optimal solutions are currently unknown for multiuser SWIPT systems.

Massive MIMO [15]–[17] has been considered as an additional attractive technology for SWIPT since it can significantly improve spectrum efficiency, energy efficiency and reliability [18], [19]. The authors in [20] and [21] investigated the wireless-energy-transfer problem in massive MIMO systems, while the asymptotically optimal solutions and interesting insights into the optimal design were derived. SWIPT techniques for multi-way massive MIMO rely
networks were developed in [22], where the fundamental tradeoff between harvested energy and sum rate was quantified. However, the works [20]–[22] again assume perfect CSI, which is difficult to obtain in massive MIMO systems [23], [24]. In practice, CSI in massive MIMO systems can only be obtained from some low complexity channel estimation approaches [25]–[31]. For instance, [25], [26] applied low-rank approximations of the channel covariance matrices to reduce the number of estimated parameters. The authors in [27]–[29] applied an angle division multiple access (ADMA) model to represent massive MIMO channels with a few channel gains and angular parameters. A beamspace channel estimation scheme was designed in [30], [31], where the channel vectors are approximated by a few orthogonal basis vectors from the discrete Fourier transform (DFT). However, all these works are based on approximately-sparse models so that channel estimation errors are inevitable [34].

In this paper, we consider the worst-case robust beamforming for SWIPT under a beamspace massive MIMO scheme [30], [31], where the estimated channels are orthogonal to each other and have bounded estimation errors. Our objective is to minimize the transmit power of the BS, while providing the information user and the energy user with different signal-to-interference-and-noise ratio (SINR) and power, respectively, for all possible channel realizations. The resulting problem belongs to a well known non-convex optimization formulation [35], for which only suboptimal solutions are available in existing works. In addition, conventional robust designs [10]–[14] suffer from high computational complexity with a large number of transmit antennas. By utilizing the orthogonality property within channel estimates [30], [31], we demonstrate that the problem can be globally solved when the channel estimation errors are smaller than a certain threshold. The optimal beamforming vectors are shown to be scaled versions of the estimated channels, where the optimal scaling factors can be analytically obtained from a power allocation problem. Hence, the proposed approach greatly reduces the computational complexity compared to conventional solutions, making it suitable for practical applications. Simulations further demonstrate that the proposed solution performs well even when the channel errors are large.

The rest of this paper is organized as follows: Section II describes the channel model of beamspace massive MIMO and formulates the proposed robust design. Section III derives the optimal solution for the non-convex problem. Simulation results are provided in Section IV and conclusions are drawn in Section V.

Throughout the paper we use the following notations: Vectors are denoted by boldface small and matrices by capital letters. The Hermitian, inverse and Moore-Penrose inverse of $A$ are written as $A^H$, $A^{-1}$ and $A^+$ respectively. The inequalities $A \succeq 0$ and $A \succeq 0$ mean that $A$ is positive semidefinite and positive definite respectively. We use $\text{Tr}(A)$ to denote the trace, $\|x\|$ is the Euclidean norm of a vector $x$, $\mathbb{E}[\cdot]$ is the statistical expectation, and $\mathbb{R}^{a \times b}$ and $\mathbb{C}^{a \times b}$ are the spaces of $a \times b$ matrices with real- and complex-valued entries, respectively. Define $\text{diag}(\cdot)$ as the operation of selecting diagonal elements of any $N \times N$ matrix. The distribution of a circularly symmetric complex Gaussian (CSCG) random variable with zero mean and variance $\sigma^2$ is written as $\mathcal{CN}(0, \sigma^2)$, and $\sim$ means “distributed as”.

II. SYSTEM MODEL AND PROBLEM FORMULATION

A. System Model

We consider SWIPT for a multiuser massive MIMO system shown in Fig. 1, where the BS is equipped with $N \gg 1$ antennas in the form of a uniform linear array (ULA) with supercritical antenna spacing (i.e., less than or equal to half of the wavelength). There are $K+1$ single-antenna users randomly distributed in the coverage area, which contains $K$ single-antenna information decoding users (or information users) with index set $K = \{1, \ldots, K\}$ and one energy-harvesting-user (or energy user). The $k$th user is located at $D_k$ meters away from BS and is surrounded by a ring of $G_k \gg 1$ local scatterers with radius $R_k$ [25], [29].

The channel from the $k$th information user to BS is composed of $G_k$ rays and can be expressed as [25], [29]:

$$h_k = \frac{1}{\sqrt{G_k}} \sum_{g=1}^{G_k} \alpha_{k,g} a(\theta_{k,g}), \quad 1 \leq k \leq K,$$  \hspace{1cm} (1)

where $\alpha_{k,g} \sim \mathcal{CN}(0, \zeta_{k,g})$ represents the complex gain of the $g$th ray. Moreover, $a(\theta_{k,g}) \in \mathbb{C}^{N \times 1}$ is the steering vector defined by

$$a(\theta_{k,g}) = \left[1, e^{j \frac{2\pi d}{\lambda} \sin \theta_{k,g}}, \ldots, e^{j \frac{2\pi d}{\lambda} (N-1) \sin \theta_{k,g}}\right]^H,$$  \hspace{1cm} (2)

where $d$ is the antenna spacing, $\lambda$ denotes the signal wavelength, and $\theta_{k,g}$ represents the direction of arrival (DOA) of the $g$th ray. We can similarly define the channel from the energy information user to BS as

$$h_q = \frac{1}{\sqrt{G_q}} \sum_{g=1}^{G_q} \alpha_{q,g} a(\theta_{q,g}).$$  \hspace{1cm} (3)

In the ideal massive MIMO case with $N \rightarrow \infty$, the rays satisfy $h_k^H h_j = 0$ and $h_k^H h_q = 0$, for all $i \neq j$. However, in practice $N$ cannot approach infinity and users with nearly orthogonal channels are allowed to transmit simultaneously.
with tolerable interference. Particularly, a popular low-complexity beamspace channel scheme [30], [31] assigns non-overlapping columns of the DFT matrix to different users, such that the estimated channels for different users exactly satisfy

$$\hat{h}_i^H h_j = 0, \quad \hat{h}_i^H h_i = 0, \forall i \neq j.$$  \hspace{1cm} (4)

Such channel estimation is not exact, resulting in an error between $h_i$ and $\hat{h}_i$, but can be implemented efficiently. When $N$ is large, the performance loss in channel estimation accuracy is small.

We therefore assume that the real channel vectors $h_k$ and $q$ lie around the estimated channel vectors $\hat{h}_k$ and $\hat{q}$, respectively, so that

$$h_k \in U_k = \left\{ \hat{h}_k + \delta_k \mid \|\delta_k\| \leq \epsilon_k \right\},$$

$$q \in U_q = \left\{ \hat{q} + \delta_q \mid \|\delta_q\| \leq \epsilon_q \right\},$$  \hspace{1cm} (5)

where $\delta_k \in \mathbb{C}^{N \times 1}$ and $\delta_q \in \mathbb{C}^{N \times 1}$ are the channel estimation errors [32], [33] with norms bounded by $\epsilon_k$ and $\epsilon_q$, respectively.

### B. Problem Formulation

Our goal is to design simultaneous information beamforming vectors $\{s_k \in \mathbb{C}^{N \times 1}\}$ and an energy beamforming vector $q \in \mathbb{C}^{N \times 1}$ for the information users and the energy user, respectively. The designed beamforming vectors should meet certain target requirements for all possible channel realizations.

The baseband signal from BS can be expressed as

$$x_b = \sum_{k=1}^{K} s_k v_k + q v_q,$$  \hspace{1cm} (6)

where $v_k \sim \mathcal{CN}(0,1)$ denotes the data symbol for the $k$th information user, and $v_q \sim \mathcal{CN}(0,1)$ is the signal energy for the energy user. The downlink signal at the $k$th information user can then be expressed as

$$y_k = h_k^H s_k v_k + \sum_{i \neq k, i \in K} h_k^H s_i v_i + h_k^H q v_q + n_k,$$  \hspace{1cm} (7)

where $n_k \sim \mathcal{CN}(0,\sigma_n^2)$ represents the antenna noise of the $k$th information user. Similarly, the downlink signal at the energy user is given by

$$y_q = \sum_{k=1}^{K} h_q^H s_k v_k + h_q^H q v_q + n_q,$$  \hspace{1cm} (8)

with $n_q \sim \mathcal{CN}(0,\sigma_q^2)$ representing the antenna noise of the energy user. Moreover, we assume that $\sigma_n^2 > 0$ and $\sigma_q^2 > 0$.

The harvested energy by the energy user is given by $\zeta \mathbb{E}[\|y_q\|^2]$, where $\zeta \in (0,1]$ denotes the energy conversion efficiency that depends on the rectification process and the energy harvesting circuit [20]–[22]. Using (8), we have

$$\mathbb{E}[\|y_q\|^2] = \sum_{k=1}^{K} \|h_q^H s_k\|^2 + \|h_q^H q\|^2 + \sigma_q^2.$$  \hspace{1cm} (9)

Our problem is to minimize the transmit power at the BS subject to the constraints that the harvested energy and SINR are above certain thresholds for all possible values of $h_k$ and $q$. This results in the optimization problem:

$$P_1 : \begin{array}{ll}
\min_{\{s_k\},q} & \|q\|^2 + \sum_{k=1}^{K} \|s_k\|^2 \\
\text{s.t.} & \zeta \left( \sum_{k=1}^{K} \|h_q^H s_k\|^2 + \|h_q^H q\|^2 + \sigma_q^2 \right) \geq Q, \\
& \|h_k^H s_k\|^2 + \|h_k^H q\|^2 + \sigma_k^2 \geq \gamma_k, \\
& \forall y_q \in U_q, \forall h_k \in U_k, k = 1,2,\ldots,K,
\end{array}$$  \hspace{1cm} (10a,10b,10c)

where $Q > 0$ is the desired harvested energy for the energy user, and $\gamma_k > 0$ is the target SINR for the $k$th information user. It is observed from (10a) that when $\sigma_q^2 - Q/\zeta \geq 0$ (the case that $Q$ is small enough), (10a) is always satisfied. We consider $\sigma_q^2 - Q/\zeta < 0$ in the rest of the paper.

When the channel estimation errors are equal to zero, i.e., $U_k = \{\hat{h}_k\}$ and $U_q = \{\hat{q}\}$, $P_1$ can be simplified to a non-robust optimization problem for massive MIMO, where a zero-forcing (ZF) beamformer [20]–[22] has been proven to be the optimal transmit strategy. In this case, the optimal information and energy beamforming directions for $P_1$ can be chosen as $h_k/\|h_k\|$ and $h_q/\|h_q\|$, respectively. Then, $P_1$ can be further simplified to a power allocation problem with ZF beamforming solutions given by

$$q = \left( \sqrt{Q/\zeta - \sigma_q^2} \right) \hat{h}_q / \|\hat{h}_q\|^2,$$

$$s_k = \left( \sqrt{\gamma_k \sigma_k^2} \right) \hat{h}_k / \|\hat{h}_k\|^2.$$  \hspace{1cm} (11)

However, when the channel estimation errors are not zero, i.e., $\epsilon_k > 0$ and $\epsilon_q > 0$, the optimal solutions of $P_1$ are in general hard to obtain [10]–[14]. Nevertheless, we next show that $P_1$ can be globally solved when $\{\epsilon_k\}$ and $\epsilon_q$ are sufficiently small. In addition, the solution reduces to (11) when there are no channel errors.

### III. Optimal Robust Beamforming

#### A. Semidefinite Relaxation (SDR)

We will solve $P_1$ by first obtaining an equivalent problem which has a natural SDR representation. Then, we show that the SDR has a closed-form solution that is optimal for the original problem under small channel errors.

The main difficulty in solving $P_1$ lies in the constraints (10a) and (10b). Substituting (5) into (10a), we equivalently...
Similarly, (10b) is equivalent to
\[
\begin{pmatrix}
\frac{1}{\gamma_k} s_k s_k^H - \sum_{i \neq k} s_i s_i^H - q q^H
\end{pmatrix}
\begin{pmatrix}
\delta_k
\end{pmatrix}
\geq 0,
\forall \delta_k,
\] (13)

We next use the following lemma to reformulate the constraints (12) and (13).

**Lemma 1 (S-Procedure [38]):** Let \( f_1(x) = x^H A_1 x + b_1^H x + c_1 \) and \( f_2(x) = x^H A_2 x + b_2^H x + c_2 \), for some \( A_1, A_2 \in \mathbb{C}^{n \times n}, b_1, b_2 \in \mathbb{C}^{n \times 1}, c_1, c_2 \in \mathbb{R} \). The condition \( f_1(x) \geq 0 \implies f_2(x) \geq 0 \) holds true if and only if there exists a nonnegative \( \mu \), such that
\[
\begin{pmatrix}
A_2 & b_2
\end{pmatrix}
\begin{pmatrix}
\mu
\end{pmatrix}
\begin{pmatrix}
b_1 & c_1
\end{pmatrix} \geq 0.
\] From Lemma 1, we know (12) holds true if and only if there exists \( \mu_q \geq 0 \) such that
\[
\begin{pmatrix}
X_q + \mu_q I
\end{pmatrix}
\begin{pmatrix}
X_q
\end{pmatrix}
\begin{pmatrix}
X_q
\end{pmatrix}
\begin{pmatrix}
\mu
\end{pmatrix}
\begin{pmatrix}
\delta_k
\end{pmatrix}
\begin{pmatrix}
\delta_k
\end{pmatrix}
\geq 0,
\forall \delta_k,
\] (14)

where for simplicity, we define
\[
X_q = q q^H + \sum_{k=1}^{K} s_k s_k^H.
\] (15)

Similarly, (13) holds true if and only if there exist \( \mu_{s_k} \geq 0 \), \( k = 1, 2, \ldots, K \) such that
\[
\begin{pmatrix}
X_{s_k} + \mu_{s_k} I
\end{pmatrix}
\begin{pmatrix}
X_{s_k}
\end{pmatrix}
\begin{pmatrix}
X_{s_k}
\end{pmatrix}
\begin{pmatrix}
\mu
\end{pmatrix}
\begin{pmatrix}
\delta_k
\end{pmatrix}
\begin{pmatrix}
\delta_k
\end{pmatrix}
\geq 0,
\forall \delta_k,
\] (16)

with
\[
X_{s_k} = \frac{1}{\gamma_k} s_k s_k^H - \sum_{i \neq k} s_i s_i^H - q q^H.
\] (17)

Using (14)–(17), P1 can be equivalently expressed as

**P1–EQV:**
\[
\min_{\mu_q, \{\mu_{s_k}\}, \{s_k\}} \text{Tr}(X_q)
\] (18a)

s.t.
\[
\begin{pmatrix}
X_q + \mu_q I
\end{pmatrix}
\begin{pmatrix}
X_q
\end{pmatrix}
\begin{pmatrix}
X_q
\end{pmatrix}
\begin{pmatrix}
\mu
\end{pmatrix}
\begin{pmatrix}
\delta_k
\end{pmatrix}
\begin{pmatrix}
\delta_k
\end{pmatrix}
\geq 0,
\forall \delta_k,
\] (18b)

\[
\begin{pmatrix}
X_{s_k} + \mu_{s_k} I
\end{pmatrix}
\begin{pmatrix}
X_{s_k}
\end{pmatrix}
\begin{pmatrix}
X_{s_k}
\end{pmatrix}
\begin{pmatrix}
\mu
\end{pmatrix}
\begin{pmatrix}
\delta_k
\end{pmatrix}
\begin{pmatrix}
\delta_k
\end{pmatrix}
\geq 0,
\forall \delta_k,
\] (18c)

\[
X_q = \sum_{k=1}^{K} S_k + Q,
\] (18d)

\[
X_{s_k} = \frac{1}{\gamma_k} S_k - \sum_{i \neq k} S_i - Q,
\] (18e)

where \( \mu_q \) and \( \{\mu_{s_k}\} \) are the auxiliary variables generated by the S-Procedure. The nonlinear constraints in (18g) are equivalent to:
\[
Q \geq 0, \quad S_k \geq 0, \quad \text{Rank}(Q) = 1, \quad \text{Rank}(S_k) = 1.
\] (19)

Clearly, P1–EQV is non-convex with rank constraints Rank(\( Q \)) = 1 and Rank(\( S_k \)) = 1. Dropping the rank constraints [39], we obtain the following relaxed convex optimization:

**P1–SDR:**
\[
\min_{\mu_q, \{s_k\}} \text{Tr}(X_q)
\] s.t. \((18b) - (18f), \quad Q \geq 0, \quad S_k \geq 0,
\] \[\text{for } k = 1, 2, \ldots, K.
\] (20)

Note that if the optimal solutions of P1–SDR are rank-1, then the optimal solutions of P1–EQV and P1–SDR are exactly the same [40], [41]. Nevertheless, directly solving P1–SDR as an SDP problem is extremely complex due to the large number of antennas. In addition, P1–SDR is not guaranteed to have rank-one solutions and hence the derived solutions may not be optimal for the initial problem P1 [13], [14]. We next show that P1–SDR indeed has rank-one solutions in the case of beamspace massive MIMO systems under some reasonable conditions.

**B. Optimal Rank-One Solutions**

In this subsection, we further investigate P1–SDR to provide more insight into the form of the optimal solutions.

Bearing in mind that under the beamspace massive MIMO setting (4), the estimated channels are orthogonal to each other, we define \( \{u_i = \hat{h}_i/||\hat{h}_i||, 1 \leq i \leq K\} \) and \( u_{K+1} = h_0/||h_0|| \).

**Proposition 1:** There exists a set of optimal solutions \( Q^* \) and \( \{S_k^*\} \) for P1–SDR that can be expressed in the following form:
\[
Q^* = \sum_{i=1}^{K+1} P_{q,i}^* u_i u_i^H, \quad S_k^* = \sum_{i=1}^{K+1} P_{s_{k,i}}^* u_i u_i^H,
\] (21)

where \( \{P_{q,i}^* \geq 0, 1 \leq i \leq K+1\} \) and \( \{P_{s_{k,i}}^* \geq 0, 1 \leq i \leq K+1\} \).

**Proof:** See Appendix A.

Due to the fact that the solution in (21) provides the same optimal objective value in (18a) as other optimal solutions, we will only consider solutions of the form (21) in the rest of the paper.

The following two propositions provide further insight into the optimal solution (21).

**Proposition 2:** At the optimal point, we have \( \mu_q > 0 \) in P1–SDR. Moreover, (18b) can be equivalently written as
\[
\mu_q \text{Tr}\left[ \hat{H}_q X_q (X_q + \mu_q I)^{-1} \right] + \sigma_q^2 - Q/\zeta - \mu_q \sigma_q^2 \geq 0,
\]
which can be further expressed as
\[
\mu_q \|\hat{h}_q\|^2 \left( P_{q,k+1} + \sum_{k=1}^{K} P_{s,k+1} \right) + \sigma_q^2 - Q/\zeta - \mu_q \epsilon_q^2 \geq 0.
\]

\[\mu_q + P_{q,k+1} + \sum_{k=1}^{K} P_{s,k+1} \]

\[\mu_q \mu_h \hat{h}_s \hat{X}_{s} (X_{s} + \mu_s I)^{\dagger} - \sigma_h^2 - \mu_s \epsilon_h^2 \geq 0,
\]
\[\hat{X}_{s} + \mu_s I \succeq 0,
\]

which can be further expressed as
\[
\mu_{s,k} \|\hat{h}_k\|^2 \left( \frac{P_{s,k}}{\gamma_k} - \sum_{i \neq k} P_{s,i,k} - P_{q,k} \right)
\]
\[\mu_{s,k} + \frac{P_{s,k}}{\gamma_k} - \sum_{i \neq k} P_{s,i,k} - P_{q,k} \geq 0, 1 \leq i \leq K + 1,
\]

respectively.

**Proof:** See Appendix C.

**Proposition 3:** At the optimal point, we have \(\mu_{s,k} > 0\) in P1–SDR. Moreover, (18c) can be equivalently written as
\[\mu_{s,k} \text{Tr} \left[ H_k X_{s} (X_s + \mu_s I)^{\dagger} \right] - \sigma_h^2 - \mu_s \epsilon_h^2 \geq 0,
\]
\[X_{s} + \mu_s I \succeq 0.
\]

**Proof:** See Appendix C.

Combining the above propositions leads to the following theorem.

**Theorem 1:** Let \(\mu_{s,k}^*, \{\mu_{s,k}^*\}\) and (21) be the optimal solutions of P1–SDR. If
\[
\min \{\mu_{s,k}^*\} \geq \sum_{i=1}^{K} P_{s,k+1}^* + P_{q,k+1}^*,
\]

then we have:

(a) \(Q^* = q^* q^H = P_{q} \hat{h}_q \hat{h}_q^H / \|\hat{h}_q\|^2\) is the optimal energy transmit covariance, where \(P_{q} = \sum_{i=1}^{K} P_{s,i,k+1}^* + P_{q,k+1}^*\) is the power allocated for energy beamforming;

(b) \(S^* = s^* s^H = P_{k} \hat{h}_k \hat{h}_k^H / \|\hat{h}_k\|^2\) is the optimal information transmit covariance, where \(P_{k}^* = P_{s,k}^* - \sum_{i \neq k} P_{s,i,k}^* - P_{q,k}^*\) is the power allocated to the kth information beamforming.

**Proof:** See Appendix D.

Theorem 1 says that when (22) holds, one of the optimal solutions of P1–SDR and P1 are exactly the same, and the optimal beamforming directions are equal to \(\hat{h}_q \hat{h}_q^H / \|\hat{h}_q\|^2\) and \(\hat{h}_k \hat{h}_k^H / \|\hat{h}_k\|^2\), respectively. The remaining optimal variables \(\mu_{q}^*, \mu_{s,k}^*, P_{q}^*\) and \(P_{k}^*\) are still to be obtained, which will be the topic of the next subsection.

**C. Optimal Power Allocation**

When (22) holds, the optimal energy beamforming and information beamforming vectors are \(q^* = \sqrt{P_{s,k}^* \hat{h}_q / \|\hat{h}_q\|}\) and \(s^*_k = \sqrt{P_{k}^* \hat{h}_k / \|\hat{h}_k\|}\), respectively. From Proposition 2, Proposition 3 and Theorem 1, P1–SDR can be simplified to the following power allocation problem:

\[
\text{P2:} \quad \begin{align*}
\min_{\mu_q, \{\mu_{s,k}\}, P_q} & \quad P_q + \sum_{k=1}^{K} P_k \\
\text{s.t.} & \quad \frac{\mu_{q} P_q \|\hat{h}_q\|^2}{\mu_q + P_q} + \sigma_q^2 - Q/\zeta - \mu_q \epsilon_q^2 \geq 0, \\
& \quad \frac{\mu_{s,k} P_k \|\hat{h}_k\|^2}{\mu_{s,k} \gamma_k + P_k} - \sigma_h^2 - \mu_s \epsilon_h^2 \geq 0, \\
& \quad \mu_q > 0, \mu_{s,k} > 0, P_q \geq 0, P_k \geq 0, \\
& \quad k = 1, 2, \ldots, K.
\end{align*}
\]

Note that when \(P_q = 0\), the constraint (23b) is never satisfied since \(\sigma_q^2 - Q/\zeta < 0\) and \(\mu_q \epsilon_q^2 > 0\). Thus, we must have \(P_q > 0\). Similarly, \(P_k > 0\) holds in P2. Moreover, since \(P_q^* = \sum_{i=1}^{K} P_{s,i,k+1}^* + P_{q,k+1}^*\) holds at the optimal point in Theorem 1, condition (22) can be expressed as
\[
\min \{\mu_{s,k}^*\} \geq P_{q,k}^*,
\]
which implies that the optimal solutions of P2 are exactly the same as P1 if \(\min \{\mu_{s,k}^*\} \geq P_{q,k}^*\).

Define
\[
f_q(\mu_q, P_q) = \frac{\mu_q P_q \|\hat{h}_q\|^2}{\mu_q + P_q}, \quad f_{s,k}(\mu_{s,k}, P_k) = \frac{\mu_{s,k} P_k \|\hat{h}_k\|^2}{\mu_{s,k} \gamma_k + P_k}.
\]

The Hessian matrices of \(f_q(\mu_q, P_q)\) and \(f_{s,k}(\mu_{s,k}, P_k)\) are given by
\[
\nabla^2 f_q(\mu_q, P_q) = \frac{-2 \|\hat{h}_q\|^2}{(\mu_q + P_q)^3} \begin{bmatrix} P_q^2 & -\mu_q P_q & -\mu_q P_q \\
-\mu_q P_q & -\mu_q P_q & -\mu_q P_q \\
-\mu_q P_q & -\mu_q P_q & -\mu_q P_q \\
\end{bmatrix},
\]
\[
\nabla^2 f_{s,k}(\mu_{s,k}, P_k) = \frac{-2 \gamma_k \|\hat{h}_k\|^2}{(\mu_{s,k} \gamma_k + P_k)^3} \begin{bmatrix} P_k^2 & -\mu_{s,k} P_k & -\mu_{s,k} P_k \\
-\mu_{s,k} P_k & -\mu_{s,k} P_k & -\mu_{s,k} P_k \\
-\mu_{s,k} P_k & -\mu_{s,k} P_k & -\mu_{s,k} P_k \\
\end{bmatrix},
\]

respectively. Due to \(\mu_q > 0, \mu_{s,k} > 0, P_q > 0, P_k > 0, \|\hat{h}_q\|^2 > 0\) and \(\|\hat{h}_k\|^2 > 0\), it can be easily derived from the Hessian matrices that \(\nabla^2 f_q(\mu_q, P_q) < 0\) and \(\nabla^2 f_{s,k}(\mu_{s,k}, P_k) < 0\), which implies that \(f_q(\mu_q, P_q)\) and \(f_{s,k}(\mu_{s,k}, P_k)\) are concave functions. Thus, P2 is a convex optimization formulation.

Using the Karush-Kuhn-Tucker (KKT) conditions for P2, we prove the following results.

**Proposition 4:** When
\[
\min \left\{ \frac{\sigma^2}{\|\hat{h}_q\|^2 - \epsilon_k \epsilon_k} \right\} \geq \frac{Q/\zeta - \sigma_q^2}{\|\hat{h}_q\|^2 - \epsilon_q \epsilon_q},
\]

the optimal solutions of P2 are also optimal for P1, and are given by
\[
\mu_q = \frac{P_q^* \|\hat{h}_q\|^2 - P_q \epsilon_q}{\epsilon_q}, \quad \mu_{s,k} = \frac{P_k^* \|\hat{h}_k\|^2 - P_k \epsilon_k}{\gamma_k \epsilon_k},
\]
\[
P_q^* = \frac{Q/\zeta - \sigma_q^2}{\|\hat{h}_q\|^2 - \epsilon_q \epsilon_q}, \quad P_k^* = \frac{Q/\zeta - \sigma_h^2}{\|\hat{h}_k\|^2 - \epsilon_h \epsilon_h},
\]
where \(k \in \{1, \ldots, K\}\).

**Proof:** See Appendix E.

The variables in (25) are all known at the BS. Thus it is easy to determine whether the solutions in (26) and (27) are optimal.
for P1. Note that when (25) is not satisfied, the optimal solutions of P2 are in general suboptimal for P1.

We summarize the main results of this section in the following theorem.

**Theorem 2:** If (25) is satisfied, then the optimal beamforming vectors for P1 are given by

\[
q^* = \sqrt{\frac{Q/\zeta - \sigma_q^2}{\|\hat{h}_q\|^2}} \hat{h}_q / \|\hat{h}_q\|,
\]

\[
s_k^* = \sqrt{\frac{\gamma_k \sigma_k^2}{\|\hat{h}_k\|^2}} \hat{h}_k / \|\hat{h}_k\|.
\]

(28)

When (25) is not satisfied, it is shown in simulations that (28) can serve as an efficient alternative to the conventional SDR method, even when the estimation errors are large. The number of variables to be solved for P1–SDR and P2 are compared in Table I. For P1–SDR, there are a total of \((N + 1)(K + 1)\) unknown variables. For P2, there are \(2(K + 1)\) unknown variables. Consequently, P2 leads to a much lower computational cost than P1–SDR. Moreover, the optimal solutions of P2 are in closed-form and can be easily calculated.

**IV. SIMULATION RESULTS**

In this section, we present simulations to evaluate the performance of the proposed closed-form robust beamformer. For simplicity, the target SINR of all users are assumed to be the same, i.e., \(\gamma = \gamma_1, \ldots, = \gamma_K\). The channel estimation errors are generated as independent CSCG random variables distributed as \(CN(0, g^2)\), where we define \(g = \epsilon_k / \|\hat{h}_k\| = \epsilon_q / \|\hat{h}_q\|\) with \(g \in [0, 1]\). The simulation results are averaged over 10000 Monte Carlo runs.

In the first example, we examine the average CPU running times versus the parameter \(g\) in Fig. 2 and the harvest power \(Q/\zeta\) in Fig. 3, respectively. The rank-1 probability (see right axis) is provided to indicate when the optimal solutions of P1–SDR are rank-1. The simulation results of the conventional randomized SDR method [39] are also displayed for comparison. It is observed from Fig. 2 and Fig. 3 that the rank-1 probability of P1–SDR is a decreasing function with respect to \(g\) and \(Q/\zeta\). The optimal solutions of P1–SDR are always rank-1 when \(g \leq 0.15\) and \(Q/\zeta \leq 10\) dBm, which means that we can always derive the optimal solutions using the closed-form robust beamforming method when \(g\) and \(Q/\zeta\) are small. In addition, we see that the average CPU running time of the closed-form robust beamforming method is a small constant (say about 0.004s) which does not change with \(g\) and \(Q/\zeta\). This is mainly due to the fact the optimal solutions have closed-forms, and thus the change of \(g\) or \(Q/\zeta\) will not affect the computational complexity. On the other hand, the average CPU running time of the conventional randomized SDR is an increasing function with respect to \(g\) and \(Q/\zeta\), which is much greater than that of the proposed method. In fact, the rank-1 probability of P1–SDR approaches zero when \(g\) and \(Q/\zeta\) are large enough, where the conventional randomized SDR method needs more time to find the suboptimal rank-1 solutions [39].

In the second example, we plot the average information users’ SINR versus \(g\) and transmit antennas \(N\) for the closed-form robust beamforming method, the randomized SDR method, and the non-robust method in Fig. 4 and Fig. 5. The optimal beamforming solutions of P1 for the non-robust method are given by (11):

\[
q = \left(\sqrt{Q/\zeta - \sigma_q^2}\right) \hat{h}_q / \|\hat{h}_q\|^2\text{ and } s_k = \left(\sqrt{\gamma_k \sigma_k^2}\right) \hat{h}_k / \|\hat{h}_k\|^2.
\]

It is clearly seen from Fig. 4 that the average SINR of information users for the non-robust method is a decreasing function with respect to \(g\). The reason

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**TABLE I**

**NUMBER OF VARIABLES COMPARISON**

<table>
<thead>
<tr>
<th>Variables</th>
<th>Problems</th>
<th>P1–SDR</th>
<th>P2</th>
</tr>
</thead>
<tbody>
<tr>
<td>Number of Real</td>
<td>(K + 1)</td>
<td>(2 \times (K + 1))</td>
<td></td>
</tr>
<tr>
<td>Number of Complex</td>
<td>(N \times (K + 1))</td>
<td>0</td>
<td></td>
</tr>
<tr>
<td>Total Variables</td>
<td>((N + 1) \times (K + 1))</td>
<td>(2 \times (K + 1))</td>
<td></td>
</tr>
</tbody>
</table>
Fig. 4. Average information users’ SINR versus parameter $g$ with $K = 30$, $N = 128$, $Q/\zeta = 10$ dBm, and $\gamma = 10$ dB.

Fig. 5. Average information users’ SINR versus number of transmit antennas $N$ with $K = 30$, $g = 0.3$, $Q/\zeta = 10$ dBm, and $\gamma = 10$ dB.

is that the non-robust solution does not take the channel estimation errors into consideration. Interestingly, the average SINR of information users for the closed-form robust beamforming algorithm increases with $g$ when $g \leq 0.3$. This is mainly due to the fact that when $g$ increases, the BS will allocate more power for information beamforming (see (E.11) for details). While the average information users’ SINR for the closed-form robust beamforming algorithm will decrease with the increase of $g$ when $g > 0.3$. This phenomenon can be explained by Fig. 2 which shows that the rank-1 probability will always be zero when $g > 0.3$. In this case, all the optimal solutions of $P1-\text{SDR}$ are not rank-1, and thus the performance of the closed-form robust beamforming algorithm deteriorates with increasing $g$. Moreover, it is clear that the performance of the closed-form robust beamforming algorithm is exactly the same as that of the randomized SDR method when $g$ is small (i.e., the rank-1 probability is equal to 1). The gap between the closed-form robust beamforming algorithm and randomized SDR is small when $g$ is large, which means that we can obtain good performance using the proposed approach. Similarly, it is seen from Fig. 5 that the average harvested power for the closed-form robust beamforming algorithm, randomized SDR and the non-robust method increases with $N$, which implies that we could use more antennas to improve the performance of beamspace massive MIMO systems.

In the third example, we plot the average harvested power versus $g$ and $N$ in Fig. 6 and Fig. 7, respectively. We see from Fig. 6 that the average harvested power is an increasing function with respect to $g$. This is mainly due to the fact that when $g$ increases, more power is received at the energy user. However, it is clear from Fig. 7 that the average harvested power is a decreasing function of $N$. Nevertheless, the average harvested power derived by the three methods is always bigger than 10 dBm, which says that the constraint in (10a) is strictly satisfied.

In the last example, we plot the average minimum transmit power versus $g$ and $N$ in Fig. 8 and Fig. 9, respectively. It is seen from Fig. 8 that the transmit power for the non-robust method will not change with $g$, while the transmit power for the closed-form robust beamforming algorithm and the randomized SDR approach increases when $g$ becomes large. This is because when the channel estimation errors increase, the BS will allocate more power to eliminate CSI uncertainty. As a result, the proposed algorithm and the randomized SDR approach can obtain a much higher average SINR of information users and average harvested power than the non-robust method. Moreover, it is clear from Fig. 9 that the transmit
power for the three methods decreases with increasing $N$, which means that we may save more power with large number of antennas at the BS.

V. CONCLUSIONS

In this paper, we design simultaneous robust information and energy beamforming for SWIPT in a multiuser beamspace massive MIMO system. Our target is to minimize the transmit power of the BS while providing the information users and the energy user with desired SINRs and harvested power, respectively. Instead of solving the optimization with SDP techniques, we solve a relaxed power allocation problem, where beamforming directions and power allocations are derived in closed-form. More importantly, we prove that the relaxed power allocation problem is equivalent to the initial robust design under beamspace massive MIMO schemes when the channel estimation errors are small enough. Simulation results are provided to corroborate the results, and show that the developed approach still achieves good performance even when the channel estimation errors are large.

APPENDIX A

PROOF OF PROPOSITION 1

Assume $Q^*$ and $S_k^*$, $1 \leq k \leq K$ are the optimal solutions of P1–SDR. Define the $N \times N$ unitary matrix $U$ as $U = [u_1, \ldots, u_N]$ where $\{u_i, K + 2 \leq i \leq N\}$ are an arbitrary set of orthonormal vectors that are orthogonal to $\{u_i, 1 \leq i \leq K + 1\}$.

A. Part (a): Proving that for any pair of optimal $Q^*$ and $S_k^*$, there must exist another pair of optimal solutions $Q^*$ and $S_k^*$ that can be simultaneously diagonalized by $U$ and $U^H$.

Since $U$ is unitary, $Q^* \succeq 0$, and $S_k^* \succeq 0$, we can always write

$$Q^* = UD_qU^H, \quad S_k^* = UD_{s_k}U^H,$$

(A.1)

for some $D_q \succeq 0$ and $D_{s_k} \succeq 0$. Substituting (A.1) into (18d) and (18e), we have

$$X_q^* = U \left( \sum_{k=1}^{K} D_{s_k} + D_q \right) U^H,$$

$$X_{s_k}^* = U \left( \frac{1}{\gamma_k} D_{s_k} - \sum_{i \neq k} D_{s_i} - D_q \right) U^H.$$  

(A.2)

We will show below that we can choose the matrices $D_q$ and $D_{s_k}$ to be diagonal.

**Lemma 2 (Schur’s Complement [43]):** Let $M = [A, B; B^H, C]$ be a Hermitian matrix. Then, $M \succeq 0$ if and only if $C - B^HA^{-1}B \succeq 0$ (assuming $A \succ 0$), or $A - BC^{-1}B^H \succeq 0$ (assuming $C \succ 0$).

**Lemma 3 (Generalized Schur’s Complement [43]):** Let $M = [A, B; B^H, C]$ be a Hermitian matrix. Then, $M \succeq 0$ if and only if $C - B^HA^B \succeq 0$ and $(I - AA^H)B = 0$ (assuming $A \succeq 0$), or $A - BC^H \succeq 0$ and $(I - CC^H)B^H = 0$ (assuming $C \succeq 0$).

Denote $D_q(i, j)$ and $D_{s_k}(i, j)$ as the $(i, j)$th elements of $D_q$ and $D_{s_k}$, respectively. Let $A_q = X_q^* + \mu_q^2 I$, $B_q = X_q^* \hat{h}_q$, and $C_q = \hat{h}_q^H X_q^* \hat{h}_q + \sigma_q^2 - Q/\zeta - \mu_q^2 \sigma_q^2$ for elements in (18b). Then $A_q \succeq 0$ and $C_q \succeq 0$ hold. Substituting (A.2) into (18b) and using the definitions of $U$ and $\{u_k\}$, we obtain

$$A_q = U \left( \sum_{k=1}^{K} D_{s_k} + D_q + \mu_q^2 I \right) U^H,$$

(A.3)

$$B_q = U \left( \sum_{k=1}^{K} D_{s_k} + D_q \right) U^H u_{K+1+1}^H \hat{h}_q ||,$$

$$= \| \hat{h}_q \| U \left( \sum_{k=1}^{K} D_{s_k}(i, K+1) + D_q(i, K+1) \right),$$  

(A.4)

$$C_q = u_{K+1}^H \hat{h}_q B_q + \sigma_q^2 - Q/\zeta - \mu_q^2 \sigma_q^2$$

$$= \| \hat{h}_q \|^2 \left( \sum_{k=1}^{K} D_{s_k}(K+1, K+1) + D_q(K+1, K+1) \right) + \sigma_q^2 - Q/\zeta - \mu_q^2 \sigma_q^2.$$  

(A.5)

We next consider the following two cases for the constraint (18b).

**Case 1:** $C_q > 0$: From Lemma 2, we know (18b) is equivalent to $A_q - B_q C_q^{-1} B_q^H \succeq 0$. Using (A.3)-(A.5),
we obtain

$$A_q - B_q C_q^{-1} B_q^H = U D_{q, \Omega} U^H,$$

where

$$D_{q, \Omega} = \left( \sum_{k=1}^{K} D_{sk} + D_q + \mu_q I \right) - \frac{||\tilde{h}_q||^2}{C_q} \left( \sum_{k=1}^{K} D_{sk} (i, K+1) + D_q (i, K+1) \right)^H.$$

Thus, (18b) is equivalent to $D_{q, \Omega} \succeq 0$. In particular, all the diagonal elements of $D_{q, \Omega}$ must be nonnegative, i.e., $\text{diag}(D_{q, \Omega}) \succeq 0$, which results in the requirement

$$\left( \sum_{k=1}^{K} D_{sk} (i, i) + D_q (i, i) + \mu_q I \right) - \frac{||\tilde{h}_q||^2}{C_q} \left( \sum_{k=1}^{K} D_{sk} (i, K+1) + D_q (i, K+1) \right)^2 \geq 0,$$

for all $1 \leq i \leq N$. To construct the following new solutions

$$Q^* = U \Lambda_q U^H, \quad S_k^* = U \Lambda_s U^H,$$

where $\Lambda_q = \text{diag}(D_q) \succeq 0$ and $\Lambda_s = \text{diag}(D_s) \succeq 0$. We next prove that (A.8) also satisfies (18b).

Using (A.2)-(A.5), we have

$$A_q^* = U \text{diag} \left( \sum_{k=1}^{K} D_{sk} + D_q + \mu_q I \right) U^H,$$

$$B_q^* = \frac{||\tilde{h}_q|| \mu_k}{k+1} \left( \sum_{k=1}^{K} D_{sk} (K+1, K+1) + D_q (K+1, K+1) \right),$$

$$C_q^* = C_q.$$

From $A_q^*, B_q^*$ and $C_q^*$, we obtain

$$A_q^* - B_q^* C_q^{-1} B_q^H = U \Lambda_q, U^H,$$

where $\Lambda_q = \text{diag}(D_q(i, i))$ can be expressed as

$$\Lambda_q(i, i) = \sum_{k=1}^{K} D_{sk} (i, i) + D_q (i, i) + \mu_q I, \quad i \neq K + 1,$$

$$\Lambda_q(i, i) = \sum_{k=1}^{K} D_{sk} (i, i) + D_q (i, i) + \mu_q I - \Omega_{K+1, K+1}, \quad i = K + 1,$$

and $\Omega_{K+1, K+1}$ is computed as

$$\frac{||\tilde{h}_q||^2}{C_q} \left( \sum_{k=1}^{K} D_{sk} (K+1, K+1) + D_q (K+1, K+1) \right)^2.$$

From (A.7), $\Lambda_q(i, i) = \text{diag}(D_q(i, i)) = \text{diag}(D_{q, \Omega}) (i, i) \geq 0$. In addition, $\Lambda_q(i, i) \geq \text{diag}(D_{q, \Omega}) (i, i) \geq 0$, $i \neq K + 1$. Thus, $\Lambda_q(i, i) \geq 0$ holds for all $1 \leq i \leq N$, and $A_q^* - B_q^* C_q^{-1} B_q^H \succeq 0$ also holds.

Case 2: $C_q = 0$: From (18b) and Lemma 3, there must be $A_q - B_q C_q^{-1} B_q^H \succeq 0$ and $(1 - C_q C_q^{-1}) B_q^H = 0$. Since $C_q = 0$ and $B_q = 0$ must hold. Thus, the constraint (18b) can be equivalently expressed as $A_q \succeq 0$, or

$$\text{diag} \left( \sum_{k=1}^{K} D_{sk} + D_q + \mu_q I \right) \succeq 0,$$

and we have $A_q^* = U \text{diag} \left( \sum_{k=1}^{K} D_{sk} + D_q + \mu_q I \right) U^H \succeq 0$.

Similarly, we can show that (A.8) also satisfy the constraint (18c). The details are omitted here for brevity.

Moreover, it can be readily checked that (A.8) does not change the objective value and at the same time satisfies the constraints (18d)-(18f), (20). Consequently, the solutions (A.8) are also optimal for $	extbf{P1-SDR}$, which can be simultaneously diagonalized by $U$ and $U^H$.

B. Part (b): Proof of (21)

Let us show that $Q^*$ and $S_k^*$ in (A.8) will have at most $K + 1$ non-zero eigenvalues, i.e., will have the form (21).

Assume first that all $K + 1$ eigenvalues in $\Lambda_q$ and $\Lambda_s$ are non-zeros. Using (A.8) and the definitions $u_i = h_i / ||h_i||, 1 \leq i \leq K$ and $u_{K+1} = h_q / ||h_q||$, we know that the optimal $Q^*$ and $S_k^*$, $1 \leq j \leq K$ can be expressed as

$$Q^* = \sum_{i=1}^{K} P_{q,i} \tilde{h}_i \tilde{h}_i^H + \sum_{j=K+2}^{N} P_{q,j} u_j u_j^H,$$

$$S_k^* = \sum_{i=1}^{K} P_{s,i} \tilde{h}_i \tilde{h}_i^H + \sum_{j=K+2}^{N} P_{s,j} u_j u_j^H,$$

where $P_{q,j} \geq 0$ and $P_{s,j} \geq 0$, for $j \in \{K+2, \ldots, N\}$. We can then set $P_{q,j} = 0$ and $P_{s,j} = 0$ to construct the following new solutions

$$Q^{**} = \sum_{i=1}^{K} P_{q,i}^* u_i u_i^H,$$

$S_k^{**} = \sum_{i=1}^{K} P_{s,i}^* u_i u_i^H.$

Substituting (A.10) into $	extbf{P1-SDR}$, we obtain from the objective function that

$$\text{Tr}(Q^{**}) + \sum_{k=1}^{K} \text{Tr}(S_k^{**}) < \text{Tr}(Q^*) + \sum_{k=1}^{K} \text{Tr}(S_k^*),$$

which says that (A.10) provides a smaller objective value. Similar to the proof of Part (a), it can be verified that (A.10) does not violate the constraint $A_q^* - B_q^* C_q^{-1} B_q^H \succeq 0$, which implies that (A.10) satisfies all constraints of $	extbf{P1-SDR}$. As a result, $Q^{**}$ and $\{S_k^{**}\}$ are better solutions than $Q^*$ and $\{S_k^*\}$, which contradicts our assumption. Thus, there exist optimal solutions that satisfy (21), which completes the proof of Proposition 1.
must be satisfied. Left and right multiplying both sides of $Y_q$ by $[-h_q^H 1]$ and $[-h_q^H 1]^H$ yields
\[ [-h_q^H 1] Y_q [-h_q^H 1]^H = \sigma_q^2 - Q/\zeta \geq 0, \] (B.2)
which, however, cannot be true due to our assumption that $\sigma_q^2 - Q/\zeta < 0$ (see P1 for details). Thus, there must be $\mu_q > 0$ in P1–SDR.

Next, due to the fact that $S_k \geq 0$ and $Q \geq 0$, there holds
\[ X_q + \mu_q I = \sum_{k=1}^{K} S_k + Q + \mu_q I > 0, \] (B.3)
and hence $(X_q + \mu_q I)^{-1}$ exists. Define $\tilde{h}_q = h_q^H$. The constraint in (18b) of P1–SDR can then be equivalently expressed as
\[ \tilde{h}_q^H X_q \tilde{h}_q + \sigma_q^2 - Q/\zeta - \mu_q \epsilon_q^2 \tilde{h}_q^H X_q (X_q + \mu_q I)^{-1} X_q \tilde{h}_q = \text{Tr} \left\{ \left( \tilde{H}_q X_q \right) \left[ I - (X_q + \mu_q I)^{-1} X_q \right] \right\} + \sigma_q^2 - Q/\zeta - \mu_q \epsilon_q^2 \\
= \text{Tr} \left\{ \left( \tilde{H}_q X_q \right) \left[ I - (X_q + \mu_q I)^{-1} (X_q + \mu_q I - \mu_q I) \right] \right\} + \sigma_q^2 - Q/\zeta - \mu_q \epsilon_q^2 \\
= \mu_q \text{Tr} \left\{ \tilde{H}_q X_q (X_q + \mu_q I)^{-1} \right\} + \sigma_q^2 - Q/\zeta - \mu_q \epsilon_q^2 \geq 0, \] (B.4)
where $X_q + \mu_q I$ is equivalent to
\[ \sum_{i=1}^{K+1} \left( \sum_{k=1}^{K} P_{k,i} + \mu_q \right) u_i u_i^H + \sum_{i=K+2}^{N} \mu_q u_i u_i^H. \] (B.5)
Noting that $\tilde{H}_q = \|h_q\|^2 u_{K+1} u_{K+1}^H$ and substituting (B.5) into (B.4), we obtain
\[ \frac{\mu_q \|\tilde{h}_q\|^2}{\mu_q + P_{q,K+1} + \sum_{k=1}^{K} P_{k,K+1} + \sum_{k=1}^{K} P_{k,K+1}} \geq 0, \] (B.6)
which completes the proof of Proposition 2.

**APPENDIX C**

**PROOF OF PROPOSITION 3**

First, we show that $\mu_{sk} > 0$ must hold via contradiction. Assuming $\mu_{sk} = 0$ for some $1 \leq k \leq K$, it follows from (18c) that
\[ Y_{sk} = \begin{bmatrix} X_{sk}^H h_k^H X_{sk} & X_{sk} \end{bmatrix} \begin{bmatrix} h_k^H X_{sk} & h_k^H \end{bmatrix} \begin{bmatrix} h_k^H \end{bmatrix} - \sigma_k^2 \geq 0, \] (C.1)
must be satisfied. Left and right multiplying both sides of $Y_{sk}$ by $[-h_{sk}^H 1]$ and $[-h_{sk}^H 1]^H$, respectively, yields
\[ [-h_{sk}^H 1] Y_{sk} [-h_{sk}^H 1]^H \geq 0, \] (C.2)
region, which cannot be true since $\sigma_k^2 > 0$. Thus, there must be $\mu_{sk} > 0$ for all $1 \leq k \leq K$ in P1–SDR.

Next, let us show that $\text{Rank} \left( X_{sk}^* + \mu_{sk}^* I \right) \geq 1$ by contradiction. Assume $\text{Rank} \left( X_{sk}^* + \mu_{sk}^* I \right) = 0$ or $X_{sk}^* + \mu_{sk}^* I = 0$ at the optimal point. We know from (18c) that
\[ \begin{bmatrix} 0 & X_{sk}^* h_k \end{bmatrix} \begin{bmatrix} h_k^H X_{sk} & h_k^H \end{bmatrix} \begin{bmatrix} h_k \end{bmatrix} - \sigma_k^2 \geq 0. \] (C.3)
However, (C.2) cannot be true due to $\mu_{sk}^* > 0$ and $h_k^H (-\mu_{sk}^* I) h_k - \sigma_k^2 - \mu_{sk}^* \epsilon_k^2 < 0$. Thus, $\text{Rank} \left( X_{sk}^* + \mu_{sk}^* I \right) \geq 1$, for all $k \in \{1, \ldots, K\}$.

Using Lemma 3, (18c) of P1–SDR can be equivalently expressed as
\[ \begin{bmatrix} I - (X_{sk} + \mu_{sk} I) (X_{sk} + \mu_{sk} I)^\dagger \end{bmatrix} X_{sk} \tilde{h}_k = 0, \] (C.3)
\[ \tilde{h}_k X_{sk} h_k - \sigma_k^2 - \mu_{sk} \epsilon_k^2 \geq 0. \] (C.4)
\[ X_{sk} + \mu_{sk} I \geq 0. \] (C.5)

We now show that the constraint (C.3) can be eliminated. Define $\tilde{H}_k = \tilde{h}_k h_k^H$, which can be further expressed as
\[ H_k = \|\tilde{h}_k\|^2 u_k u_k^H. \] (C.6)
Due to the fact that $\sigma_k^2 > 0$, $\mu_{sk} > 0$ and $\epsilon_k^2 > 0$, it is easily seen from (C.4) that $\text{Tr} \left( H_k X_{sk} \right) > 0$ holds, where $X_{sk}$ can be expressed as
\[ X_{sk} = \sum_{i=1}^{K+1} \left( \sum_{j=k}^{K} P_{j,i} - P_{q,i} \right) u_i u_i^H, \] (C.7)
with the aid of (21). Substituting (C.6) and (C.7) into $\text{Tr} \left( H_k X_{sk} \right) > 0$, we obtain
\[ \text{Tr} \left( H_k X_{sk} \right) = \|\tilde{h}_k\|^2 \left( \sum_{j=k}^{K} P_{j,k} - P_{q,k} \right) > 0. \] (C.8)
Consequently, we have $\|\tilde{h}_k\|^2 > 0$ and
\[ \sum_{j=k}^{K} P_{j,k} - P_{q,k} > 0, \] (C.9)
which says that the $k$th eigenvalue of $X_{sk}$ is greater than zero. Moreover, since $\mu_{sk} > 0$, we know that the $k$th eigenvalue of $X_{sk} + \mu_{sk} I$ is greater than zero, which implies that the $k$th eigenvalue of $\left( X_{sk} + \mu_{sk} I \right) \left( X_{sk} + \mu_{sk} I \right)^\dagger$ is equal to one. As a result, we conclude that the $k$th eigenvalue of $I - (X_{sk} + \mu_{sk} I) (X_{sk} + \mu_{sk} I)^\dagger$ is equal to zero. Thus (C.3) will always be satisfied when (C.4) and (C.5) are true, i.e., (18c) of P1–SDR can be equivalently expressed as (C.4) and (C.5). Finally, since $X_{sk} = X_{sk}^H$, (C.4) is equivalent to
\[ \begin{bmatrix} I - (X_{sk} + \mu_{sk} I) (X_{sk} + \mu_{sk} I)^\dagger \end{bmatrix} X_{sk} \tilde{h}_k = 0, \] (C.10)
Due to the fact that the $k$th eigenvalue of $I - (X_{sk} + \mu_{sk} I) (X_{sk} + \mu_{sk} I)^\dagger$ is equal to zero, using (C.6) and (C.7), we have
\[ \text{Tr} \left( H_k X_{sk} \right) \left( I - (X_{sk} + \mu_{sk} I) (X_{sk} + \mu_{sk} I)^\dagger \right) = 0. \] (C.11)
Thus, (C.9) can be expressed as
\[
\begin{align*}
\hat{h}_k^H X_{s_k} \hat{h}_k - \sigma_k^2 - \mu_s^2 \epsilon_k^2 - \hat{h}_k^H X_{s_k} (X_{s_k} + \mu_s I)^\dagger X_{s_k} \hat{h}_k \\
= \mu_{sk} \text{Tr} \left[ \hat{H}_k^H X_{s_k} (X_{s_k} + \mu_s I)^\dagger \right] - \sigma_k^2 - \mu_s \epsilon_k^2 \geq 0.
\end{align*}
\]

Consequently, substituting (C.6) and (C.7) into (C.4) and (C.5), (18c) of P1–SDR is equivalent to
\[
\begin{align*}
\mu_{sk} \| \hat{h}_k \|^2 (P_{sk,k}/\gamma_k - \sum_{i \neq k} P_{s_i,k} - P_{q,k}) - \sigma_k^2 - \mu_s \epsilon_k^2 \geq 0,
\end{align*}
\]
\[
\begin{align*}
\frac{P_{sk,i}}{\gamma_k} - \sum_{i \neq k} P_{s_i,i} - P_{q,i} + \mu_s \geq 0, \quad \forall 1 \leq i \leq K + 1,
\end{align*}
\]
completing the proof of Proposition 3.

**APPENDIX D**

**PROOF OF THEOREM 1**

From Proposition 2 and Proposition 3, we know that P1–SDR can be equivalently expressed as

\[
\begin{align*}
P1–SDR–EQV : \quad & \min_{\mu_q \in \{\mu_q\}, Q, \{S_k\}} \text{Tr}(X_q) \\
& \text{s.t.} \\
& \mu_q \text{Tr} \left[ \hat{H}_q X_q (X_q + \mu_q I)^\dagger \right] + \sigma_q^2 - Q/\zeta - \mu_q^2 \geq 0, \quad \text{(D.1a)} \\
& \mu_{sk} \text{Tr} \left[ \hat{H}_k X_{s_k} (X_{s_k} + \mu_s I)^\dagger \right] - \sigma_k^2 - \mu_s \epsilon_k^2 \geq 0, \quad \text{(D.1b)} \\
& X_{s_k} + \mu_s I \succeq 0, \quad \text{(D.1c)} \\
& X_q = \sum_{k}^K S_k + Q, \quad X_{s_k} = \frac{1}{\gamma_k} S_k - \sum_{i \neq k} S_i - Q, \quad \text{(D.1d)} \\
& \mu_q \geq 0, \mu_{sk} \geq 0, Q \succeq 0, S_k \succeq 0, \quad k = 1, 2, \ldots, K, \quad \text{(D.1e)}
\end{align*}
\]

Assuming $\mu_q^*, \{\mu_{sk}^*\}, Q^*, \{S_k^*\}$ are the optimal solutions of P1–SDR–EQV, it has been shown in Proposition 1 that $Q^*, \{S_k^*\}$ can be chosen to have the following form
\[
\begin{align*}
Q^* &= \sum_{i=1}^{K} P^*_{q,i} \frac{\hat{h}_{q,i}^H}{\| \hat{h}_{q,i} \|^2} + P^*_{q,K+1} \frac{\hat{h}_{q,K+1}^H}{\| \hat{h}_{q,K+1} \|^2}, \\
S_k^* &= \sum_{i=1}^{K} P^*_{s_k,i} \frac{\hat{h}_{s_k,i}^H}{\| \hat{h}_{s_k,i} \|^2} + P^*_{s_k,K+1} \frac{\hat{h}_{s_k,K+1}^H}{\| \hat{h}_{s_k,K+1} \|^2}.
\end{align*}
\]

Let the transmit power for the energy user be
\[
P_q^* = \sum_{i=1}^{K} P^*_{q,i,K+1} + P^*_{q,K+1}, \quad \text{(D.3)}
\]
and the transmit power for the information users be
\[
P_k^* = P^*_{s_k,k} - \sum_{i \neq k} P^*_{s_i,k} - P^*_{q,k}. \quad \text{(D.4)}
\]

Construct a sequence of new solutions as follows
\[
Q^* = \sum_{i=1}^{K} P^*_{q,i} \frac{\hat{h}_{q,i}^H}{\| \hat{h}_{q,i} \|^2}, \quad S_k^* = \sum_{i=1}^{K} P^*_{s_k,i} \frac{\hat{h}_{s_k,i}^H}{\| \hat{h}_{s_k,i} \|^2}, \quad k = 1, 2, \ldots, K, \quad \text{(D.5)}
\]
which satisfy $\text{Rank} (Q^*) \leq 1$ and $\text{Rank} (S_k^*) \leq 1$, for all $k \in \{1, \ldots, K\}$.

With (D.5),
\[
X_q^* = \sum_{k=1}^{K} S_k^* + Q^* \quad \text{and} \quad X_{s_k}^* = \frac{1}{\gamma_k} S_k^* - \sum_{i \neq k} S_i^* - Q^*.
\]

Let the transmit power for the energy user be
\[
P_q^* = \sum_{i=1}^{K} P^*_{q,i,K+1} + P^*_{q,K+1}, \quad \text{(D.3)}
\]
and the transmit power for the information users be
\[
P_k^* = P^*_{s_k,k} - \sum_{i \neq k} P^*_{s_i,k} - P^*_{q,k}. \quad \text{(D.4)}
\]

Construct a sequence of new solutions as follows
\[
Q^* = \sum_{i=1}^{K} P^*_{q,i} \frac{\hat{h}_{q,i}^H}{\| \hat{h}_{q,i} \|^2}, \quad S_k^* = \sum_{i=1}^{K} P^*_{s_k,i} \frac{\hat{h}_{s_k,i}^H}{\| \hat{h}_{s_k,i} \|^2}, \quad k = 1, 2, \ldots, K, \quad \text{(D.5)}
\]
which satisfy $\text{Rank} (Q^*) \leq 1$ and $\text{Rank} (S_k^*) \leq 1$, for all $k \in \{1, \ldots, K\}$.

With (D.5),
\[
X_q^* = \sum_{k=1}^{K} S_k^* + Q^* \quad \text{and} \quad X_{s_k}^* = \frac{1}{\gamma_k} S_k^* - \sum_{i \neq k} S_i^* - Q^*.
\]

Let the transmit power for the energy user be
\[
P_q^* = \sum_{i=1}^{K} P^*_{q,i,K+1} + P^*_{q,K+1}, \quad \text{(D.3)}
\]
and the transmit power for the information users be
\[
P_k^* = P^*_{s_k,k} - \sum_{i \neq k} P^*_{s_i,k} - P^*_{q,k}. \quad \text{(D.4)}
\]

Construct a sequence of new solutions as follows
\[
Q^* = \sum_{i=1}^{K} P^*_{q,i} \frac{\hat{h}_{q,i}^H}{\| \hat{h}_{q,i} \|^2}, \quad S_k^* = \sum_{i=1}^{K} P^*_{s_k,i} \frac{\hat{h}_{s_k,i}^H}{\| \hat{h}_{s_k,i} \|^2}, \quad k = 1, 2, \ldots, K, \quad \text{(D.5)}
\]
which satisfy $\text{Rank} (Q^*) \leq 1$ and $\text{Rank} (S_k^*) \leq 1$, for all $k \in \{1, \ldots, K\}$.

With (D.5),
\[
X_q^* = \sum_{k=1}^{K} S_k^* + Q^* \quad \text{and} \quad X_{s_k}^* = \frac{1}{\gamma_k} S_k^* - \sum_{i \neq k} S_i^* - Q^*.
\]

Let the transmit power for the energy user be
\[
P_q^* = \sum_{i=1}^{K} P^*_{q,i,K+1} + P^*_{q,K+1}, \quad \text{(D.3)}
\]
and the transmit power for the information users be
\[
P_k^* = P^*_{s_k,k} - \sum_{i \neq k} P^*_{s_i,k} - P^*_{q,k}. \quad \text{(D.4)}
\]

Construct a sequence of new solutions as follows
\[
Q^* = \sum_{i=1}^{K} P^*_{q,i} \frac{\hat{h}_{q,i}^H}{\| \hat{h}_{q,i} \|^2}, \quad S_k^* = \sum_{i=1}^{K} P^*_{s_k,i} \frac{\hat{h}_{s_k,i}^H}{\| \hat{h}_{s_k,i} \|^2}, \quad k = 1, 2, \ldots, K, \quad \text{(D.5)}
\]
which satisfy $\text{Rank} (Q^*) \leq 1$ and $\text{Rank} (S_k^*) \leq 1$, for all $k \in \{1, \ldots, K\}$.

With (D.5),
\[
X_q^* = \sum_{k=1}^{K} S_k^* + Q^* \quad \text{and} \quad X_{s_k}^* = \frac{1}{\gamma_k} S_k^* - \sum_{i \neq k} S_i^* - Q^*.
\]
Using Proposition 3, we know from (D.1c) that
\[
\mu_{s_k}^* \text{Tr} \left[ \hat{H}_k X_{s_k}^* (X_{s_k}^* + \mu_{s_k}^* I)^\dagger \right] - \sigma_k^2 - \mu_{s_k}^* \epsilon_k^2 \\
= \mu_{s_k}^* \| \hat{H}_k \|^2 \left( \frac{P_{s_k}^* \sum_{j \neq k} P_{s_j,k}^* - P_{q,k}^*}{\gamma_k} \right) /\gamma_k - \sigma_k^2 - \mu_{s_k}^* \epsilon_k^2 \\
\geq \mu_{s_k}^* \| \hat{H}_k \|^2 \left( \frac{P_{s_k}^*/\gamma_k - \sum_{j \neq k} P_{s_j,k}^* - P_{q,k}^*}{\gamma_k} \right) /\gamma_k - \sigma_k^2 - \mu_{s_k}^* \epsilon_k^2 \\
= \mu_{s_k}^* \text{Tr} \left[ \hat{H}_k X_{s_k}^* (X_{s_k}^* + \mu_{s_k}^* I)^\dagger \right] - \sigma_k^2 - \mu_{s_k}^* \epsilon_k^2 > 0, \quad \text{(D.10)}
\]
where \( \mu_{s_k}^* \text{Tr} \left[ \hat{H}_k X_{s_k}^* (X_{s_k}^* + \mu_{s_k}^* I)^\dagger \right] - \sigma_k^2 - \mu_{s_k}^* \epsilon_k^2 > 0 \) if
\[
\text{Rank} \left( Q^* \right) \geq 2 \quad \text{or} \quad \text{Rank} \left( S_k^* \right) \geq 2.
\]
Moreover, we obtain from (D.1d) that
\[
X_{s_k}^* + \mu_{s_k}^* I = - \sum_{i=1}^{k-1} P_i^* u_i u_i^H + P_{s_k}/\gamma_k u_k u_k^H \\
- \sum_{i=k+1}^K P_i^* u_i u_i^H - P_s^* u_k u_{K+1} u_{K+1}^H + \mu_{s_k}^* I \\
= U \Lambda_k^* U^H,
\]
where \( \Lambda_k^* \) can be expressed as
\[
\Lambda_k^* = \text{diag}(-P_{s_k}^*/\gamma_k + \mu_{s_k}^*, \ldots, -P_{s_{k-1}}^*/\gamma_k + \mu_{s_{k-1}}^*, P_{s_k}/\gamma_k + \mu_{s_k}^*, \ldots, -P_{s_1}^*/\gamma_k + \mu_{s_1}^*).
\]
We now consider the diagonal elements of \( \Lambda_k^* \) in the following four cases.

(a) For the \( k \)th element of \( \Lambda_k^* \), using (D.4) we have
\[
P_{s_k}/\gamma_k + \mu_{s_k}^* \geq P_{s_k}/\gamma_k - \sum_{j \neq k} P_{s_j,k} + P_{q,k}^* < 1, \quad \text{and} \quad \gamma_k > 1,
\]
then
\[
P_{s_k}/\gamma_k + \mu_{s_k}^* \geq P_{s_k}/\gamma_k - \sum_{j \neq k} P_{s_j,k} + P_{q,k}^* + \mu_{s_k}^* \geq 0.
\]
(b) For the \( j \)th element of \( \Lambda_k^* \) where \( j = 1, \ldots, k-1, k+1, \ldots, K \), using Proposition 3 and \( \gamma_k > 1 \),
\[
-P_{s_k}^* + \mu_{s_k}^* = -P_{s_{j,k}}^* + \sum_{i \neq j,k} P_{s_{i,j}}^* + P_{q,j}^* + \mu_{s_k}^* \\
= P_{s_{j,k}}^* - P_{s_{j,k}}^* + \sum_{i \neq j,k} P_{s_{i,j}}^* + P_{q,j}^* + \mu_{s_k}^* \\
\geq P_{s_{j,k}}^* - \sum_{i \neq j,k} P_{s_{i,j}}^* + P_{q,j}^* + \mu_{s_k}^* \\
\geq \frac{P_{s_{j,k}}^*}{\gamma_k} - \sum_{i \neq j,k} P_{s_{i,j}}^* + P_{q,j}^* + \mu_{s_k}^* \geq 0.
\]
(c) For the \( K+1 \)th element of \( \Lambda_k^* \), using the assumption that
\[
\min \{ \mu_{s_k}^* \} \geq \sum_{i=1}^K P_{s_i,k} + P_{q,K+1} \geq 0,
\]
we have \(-P_{q,K+1} + \mu_{s_k}^* \geq 0 \).
(d) For the \( l \)th element of \( \Lambda_k^* \) where \( l = K+2, \ldots, N \),
\[
\mu_{s_k}^* \geq 0.
\]
Consequently,
\[
X_{s_k}^* + \mu_{s_k}^* I \succeq 0. \quad \text{(D.11)}
\]
From (D.1e) and (D.1f),
\[
X_{s_k}^* = \sum_{k=1}^K S_k^* + Q^*, \quad X_{s_k}^* = \frac{1}{\gamma_k} S_k^* - \sum_{k \neq i} S_i^* - Q^*, \quad \mu_{q,k}^* \geq 0, \quad \mu_{s_k}^* \geq 0, \quad Q^* \geq 0, \quad S_k^* \geq 0,
\]
where \( k = 1, 2, \ldots, K \). Based on (D.8)–(D.13), we know that \( Q^* \) and \( S_k^* \) satisfy all the constraints of \( \text{P1–SDR} \) and provide a smaller trace than \( Q^* \) and \( S_k^* \). Thus, \( Q^* \) and \( S_k^* \) are better solutions, which contradicts the assumption that \( Q^* \) and \( S_k^* \) are the optimal solutions. Consequently, \( \text{Rank} (Q^*) \leq 2 \) and \( \text{Rank} (S_k^*) \leq 1 \), for all \( k \in \{ 1, \ldots, K \} \), which completes the proof.

**APPENDIX E**

**PROOF OF PROPOSITION 4**

The Lagrangian of \( \text{P2} \) is expressed as
\[
\mathcal{L} (\mu_q, \{ \mu_{s_k} \}, P_q, \{ P_k \}, \varpi, \{ \xi_k \}, \delta_q, \{ \theta_k \}, v_q, \{ v_k \}) = P_q + \sum_{k=1}^K P_k - \varpi \left( \frac{\mu_q P_q \| \hat{h}_k \|^2}{\mu_q + P_q} + \sigma_q^2 - Q/\zeta - \mu_q \epsilon_q^2 \right) - \sum_{k=1}^K \xi_k \left( \frac{\mu_q P_q \| \hat{h}_k \|^2}{\mu_q + P_q} - \sigma_k^2 - \mu_q \epsilon_k^2 \right) - \varpi P_q - \varpi q, \mu_{s_k}, v_q, v_k.
\]
where \( \varpi \geq 0 \) and \( \{ \xi_k \geq 0 \} \) are the dual variables associated with the constraints in (23b) and (23c), respectively. Moreover, \( \theta_q \geq 0, \{ \theta_k \geq 0 \} \), \( v_q \geq 0 \) and \( \{ v_k \geq 0 \} \) are the dual variables associated with the constraints in (23d). The KKT conditions related to \( \mu_q, \{ \mu_{s_k} \}, P_q \) and \( \{ P_k \} \) can be formulated as
\[
\frac{\partial \mathcal{L}}{\partial \mu_q} = \varpi^* c^2_q - \varpi^* P_q^2 \| \hat{h}_k \|^2 /\mu_q^2 + P_q^2 - \varpi q^* = 0, \quad \text{(E.1)}
\]
\[
\frac{\partial \mathcal{L}}{\partial \mu_{s_k}^*} = \xi_k^* c_k^2 - \xi_k^* P_k^2 \| \hat{h}_k \|^2 /\mu_k^2 + P_k^2 - \varpi q^* = 0, \quad \text{(E.2)}
\]
\[
\frac{\partial \mathcal{L}}{\partial P_q} = 1 - \varpi^* c^2_q - \varpi P_q^2 \| \hat{h}_k \|^2 /\mu_q^2 + P_q^2 - \varpi q^* = 0, \quad \text{(E.3)}
\]
\[
\frac{\partial \mathcal{L}}{\partial P_k} = 1 - \xi_k^* c_k^2 - \xi_k^* P_k^2 \| \hat{h}_k \|^2 /\mu_k^2 + P_k^2 - \varpi q^* = 0, \quad \text{(E.4)}
\]
\[
\varpi^* \left( \frac{\mu_q P_q \| \hat{h}_k \|^2}{\mu_q + P_q} + \sigma_q^2 - Q/\zeta - \mu_q \epsilon_q^2 \right) = 0, \quad \text{(E.5)}
\]
\[
\xi_k \left( \frac{\mu_q P_q \| \hat{h}_k \|^2}{\mu_q + P_q} - \sigma_k^2 - \mu_q \epsilon_k^2 \right) = 0, \quad \text{(E.6)}
\]
where \( 1 \leq k \leq K, \mu_q^*, \{ \mu_{s_k}^* \}, P_q^*, \{ P_k^* \} \) are the optimal primal variables, while \( \varpi^* \geq 0, \{ \xi_k^* \geq 0 \}, \varpi q^* \geq 0, \{ \theta_k \geq 0 \}, v_q^* = 0, \{ v_k^* = 0 \} \) are the optimal dual variables.
From (E.3) and (E.4), there must be $\sigma^q > 0$ and $\{\xi_k^q > 0\}$.

From (E.5) and (E.6),

$$\frac{\mu^q_k P^*_k \|h_k\|^2}{\mu^q_k \sigma_q^2} + \sigma^q - \frac{Q}{\xi^q} - \mu^q_k \sigma^q_q = 0,$$

(E.8)

$$\frac{\mu^q_k P^*_k \|h_k\|^2}{\mu^q_k \gamma_k + P^*_k} - \sigma^q - \mu^q_k \sigma^q_k = 0, \quad 1 \leq k \leq K.$$  

(E.9)

Moreover, it is easily derived from (E.1) and (E.2) that

$$\mu^q_k = \frac{P^*_k \|h_k\|^2}{\|P^*_k \|h_k\|-\sigma^q_k}.$$  

(E.10)

Substituting (E.10) into (E.8) and (E.9), respectively, we obtain

$$P^*_k = \frac{Q/\xi^q - \sigma^q_k}{\|h_k\|^2 - \sigma^q_k} \|h_k\|^2,$$

(E.11)

Plugging $P^*_k$ into $\mu^q_k$, we have

$$\mu^q_k = \left(\frac{\sigma^q_k}{\|h_k\| - \sigma^q_k}\right)^2.$$  

As a result, the optimal condition (24) can be expressed as

$$\min \left\{ \frac{\sigma^q_k^2}{\|h_k\|^2 - \sigma^q_k}\right\} \geq \frac{Q/\xi^q - \sigma^q_k}{\|h_k\|^2 - \sigma^q_k},$$  

(E.12)

which completes the proof of Proposition 4.

REFERENCES


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