

Early detection of drought-stressed stands in Mediterranean forests using remote sensing and machine learning classification models in a rainfall exclusion experiment

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ARTICLE INFO

Keywords:

Drought-risk
Forest decline
Remote sensing
Support vector machine
Rain exclusion
VEN μ S

ABSTRACT

Climate change-driven droughts increasingly threaten Mediterranean forests. Early detection is crucial for mitigating long-term impacts; yet, conventional methods are limited in spatial and temporal coverage. Remote sensing offers a large-scale solution, but its application at the individual-tree level remains limited, particularly in mixed-species forests.

We combined a controlled rainfall exclusion experiment with drone-based hyperspectral imaging and machine learning to classify drought stress at the individual-tree level in a semi-arid Mediterranean forest (Yishi Forest, Israel). Six 0.05-ha plots with five co-occurring tree species were monitored over two hydrological years. Hyperspectral data (274 bands, 400–1000 nm) were used as is and after synthetically simulating Planet, VEN μ S, and Sentinel-2 bands in three machine learning classification models.

Results show that rainfall was reduced by nearly half in treated plots. Standard physiological metrics—leaf water potential, carbon assimilation, and transpiration—showed limited treatment sensitivity across most species and seasons, whereas hyperspectral-driven machine learning classification models accurately distinguished between drought-treated and control stands. Logistic Regression (LR) outperformed Support Vector Machines (SVM) and Random Forest (RF), reaching an accuracy of 0.85, a recall of 0.94, and an F1 score of 0.83 in classifying treated stands on a held-out test set. High performance persisted after reducing input to 21 bands. Simulated satellite spectral data showed that SVM performed best using VEN μ S bands (accuracy = 0.74, F1 = 0.73). When applied to real VEN μ S imagery from three independent forest sites, the model identified areas of high drought risk one to two years before visible canopy decline.

The presented approach offers a scalable and transferable tool for real-time forest drought monitoring, supporting early warning systems amid growing climate pressures.

1. Introduction

Climate variability profoundly impacts forest ecosystems worldwide, with increasing frequency and severity of drought events posing a significant threat to forest health and productivity (Allen et al., 2010). Rising temperatures, associated with increased atmospheric CO₂, elevate evaporative demand and accelerate soil drying, potentially outweighing any benefits of improved water-use efficiency (Sanginés de Cárcer et al., 2018; Yuan et al., 2019). Moreover, high temperatures

disrupt stomatal regulation, causing rapid depletion of soil water reserves. This pushes trees closer to their physiological limits—a trend expected to intensify with continued global warming (Brodribb et al., 2020; Drake et al., 2018; IPCC, 2023; Urban et al., 2017; Zheng et al., 2022).

This is particularly critical in Mediterranean forests, characterized by dry summers and rainy winters, which are particularly vulnerable to these changes and are expected to face more intense and prolonged dry periods (Cramer et al., 2018). The increased frequency and severity of

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<https://doi.org/10.1016/j.agrformet.2025.110855>

Received 18 May 2025; Received in revised form 4 September 2025; Accepted 15 September 2025

Available online 22 September 2025

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droughts in these regions can decrease forest productivity and biodiversity (Essa et al., 2023; Klein et al., 2019). In addition, some tree species may be at risk of hydraulic collapse in mixed Mediterranean forests during severe droughts, underscoring the critical importance of early detection methods to identify vulnerable stands and initiate timely interventions (Italiano et al., 2024). Accordingly, detecting and monitoring drought stress in forests is crucial for understanding ecosystem responses to climate change and developing effective management strategies (Hartmann et al., 2018).

Remote sensing involves measuring electromagnetic radiation reflected or emitted from objects at various wavelengths. This technique has become invaluable for monitoring forest health and detecting environmental stresses over extensive spatial scales with high temporal resolution (Helman et al., 2019a). By enabling non-invasive assessments, these techniques allow the evaluation of vegetation properties that indicate plant physiological status and stress responses (Helman et al., 2022, 2019b; Mulero et al., 2023; Zarco-Tejada et al., 2021). Several recent studies have demonstrated the application of remote sensing for drought detection in forests, leveraging various spectral bands and vegetation indices.

For example, Asner et al. (2016) demonstrated the utility of airborne imaging spectroscopy for mapping canopy water content and detecting drought-induced tree mortality in California forests (Asner et al., 2016). Zarco-Tejada et al. (2018) used narrow-band hyperspectral indices to detect early signs of water stress in olive orchards, while Hernández-Clemente et al. (2014) combined visible, near-infrared, and thermal data to assess drought-induced physiological changes in Mediterranean oak forests. Anderson et al. (2010) used MODIS data to evaluate the 2005 Amazonian drought, revealing relationships between vegetation indices and tree mortality rates. Zhang et al. (2017) compared various remote sensing-based drought indices across the Continental United States, noting the effectiveness of vegetation-based indices like VCI for short-term drought conditions. Przędziecki et al. (2023) addressed the challenges of applying drought indices in forests by developing a novel approach to calculate the Temperature Vegetation Dryness Index (TVDI) based on temporal changes in soil moisture rather than spatial heterogeneity. In a study on Mediterranean hardwood forests, Italiano et al. (2023) combined remote sensing indices with tree-ring analysis and wood anatomy, revealing variability in species-specific drought responses and identifying links between canopy cover, hydraulic conductivity, and growth patterns in drought-affected sites.

Parallel to these developments, recent advancements in machine learning algorithms have greatly enhanced the capacity to extract meaningful information from complex remote sensing datasets (Lary et al., 2016; Li et al., 2023). Several studies have demonstrated the effectiveness of various algorithms in identifying drought-affected areas and assessing forest vulnerability. Olano et al. (2021) used Support Vector Machines (SVM) to detect frost defoliation events in European beech forests, while Mohammed et al. (2022) compared multiple algorithms for drought prediction in the eastern Mediterranean. Cui et al. (2022) employed Long Short-Term Memory models to project evapotranspiration and assess water stress vulnerability in Mediterranean-climate forests. Buthlezi et al. (2022) evaluated several machine-learning techniques for classifying drought-damaged trees using Landsat-derived vegetation indices in subtropical regions. Additionally, machine learning approaches such as random forests (RF), SVM, and artificial neural networks (ANN) have been successfully used to estimate various water-related plant parameters, including leaf water content, leaf water potential, and equivalent water thickness, from both hyperspectral and multispectral remote sensing data (Fishman et al., 2025; Li et al., 2023; Sadiq et al., 2023; Virnodkar et al., 2020).

However, despite these advances, most remote sensing applications in forest drought monitoring still rely heavily on retrospective analyses of naturally occurring events. A critical gap remains in accurately classifying drought-stressed stands under controlled experimental conditions. Specifically, no study has yet combined high-resolution

hyperspectral drone imagery with machine learning algorithms to classify experimentally induced drought stress at the individual tree level in a forest ecosystem. This approach is particularly important for monitoring stands in Mediterranean forests, where the complex composition of multiple tree species and their varied drought sensitivity complicate monitoring efforts (Cramer et al., 2018; Klein et al., 2019).

To address this gap, we combine hyperspectral drone imagery with machine learning algorithms to classify drought stress in a mixed Mediterranean forest under a unique natural controlled rainfall reduction experiment. We compare three machine learning classification algorithms, accounting for heterogeneous responses of co-occurring species, and integrate high-resolution spectral data with physiological measurements across five tree species to develop drought classification models at the individual tree level. Furthermore, we train new models based on synthetic data from drone-based hyperspectral images based on Sentinel-2, VENUS, and Planet satellite bands, expanding the applicability of our approach to operational satellite systems.

2. Data

2.1. Study site and experimental design

The research was conducted in Yishi Forest, a semi-arid mixed Mediterranean woodland in Israel's Judean foothills (31° 43' N 34° 57' E; Fig. 1). This forest covers approximately 650 hectares and is located 4 km southwest of Beit Shemesh at an average elevation of 300 m above sea level (Lapidot et al., 2019; Rog et al., 2024). The climate is characterized by a mean annual precipitation of 460 mm, primarily occurring between November and May, based on data from the past two decades. Temperature records from the Israel Meteorological Service indicate a mean annual temperature of 20.4 ± 6.8 °C, with winter (January-March) and summer (June-August) averages of 16.5 ± 1.9 °C and 24.1 ± 7.9 °C, respectively (Israel Meteorological Service). The predominant soil type in Yishi is terra rossa, comprising A and C horizons. The C horizon soil infiltrates fissures within the weathered limestone bedrock. The A horizon depth averages 21 cm, ranging from 16 to 25 cm (Rog et al., 2021).

The vegetation in Yishi Forest includes both planted and native Mediterranean woody species. The planted gymnosperms are *Pinus halepensis* (Pine) and *Cupressus sempervirens* (Cypress), while the indigenous angiosperms include *Quercus calliprinos* (Oak), *Ceratonia siliqua* (Carob), and *Pistacia lentiscus* (Pistacia). These species have been previously investigated in situ for their water relations and carbon management strategies (Rog et al., 2024, 2021). The forest understory supports a diverse community of annual plants, which flourish during the winter-spring period.

The rainfall exclusion experiment started in November 2021 and was conducted in six 0.05-hectare plots within the forest, each containing the five co-occurring woody species (Fig. 1b,c). Three plots were subjected to rainfall reduction, while three served as controls. The drought simulation employed an open-pipe harvesting system with gutters (Fig. 1d,e) to divert approximately 50 % of incident precipitation from treated plots. Soil moisture sensors (EC-5; Meter; Pullman, WA, USA) monitored treatment efficacy, aiming to reduce soil moisture content by 50 % compared to control plots. Sensors determined volumetric water content by measuring the dielectric constant of the media using capacitance/frequency domain technology. Five sensors were installed in each stand, in locations under tree canopies and between trees, in undisturbed soil volumes at depths of 15–20 cm below the surface. In each stand, the five sensors were connected to a datalogger (ZL6; Meter; Pullman, WA, USA), which recorded measurements at an hourly resolution and was downloaded during field measurement days.

2.2. Field measurements

To monitor trees' physiological response to rainfall reduction, three

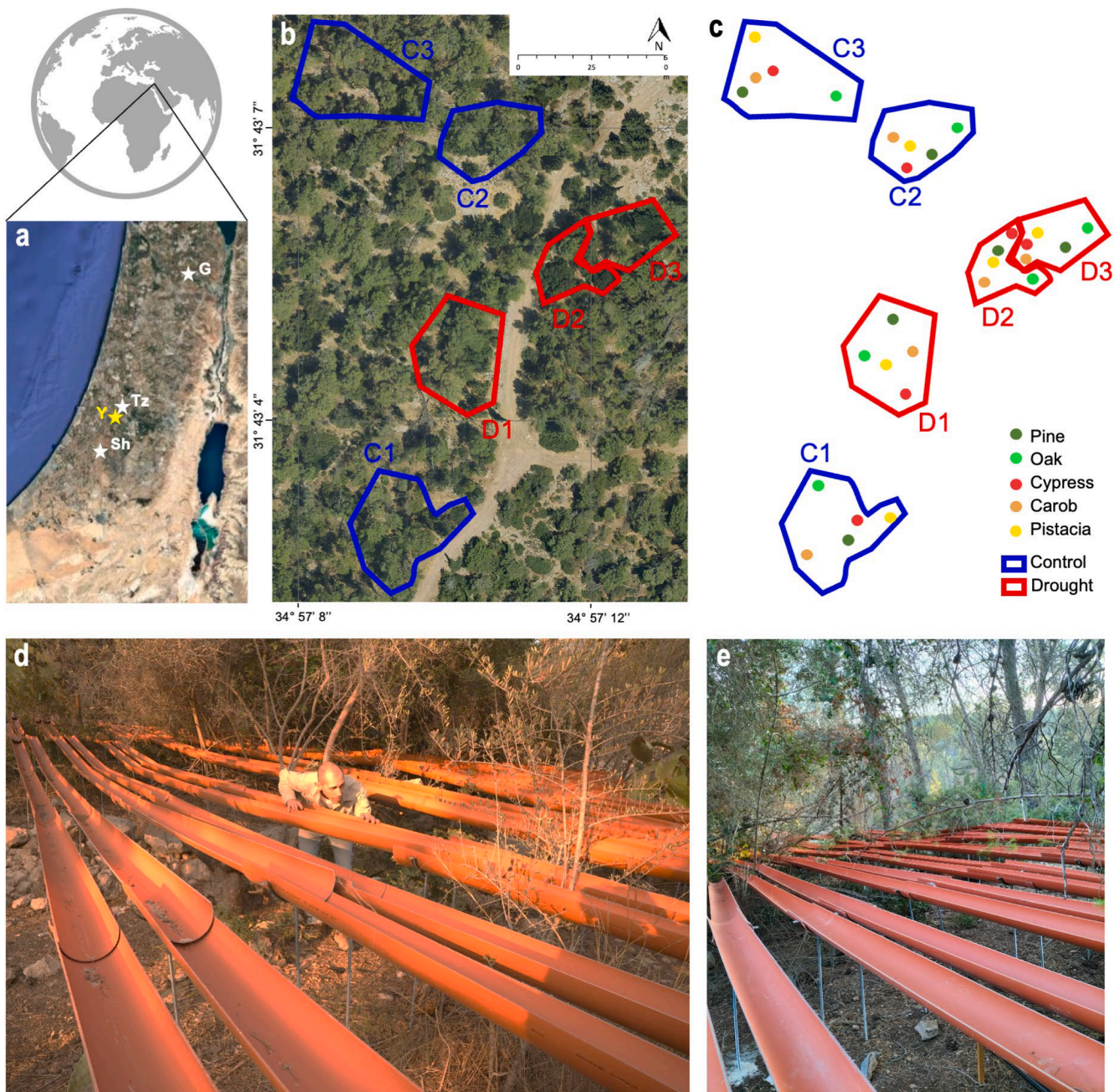


Fig. 1. The study area showing (a) the experimental site of Yishi forest (Y; yellow star) and the three forest sites of Tzora (Tz), Shacharia (Sh), and Gilboa (G). (b) Aerial view of the 0.05-hectare plots at Yishi, with control plots in blue (C1-C3) and rainfall exclusion plots in red (D1-D3). (c) Same as (b) but with the species marked on the map. (d-e) The rainfall exclusion system in Yishi consisting of open-pipe gutters installed to divert approximately 50 % of incident precipitation.

key parameters were assessed: leaf water potential (ψ_{leaf}), assimilation rate (A_n), and transpiration rate (T_r). These measurements provided insights into the trees' water relations status and photosynthetic activity under varying rainfall conditions (Blackman et al., 2009; Flexas et al., 2004).

ψ_{leaf} was measured using the pressure chamber method (Boyer, 1967). This technique involves sealing a leaf petiole within a chamber and incrementally raising the internal pressure until sap emerges from the cut end of the petiole. The pressure at this point equals the negative of the ψ_{leaf} , which directly measures the leaf's hydration status (Ritchie and Hinckley, 1975).

ψ_{leaf} measurements were conducted monthly from October 2021 to March 2023. Sampling was conducted between 11 AM and 1 PM to capture peak daily ψ_{leaf} values, with the specific time adjusted season-

ally. We focused on midday ψ_{leaf} measurements, as they better reflect tree water stress under peak evaporative demand, and are less susceptible to nocturnal disequilibrium that can affect predawn values in dry environments.

In each plot, one leaf per species was sampled to ensure consistent conditions across species. To minimize measurement errors due to time lags, excised leaves were immediately sealed in airtight plastic bags and kept cool. For analysis, ~30 leaves were sampled per measurement date using a PMS1515 pressure chamber (PMS, Albany, OR, USA). In total, 480 leaf samples were collected over the study period.

In addition to ψ_{leaf} , gas exchange parameters were measured to assess the trees' physiological responses to the rainfall reduction treatment. A_n and T_r were measured monthly from October 2021 to March 2023 on clear sky days using a portable infrared gas analyzer system

(IRGA; GFS-3000, Walz). Measurements were conducted on mature leaves concurrently with ψ_{leaf} assessments, allowing for non-destructive, in situ evaluation of gas exchange dynamics.

The GFS-3000 was configured with the following settings: standard leaf chamber (Walz 3010-S), an ambient CO₂ concentration of 400 ppm, a flow rate of 750 $\mu\text{mol s}^{-1}$, and an impeller speed of 7 steps. The temperature was set to ambient with a 1 °C offset. The projected leaf area relative to the chamber size was calculated and adjusted for each tree species to ensure accurate measurements.

A_n , representing CO₂ uptake by the leaves, was measured in $\mu\text{mol CO}_2 \text{ m}^{-2} \text{ s}^{-1}$. T_r , indicating leaf transpiration, was recorded in $\text{mmol H}_2\text{O m}^{-2} \text{ s}^{-1}$. These measurements provided insights into plant gas exchange dynamics under varying environmental conditions and treatments.

2.3. Hyperspectral data acquisition and preprocessing

Hyperspectral imagery was collected using a Nano-Hyperspec camera (Headwall Photonics) mounted on a DJI Matrice 600 Pro (M600) Hexacopter. The M600, equipped with a Global Navigation Satellite System (GNSS) GPS and an Inertial Measurement Unit (IMU), was operated via a remote-control transmitter and a ground control station. The NanoSpec sensor, a push-broom hyperspectral device, captured 274 spectral bands across 640 spatial pixels within the 400–1000 nm range.

Image acquisition coincided with leaf measurements between 11:00 AM and 1:00 PM. The drone flew 60 m above ground level, yielding a spatial resolution of 2–3 cm per pixel. Three flights were required to cover the entire study area. Radiometric calibration employed an in-situ 3 × 3 m grey-white reflectance panel with three distinct reflectance factors (56 %, 30 %, and 11 %). Geometric corrections were based on a ground GNSS receiver (Trimble SPS585 precision RTK) to collect static geolocation data, enabling post-processing kinematic (PPK) flight trajectory calculations.

Raw hyperspectral image cubes underwent radiometric calibration, geometric corrections, and ortho-mosaicking using SpectralView software (version 3.1.4, Headwall Photonics). A two-stage masking process removed non-representative pixels (Fig. 2). First, pixels with a Normalized Difference Vegetation Index (NDVI; Rouse, 1973) value lower than 0.3 were excluded to eliminate soil and understory vegetation (Fig. 1a). Second, shaded canopy portions were masked using a near-infrared reflectance threshold below 0.07–0.2 (Fig. 1b). These NDVI and near infrared (NIR) thresholds were determined through iterative visual inspection to optimize removing extraneous elements while retaining vegetation pixels (Fig. 1c). The masking process was done using the Quantum GIS free software (version- 3.32.3).

For each tree, the reflectance values of the remaining pixels were averaged to obtain a single mean reflectance spectrum representative of the entire canopy. To mitigate potential artifacts and anomalies in the spectral signatures, a Savitzky-Golay filter (Savitzky and Golay, 1964) was applied, using a window size of 20 bands and second-order

polynomials.

The sampling strategy yielded 25–30 spectral samples per species for each treatment, with one exception. Due to its understory growth habit, *Pistacia* yielded only four spectral samples from drought-treated plots compared to 22 from control plots. In total, the study comprised 246 samples, consisting of 125 from control plots and 121 from the rainfall reduction treatments.

2.4. Synthetic and actual satellite data

To enhance the approach's applicability, we used the bands of three high-resolution satellites: Sentinel-2, VEN μ S, and Planet. We synthetically produced the satellite-equivalent bands from the drone's hyperspectral images, which fall within the same 400–1000 nm range as our Headwall Photonics' hyperspectral camera (Table 1).

Synthetic bands were created for each satellite by averaging the hyperspectral data over the wavelengths corresponding to each satellite band to train and evaluate the models. We further used the model with actual satellite data (for the optimal satellite/model combination) at three additional Mediterranean forest sites along the rainfall gradient in Israel (see Section 3.3 below), providing insights into the model's ability to detect early drought-stressed stands using real satellite data.

Following the results of the synthetic model evaluation, we obtained actual satellite imagery of the best satellite platform for the three case study sites (Tzora Forest (Tz), Shacharia Forest (Sh), and Gilboa Forest (G) shown in Fig. 1a). Data was downloaded from the Israel VEN μ S data portal, maintained by Ben-Gurion University of the Negev (<https://venus.bgu.ac.il/venus/>) for: Tz site, dates 11/9/18, 19/9/19, 19/9/20, site G –1/12/17, 1/9/2018, 4/9/20, and site Sh –1/9/18, 2/9/19, 4/9/20. Images were obtained from identical months across multiple years to control for phenological and seasonal variability, spanning three key temporal phases: pre-drought conditions, drought year, and post-drought management intervention periods as documented by JNF (see Section 3.3 and Fig. S1). Level-2 products were downloaded, providing surface reflectance after atmospheric correction for single-day acquisitions at a spatial resolution of 5 m. The data were provided in ready-to-use GeoTIFF format, and no additional preprocessing was required prior to analysis.

3. Methods

3.1. Machine learning classification models

We tested three machine learning classification algorithms to build a model that distinguishes drought from control stands using only hyperspectral data: Logistic Regression (LR), Support Vector Machine (SVM), and Random Forest (RF). LR estimates the probability of an outcome using a linear model based on input variables (Cox, 1958), SVM identifies the hyperplane that best separates classes in a

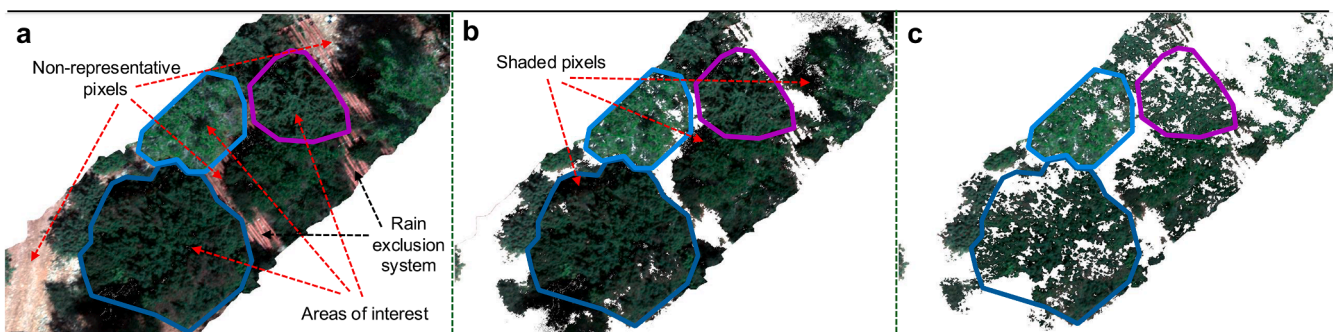


Fig. 2. Hyperspectral image preprocessing workflow for isolating tree canopy pixels, showing (a) original image of experimental plots with outlined areas of interest (canopy), non-representative pixels, and visible components of the rainfall exclusion system (black arrows). At first, (b) non-vegetated pixels are removed using an NDVI threshold of <0.3 . (c) Then, to remove the shaded canopy portions, the near-infrared reflectance threshold of $0.07\text{--}0.2$ was used.

Table 1

Specifications of sensors used in this study: UAV, Sentinel-2, VEN μ S, and Planet. The temporal and spatial resolutions, along with the specific spectral bands and their corresponding wavelength ranges, are presented. Only the relevant bands to this research are included.

Sensor	Temporal Resolution	Spatial Resolution	Bands	Wavelength Range (nm)
Matrice 600 Pro Hexacopter (UAV)	~1 Month	2–3cm	274 bands (~2 nm bandwidth)	400–1000
			274 bands (~2 nm bandwidth)	400–1000
Sentinel-2 (satellite)	5 Days	10m	B2 (Coastal Aerosol)	443–490
			B2 (Blue)	490–560
			B3 (Green)	560–665
			B4 (Red)	665–705
			B5 (Vegetation Red Edge)	705–740
			B6 (Vegetation Red Edge)	740–783
		20m	B7 (Vegetation Red Edge)	783–842
			B8 (NIR)	842–865
			B8A (Narrow NIR)	865–945
			B9 (Water vapor)	945–1375
			B2	400–440
			B3	423–463
VEN μ S (satellite)	2 Days	5m	B4	470–510
			B5	535–575
			B6	600–640
			B7	652–682
			B8	690–714
			B9	734–750
			B10	774–790
			B11	845–885
			B12	900–920
			Coastal Blue	433–453
			Blue	465–515
			Green I	513–549
Green	547–583			
Yellow	600–620			
Red	649–680			
Red-Edge	697–712			
NIR	845–885			
PlanetScope (satellite)	1 Day	3 m	Coastal Blue	433–453
			Blue	465–515
			Green I	513–549
			Green	547–583
			Yellow	600–620
			Red	649–680
			Red-Edge	697–712
			NIR	845–885

high-dimensional space (Cortes and Vapnik, 1995), and RF constructs multiple decision trees and assigns the class that is the mode of the classes predicted by these trees (Breiman, 2001).

Input features comprised average canopy reflectance values across 274 hyperspectral bands, for the hyperspectral data models, and fewer bands, for the satellite synthetic data model (see Table 1). The predicted variable consisted of 246 samples, comprising 125 controls and 121 drought samples, which were randomly partitioned into a training set (70 %, $N = 172$) and a held-out test set (30 %, $N = 74$), with reproducibility ensured through a fixed random state.

3.1.1. Hyperparameter selection

Model hyperparameters were systematically optimized to enhance performance and mitigate overfitting, using a randomized search strategy coupled with cross-validation restricted to the training dataset.

For LR, optimization employed a 3-fold cross-validation scheme across 50 iterations, with accuracy as the optimization metric. The hyperparameter space included penalty type, inverse regularization strength, solver algorithm, convergence tolerance, intercept inclusion, and intercept scaling factor (applicable only with specific solver and intercept configurations), as well as maximum iterations ranging from 100 to 500.

For SVM, accuracy optimization used a 3-fold cross-validation across 50 iterations. The hyperparameter space encompassed the following

options: kernel type (linear, polynomial, radial basis function, and sigmoid), shrinking heuristic utilization, regularization parameter, kernel coefficients relevant for polynomial and sigmoid kernels, polynomial degree for polynomial kernels, and convergence tolerance.

For RF, hyperparameter optimization employed a 3-fold cross-validation scheme across 50 iterations, with accuracy as the optimization metric. Optimized parameters included the number of trees ranging from 200 to 2000, a split quality criterion based on either Gini impurity or entropy, maximum tree depth, minimum samples required for node splitting, minimum samples required per leaf node, and the number of features considered for optimal splitting. The search used all available processor cores.

3.1.2. Feature selection

We implemented a multi-step approach to address potential overfitting due to the high dimensionality of the data for models using all 274 spectral bands (for only 246 samples), as described below. Models using the satellite synthetic data did not require dimensionality reduction.

To facilitate this dimensionality reduction, feature importance was quantified for each model trained on the training set ($N = 172$). The method for calculating importance varied by algorithm:

For the LR model, importance was calculated as the absolute value of the fitted coefficients, normalized to represent the percentage contribution of each spectral band. For the RF model, the intrinsic mean decrease in impurity, also known as Gini importance, was calculated during training and normalized to percentages. For the SVM, which used the optimized kernel and required probability estimates, feature importance was estimated using Permutation Importance. This involved measuring the mean decrease in model accuracy on the training data when the values of individual features were randomly permuted across 10 repeats. The resulting mean importance scores were normalized to percentages.

Feature selection was then performed for each model. Features accounting for 80 % of the cumulative importance were retained. If the number of selected features exceeded 25 bands (10 % of the sample size), an additional filter was applied to retain only the most significant band within each 10 nm range. Following feature selection, models were retrained using this reduced feature set, with random hyperparameter search and k-fold cross-validation applied again.

Final evaluations of these refined models were conducted on the test set using the metrics above to assess their generalizability to unseen data. The final evaluation of these refined models was conducted on the held-out test set using standard classification metrics: Accuracy, Recall, Precision, and F1 Score, defined in Section 3.2. In addition to these metrics, the distribution of predicted probabilities for the 'drought' class, generated using probability estimation on the test set, was examined for each model. Histograms comparing the distributions for control versus drought actual samples were plotted to assess class separability and analyze misclassification patterns.

Fig. 3 summarizes the entire modeling scheme.

3.2. Statistical analyses

Statistical analyses were performed to examine the effects of the drought treatment on tree physiology. For each measured parameter, t -tests were conducted on control and drought-treated plots within each season (summer: June–August, autumn: September–November, winter: December–February, spring: March–May) to quantify treatment effects on tree physiological responses across seasonally varying conditions. ψ_{leaf} , A_n , and T_r measurements were tested for normality at $p > 0.05$ sample with the Shapiro–Wilk test using the JMP 17 Pro statistical software (SAS Institute) before applying the t -test. All tests for statistical significance of model performance were performed within the Python pipeline at $p < 0.05$. All ML models were implemented using the scikit-learn library (Version 1.6.1; Pedregosa et al., 2011) within a Python

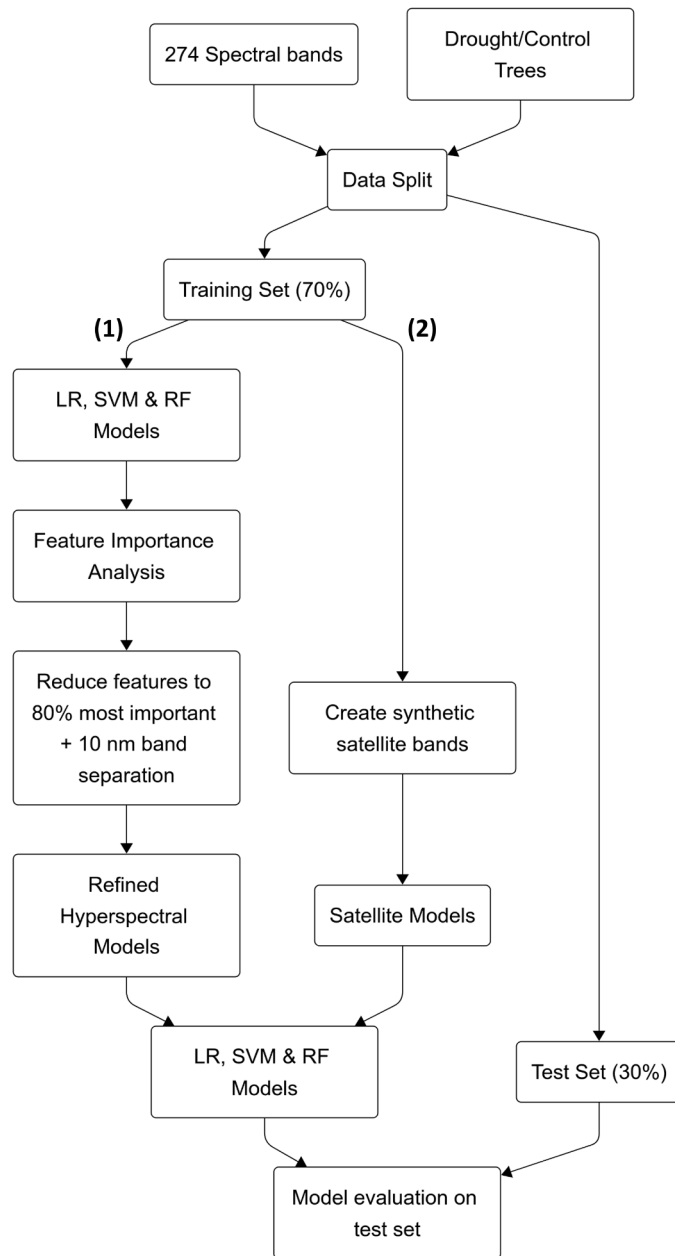


Fig. 3. Workflow of the modeling framework, illustrating the use of inputs comprising 274 spectral bands from hyperspectral imagery and labeled drought/control trees, which were partitioned into training (70 %) and test (30 %) sets. The training data follows two parallel processing paths: (1) the hyperspectral pathway (left) where machine learning models are trained, followed by feature importance analysis and dimensionality reduction to retain bands representing 80 % cumulative importance with 10 nm separation, resulting in refined hyperspectral models; and (2) the satellite simulation pathway (right) where synthetic satellite bands are created to train satellite-compatible models. Both refined hyperspectral and satellite models are evaluated using the same held-out test set to assess classification performance for drought stress detection.

(Version 3.11.12) environment.

Model performance was assessed using Accuracy, Recall, Precision, and F1 Score metrics. These metrics are calculated as follows:

$$\text{Accuracy} = \frac{TP + TN}{TP + TN + FP + FN} \quad (1)$$

$$\text{Recall} = \frac{TP}{TP + FN} \quad (2)$$

$$\text{Precision} = \frac{TP}{TP + FP} \quad (3)$$

$$\text{F1 Score} = 2 \times \frac{\text{Precision} \times \text{Recall}}{\text{Precision} + \text{Recall}} \quad (4)$$

where TP denotes True Positives, TN denotes True Negatives, FP denotes False Positives, and FN denotes False Negatives. Accuracy measures the proportion of correct predictions (both true positives and true negatives) among the total number of cases examined. Recall, also known as sensitivity, quantifies the proportion of actual positive cases that were correctly identified. In our context, it represents the model's ability to identify trees under drought stress correctly. Precision measures the proportion of positive predicted positive cases, highlighting the model's ability to accurately identify drought-stressed trees. The F1 Score is the harmonic mean of precision and recall, providing a single score that balances both metrics.

3.3. Case studies for model evaluation with actual satellite data

To validate the efficacy of our best-performing model beyond experimental conditions, we conducted an independent assessment across three geographically distinct Mediterranean forests in Israel: Tzora Forest (Tz), Shacharia Forest (Sh), and Gilboa Forest (G) (Fig. 1a). This approach enabled evaluation of the model's transferability to actual satellite imagery for detecting naturally occurring drought stress across diverse environmental gradients. The evaluation sites represent a range of varied microclimatic conditions within Israel's Mediterranean forest ecosystem. The Tz site has a mean annual temperature of 20.5 ± 6.8 °C and a relative humidity of 60.6 ± 21.9 %. The Sh site has a mean annual temperature of 20.7 ± 7.1 °C and a relative humidity of 67.0 ± 21.0 %. G site has a mean annual temperature of 19.1 ± 7.0 °C and a relative humidity of 66.5 ± 23.9 %.

To quantify drought occurrence at each site, we analyzed annual precipitation data from the nearest Israel Meteorological Service (IMS) stations, at distances of 5.8 km, 4.8 km, and 7.5 km from Tzora, Shacharia, and Gilboa forests, respectively. 2017 saw a severe drought in all three sites (Fig. S1). Thus, we selected this year for our model evaluation and searched for signs of forest decline in subsequent years, looking for overlapping areas marked as stressed according to the model.

Following the comparative analysis of hyperspectral-derived synthetic satellite bands, we used the satellite platform that yielded the highest classification accuracy in our experimental setup to produce drought risk maps for the three sites (Tz, Sh, and G). The optimal classification model, as determined from our experimental site analysis, was applied directly to the raw satellite imagery. The model generated pixel-level drought probability scores ranging from 0 (low drought probability) to 1 (high drought probability) across the site.

4. Results

4.1. Field observations

The soil water content was consistently lower at the rain-exclusion plots during the entire period (Fig. 4). The average reduction was 47.2 %.

However, it seems that such a reduction did not affect the ψ_{leaf} in most stands (Fig. 5), except the oak that exhibited more negative values during summer and autumn (Fig. 5c) and the pine that showed lower values during the spring (Fig. 5d). The *t*-tests verified that the reduction of almost half the incoming water did not affect ψ_{leaf} , A_n and T_r for most of the season and most species (Table 2).

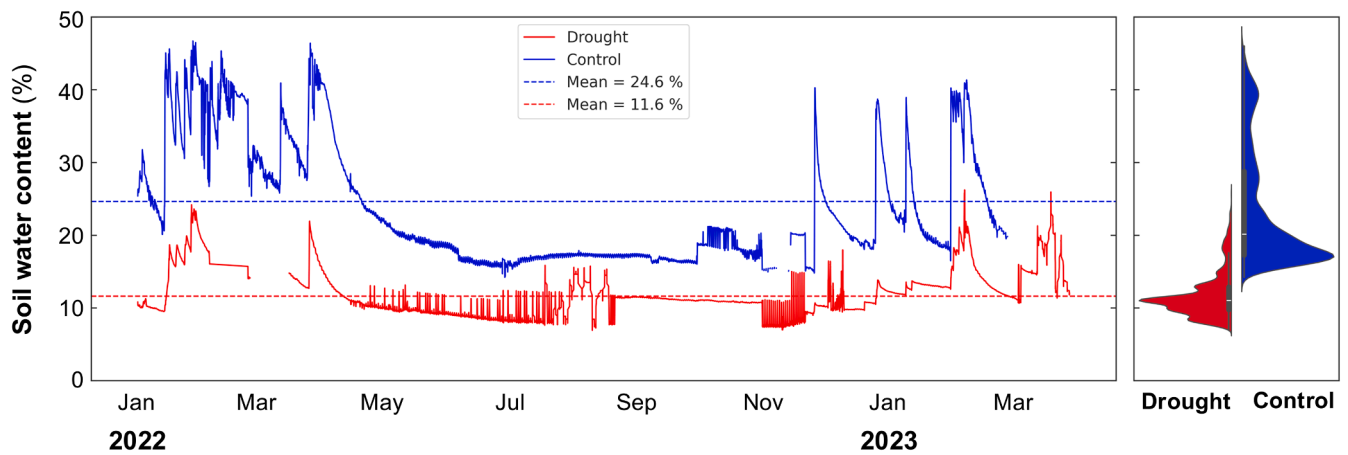


Fig. 4. Soil water content (SWC; %) dynamics in control and rainfall exclusion plots over the experimental period. The blue line represents the averaged SWC in control plots, and the red one represents the SWC in rainfall exclusion plots from January 2022 to March 2023. Horizontal dashed lines indicate the mean values across the entire period. The violin plot on the right displays the full distribution of soil moisture measurements for each treatment. Data were smoothed using a Savitzky-Golay filter with a window length of 21 and a polynomial order of 3 to improve the visualization of temporal trends.

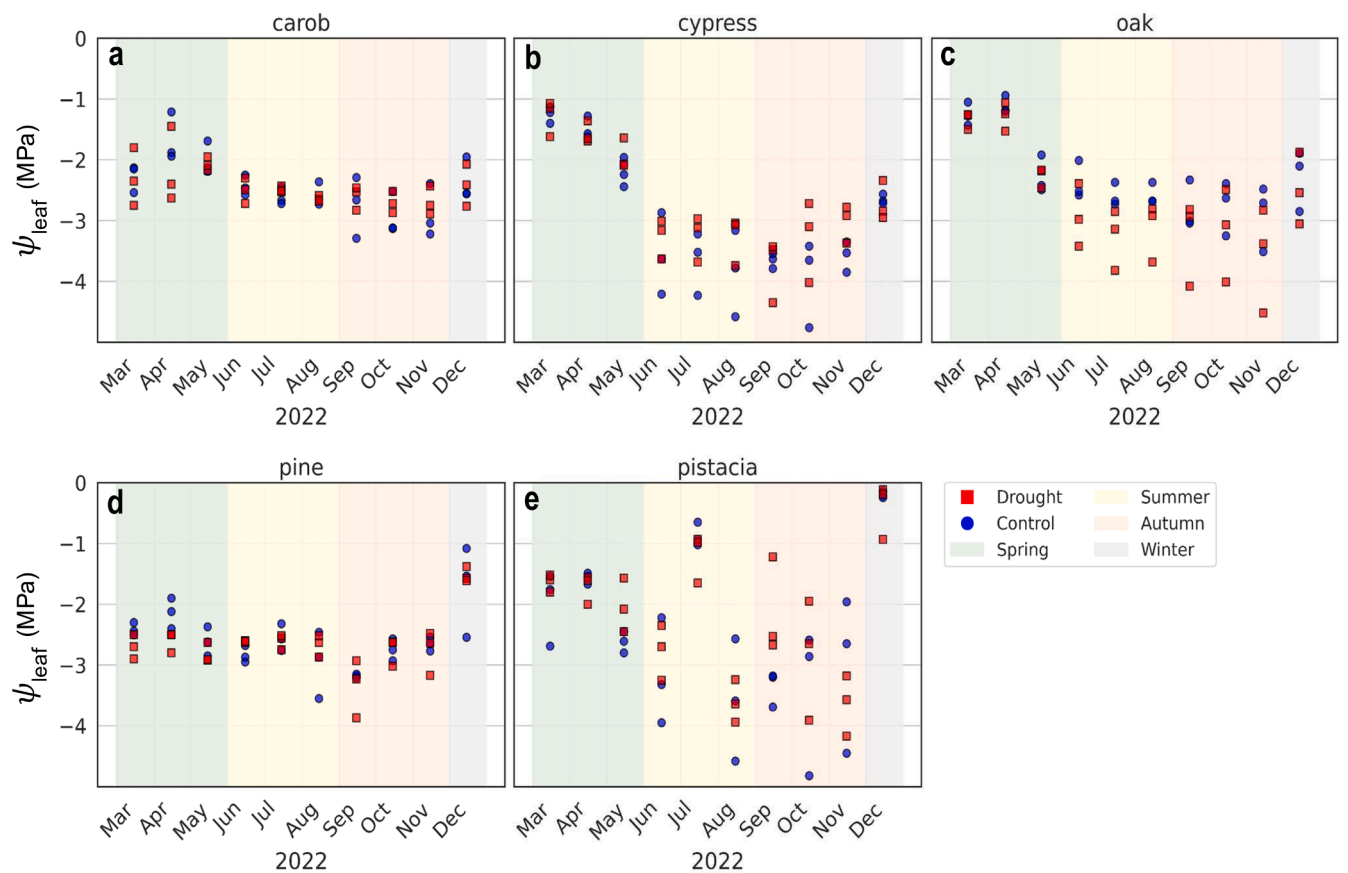


Fig. 5. Leaf water potential (ψ_{leaf}) measurements across the five species under control and rainfall exclusion treatments. Scatter plots showing ψ_{leaf} (MPa) for (a) carob, (b) cypress, (c) oak, (d) pine, and (e) pistacia from March to December 2022. Each point represents an individual tree measurement, with control trees denoted by blue circles and drought-treated trees by red squares. Background colors indicate seasons: spring (green, March-May), summer (yellow, June-August), autumn (light red, September-November), and winter (gray, December-February).

4.2. Machine learning classification models

The classification models, however, showed a significant difference among the spectroscopy of drought and control stands (Table 3). The best model was the linear model (LR), with an accuracy of 0.85, a recall of 0.94, and an F1 score of 0.83. LR was the best-performing algorithm even when the number of bands was reduced to 80 % of the most

important bands, from 274 bands to only 21 bands.

The LR was not only the best model, but it also showed to perform extremely accurate in separating drought from control stands, with only few overlapping cases (Fig. 6). Most misclassified cases were within the ± 20 % overlapping zone (i.e., between 0.3 and 0.7; Fig. S2a), with only three false positive (i.e., undetected drought stands) cases (Fig. S2b).

Table 2

Results of two-sided *t*-tests comparing the effects of drought and control treatments on leaf water potential (ψ_{leaf}), transpiration (T_r), and carbon assimilation (A_n) for the five woody species across four seasons. P-values from the *t*-tests are reported, with significant ($p < 0.05$) and marginally significant ($0.1 > p > 0.05$) effects indicated in bold and italics, respectively.

Species	Season	ψ_{leaf} (MPa)	T_r (mmol m ⁻² s ⁻¹)	A_n (μmol m ⁻² s ⁻¹)
cypress	Spring	0.771	0.994	0.275
	Summer	0.070	0.910	0.542
	Autumn	0.127	0.366	0.335
	Winter	0.770	0.603	0.160
oak	Spring	0.751	0.127	0.428
	Summer	0.002	0.026	0.101
	Autumn	0.066	0.133	0.472
	Winter	0.666	0.117	0.309
pine	Spring	0.010	0.249	0.927
	Summer	0.247	0.702	0.274
	Autumn	0.589	0.797	0.577
	Winter	0.672	0.904	0.164
carob	Spring	0.314	0.336	0.021
	Summer	0.963	0.089	0.117
	Autumn	0.212	0.472	0.338
	Winter	0.841	0.040	0.643
pistacia	Spring	0.239	0.348	0.754
	Summer	0.978	0.628	0.635
	Autumn	0.381	0.989	0.294
	Winter	0.459	0.454	0.376

Table 3

Performance metrics of the three machine learning models for binary classification using hyperspectral drone imagery models trained using either the full spectral range (274 bands, 400–1000 nm) or a reduced set of the most important features (determined by feature importance ranking, retaining 80 % of cumulative importance). Each sample represents the spectral signature of an individual tree canopy. The highest score for each performance metric is highlighted in bold.

Performance Metric	Full Spectral Range (274 Bands)			Reduced Features (80 % Importance)		
	LR	SVM	RF	LR (21 Bands)	SVM (13 Bands)	RF (23 Bands)
Accuracy	0.85	0.81	0.59	0.82	0.68	0.62
Recall	0.94	0.85	0.50	0.91	0.82	0.53
Precision	0.78	0.76	0.57	0.76	0.61	0.60
F1 Score	0.85	0.81	0.53	0.83	0.71	0.56

4.3. Satellite synthetic and actual data

The best model for the satellite synthetic data was, in this case, the SVM (Table 4). Statistics show that SVM had a better performance with the bands of almost all the three satellites. However, Venμs outperformed other satellites with an accuracy of 0.74 and F1 of 0.73. There was no significant difference in the importance of the bands, with B12 (900–920 nm) being the most important (10 %), and B2 (400–440 nm), the least (7 %; Fig. S3).

Using the SVM model with the actual Venμs satellite imagery data for December 2017, showed specific areas in all three sites with a high degree of drought-stress risk (red areas in Fig. 7). The RGB images of the same date, however, did not indicate forest decline or particular stands at risk. Nevertheless, the Tzora site exhibited severe tree mortality the following year (as observed in the aerial image and reported by the JNF), almost precisely in the same area predicted to be at high risk by the SVM model. The same observation was made two years later at the Shacharia and Gilboa sites. Once the damage was visible (in the RGB images), the model no longer indicated drought-stress risk zones (Fig. 7).

5. Discussion

Accurate canopy-level detection of incipient drought stress in Mediterranean forest stands is critical for implementing timely intervention strategies in increasingly water-limited environments. This study demonstrates that hyperspectral imaging coupled with advanced machine learning algorithms enables the identification of water stress signatures before conventional physiological metrics indicate drought conditions, representing a promising advancement in precision forest monitoring methodologies.

The rainfall exclusion successfully reduced soil water content by approximately ~47 % in the treatment plots, clearly establishing differential water availability conditions. However, this substantial reduction in water availability did not translate into consistent, detectable differences in physiological parameters for most species and seasons (Table 2). These findings align with previous studies, indicating Mediterranean woody species possess diverse adaptive mechanisms to cope with seasonal water shortages (Klein et al., 2019; Lloret et al., 2004). The observed physiological resilience may be attributed to: (i) leaf-level measurements inadequately capturing integrated canopy responses (Zarco-Tejada et al., 2018), (ii) deep root systems accessing water beyond monitored soil layers (Rog et al., 2021), (iii) efficient water-use strategies maintaining physiological function despite reduced water availability (Brodrribb et al., 2020; Liu et al., 2015), or (iv) the fact that the induced drought was not severe enough to elicit physiological responses.

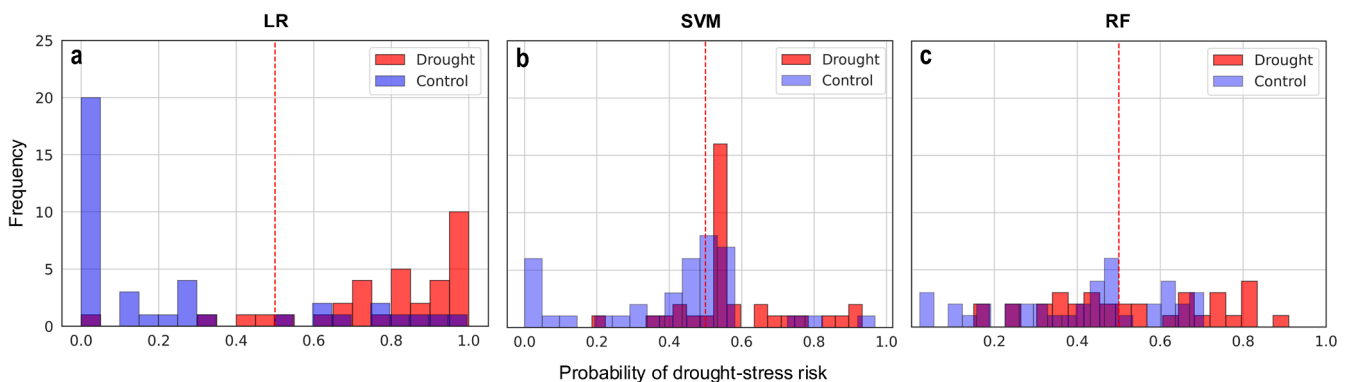


Fig. 6. Histograms showing the frequency of predicted drought-stress risk probabilities for (a) Logistic Regression (LR), (b) Support Vector Machine (SVM), and (c) Random Forest (RF) models applied to the test dataset ($N = 74$). Models were trained using a reduced hyperspectral feature set that contained only the top spectral bands, representing 80 % of the cumulative importance. Blue bars represent control samples and red bars represent drought-treated samples. The vertical dashed red line at 0.5 indicates the classification threshold above which samples were classified as drought-stressed.

Table 4

Performance metrics of the three machine learning models for binary classification using Satellite synthetic bands for PlanetScope, VEN μ S, and Sentinel-2. The highest score for each satellite and metric is highlighted in bold.

Satellite	PlanetScope			VEN μ S			Sentinel-2		
	LR	SVM	RF	LR	SVM	RF	LR	SVM	RF
<i>Accuracy</i>	0.55	0.65	0.61	0.64	0.74	0.54	0.54	0.70	0.51
<i>Precision</i>	0.51	0.63	0.58	0.58	0.70	0.50	0.50	0.66	0.47
<i>Recall</i>	0.68	0.67	0.56	0.74	0.76	0.41	0.62	0.74	0.44
<i>F1 Score</i>	0.58	0.65	0.57	0.65	0.73	0.45	0.55	0.69	0.45

Species-specific sensitivity was evident despite overall resilience. Oak species exhibited lower ψ_{leaf} during the summer and autumn periods (Fig. 5c), while pines showed reduced ψ_{leaf} in spring (Fig. 5d; Table 2). This differential sensitivity is consistent with studies showing that Mediterranean species vary in their hydraulic thresholds and drought response strategies (Italiano et al., 2024; Liu et al., 2015). For instance, while the oak's response here was limited to ψ_{leaf} changes, long-term experimental drought has been shown to significantly reduce aboveground biomass increment in *Quercus ilex* (Liu et al., 2015), indicating that sustained water deficit, even if not immediately reflected in all physiological metrics, can have cumulative impacts on growth. Similarly, the observed spring sensitivity in pines could be an early indicator of this genus's known vulnerability to drought-induced mortality in the region, which often becomes apparent under more severe or prolonged water stress (Klein et al., 2019).

Notably, despite limited detection through conventional physiological measurements, our machine learning models successfully identified distinct spectral signatures associated with rainfall reduction treatment using canopy-level hyperspectral data. This indicates that hyperspectral imaging captures subtle, integrated changes in vegetation optical properties induced by water stress, potentially reflecting biochemical changes, alterations in canopy water content (Asner et al., 2016), or structural adjustments such as changes in LAI (Hernández-Clemente et al., 2014) before pronounced physiological symptoms become apparent at the leaf level (Zarco-Tejada et al., 2018).

The superior performance of the LR model (accuracy = 0.82, recall = 0.91; Table 3) indicates that hyperspectral imagery effectively captures drought-induced vegetation changes, even when conventional physiological measurements detect minimal differences. This linear model outperformed more complex algorithms when applied to high-resolution spectral data. The maintenance of high classification accuracy with only 21 bands reduced from 274 demonstrates the efficiency of targeted spectral monitoring, with important practical implications for operational drought detection systems. The high recall value (0.91) is particularly valuable for early warning systems where missed detections could preclude timely management interventions.

The efficacy of LR with hyperspectral data likely stems from the nature of the classification problem at high spectral resolution. Hyperspectral data retain narrow absorption features that create a nearly linear separation boundary between drought and control classes, allowing a weighted sum of key bands to effectively distinguish between treatments (Peñuelas et al., 1993). Additionally, the L1-regularized LR performs embedded feature selection, making it particularly well-suited for high-dimensional data with hundreds of potentially correlated bands, as evidenced by its robust performance even after dimensionality reduction.

The consistently suboptimal RF performance (accuracy=0.62; Table 3) can be attributed to several factors: tree-split algorithms lack the global regularization necessary for high-dimensional correlated data; with 246 samples distributed across 274 bands, RF requires stronger signals to rise above random splits; and the limited data per terminal node leads to either high-variance predictions or overly pruned trees. These findings contrast with previous studies by Buthelezi et al. (2022) and Mohammed et al. (2022), which reported favorable results using RF for drought classification, though in different forest ecosystems

with larger datasets (Buthelezi et al., 2022; Mohammed et al., 2022).

When extending our approach to satellite-compatible spectral resolutions, the SVM algorithm demonstrated superior performance across all three simulated satellite platforms (Table 4), with VEN μ S satellite bands yielding the best results (accuracy = 0.74, F1 = 0.73). This represents a moderate reduction in performance compared to the full hyperspectral dataset, but remains promising for operational applications given the wider coverage and regular revisit times of satellite platforms. While broader vegetation indices derived from satellites, such as the Vegetation Condition Index (VCI), are used for monitoring general drought conditions across large areas, their performance can vary significantly depending on the region and land cover (Zhang et al., 2017). Our approach focuses on identifying physiological stress spectrally at a finer scale before such indices might show significant changes.

The shift in optimal algorithm from LR with hyperspectral to SVM with satellite-simulated data reflects a fundamental transformation in the classification problem. Aggregated satellite bands blur the narrow absorption features that enable linear separation in hyperspectral data, resulting in classification that now relies on non-linear interactions between bands, which SVM, with its polynomial kernel, can effectively capture. The versatility of SVM for analyzing forest stress using satellite data has also been demonstrated in other contexts, such as detecting frost defoliation (Olano et al., 2021). RF models continued to underperform across all satellite platforms (Table 4), with accuracies ranging from 0.51–0.61, substantially below both SVM and LR models. Even with reduced dimensionality, RF struggled with the same fundamental limitations: our relatively modest sample size ($n = 246$) provided insufficient data for stable tree construction across even the reduced feature space (Barreñada et al., 2024; Han et al., 2021).

The relative uniformity in band importance observed for the VEN μ S satellite, with B12 (900–920 nm) being only marginally more important at 10 % (Figure S3), suggests that the drought signal is distributed across multiple spectral regions rather than concentrated in specific bands.

The model's ability to identify drought-stressed zones 1–2 years before visible forest decline represents the study's most significant contribution. The SVM model applied to VEN μ S satellite imagery successfully predicted areas of high drought-stress risk in all three test sites, which subsequently experienced severe tree mortality (Fig. 7), despite showing no visual symptoms in RGB imagery at the time of prediction.

This early detection capability advances traditional monitoring, extending pre-visual spectral stress detection (Zarco-Tejada et al., 2018) to operational satellite platforms in Mediterranean forests. Notably, the model identified high-risk zones before visible damage appeared but ceased predictions post-decline, indicating sensitivity to active physiological stress rather than advanced symptoms. This temporal specificity aligns with studies linking spectral data and machine learning to physiological indicators, like earlywood hydraulics (Italiano et al., 2023) or ψ_{leaf} (Fishman et al., 2025) in Mediterranean forests, and more broadly to water stress assessments (Sadiq et al., 2023; Virnodkar et al., 2020).

The model's ability to predict drought stress in unseen areas, areas excluded from the training set, indicates its generalization and robustness.

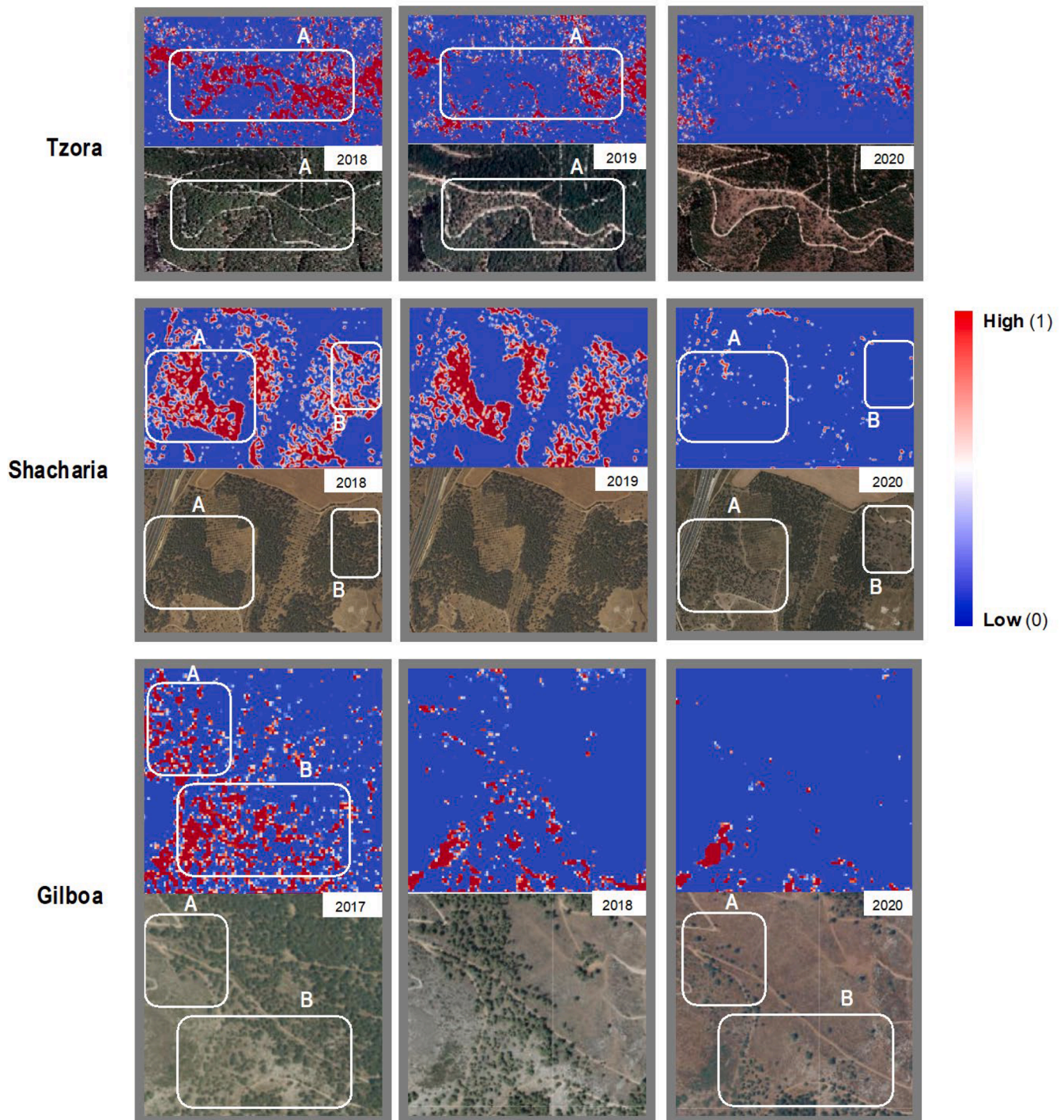


Fig. 7. Application of SVM drought detection model to VEN μ S satellite imagery across three Mediterranean forest sites over multiple years. Each row represents a different forest: Tzora (top), Shacharia (middle), and Gilboa (bottom). Each column shows a different year (the year is indicated at the top right corner) with paired images: upper panels display the model's drought risk prediction (blue = low risk, red = high risk) and lower panels show corresponding RGB satellite imagery. White rectangular outlines (A and B) highlight areas of interest where the model predicted high drought stress risk (red pixels) before visible decline was visible. The color bar on the right indicates drought stress risk probability from 0 (low, blue) to 1 (high, red).

5.1. Limitations and future directions

Several limitations warrant consideration. First, our experimental drought simulation, although substantial, may not fully replicate the complex dynamics of natural drought events, which involve interactions between water limitation, heat stress, and extended duration (Allen et al., 2010; IPCC, 2023). Large-scale natural droughts, such as the 2005 Amazonian event analyzed using MODIS data by Anderson et al. (2010),

often involve widespread, heterogeneous impacts and mortality patterns that are challenging to fully replicate experimentally (Anderson et al., 2010). Second, our model identified drought stress within a single growing season. Yet, longer-term monitoring would enhance understanding of how spectral signatures evolve over extended drought periods and seasonal cycles. Finally, other traits such as changes in leaf, shoot, and vessel size might have helped to detect drought impacts better.

The performance reduction when moving from hyperspectral to multispectral satellite data indicates that some drought-related spectral information is lost at coarser resolutions. Future research should assess model performance over multiple years, explore its applicability in diverse biomes, leverage higher spectral resolution satellite data as they become available, and integrate complementary sensors, such as thermal imaging or LiDAR, to potentially enhance accuracy (Jimenez-Berni et al., 2018; Przeździecki et al., 2023). To enable broader application at larger spatial scales, future work should also incorporate statistical approaches (e.g., spatial autocorrelation or geostatistical modeling) and consider methods for fusing high-resolution UAV data with satellite-based observations through hierarchical modeling or transfer learning frameworks.

6. Conclusions and implications

This study demonstrates that machine learning classification models applied to hyperspectral and multispectral satellite data can effectively detect early signs of drought stress in Mediterranean forests, even when traditional physiological measurements fail to indicate water-related stress. Our findings have several important implications for forest management and conservation strategies.

The early detection capability we demonstrated could significantly improve the timing and targeting of intervention measures, such as selective thinning or emergency irrigation, potentially preventing large-scale forest dieback events. As climate change intensifies drought frequency and severity in Mediterranean regions, such early warning systems become increasingly valuable for preserving forest ecosystem services and biodiversity.

The operational implementation of our approach is facilitated by the developed Streamlit application, available at <https://drought-risk-ml-analyzer.streamlit.app/>, which allows users to upload VENUS or Sentinel-2 satellite data and receive drought risk assessments without specialized remote sensing expertise. This technology transfer addresses a significant gap between research advancements and practical applications.

CRedit authorship contribution statement

Yehuda Yungstein: Writing – review & editing, Writing – original draft, Visualization, Validation, Software, Methodology, Investigation, Formal analysis, Data curation, Conceptualization. **Netanel Fishman:** Writing – review & editing, Visualization, Methodology, Investigation, Formal analysis, Data curation. **Gil Lerner:** Project administration, Data curation. **Gabriel Mulero:** Methodology. **Yaron Michael:** Data curation. **Assaf Yaakobi:** Methodology, Data curation. **Sophie Obersteiner:** Methodology, Data curation. **Laura Rez:** Methodology, Data curation. **Tamir Klein:** Writing – review & editing, Resources, Project administration, Methodology, Investigation, Funding acquisition, Conceptualization. **David Helman:** Writing – review & editing, Writing – original draft, Supervision, Resources, Project administration, Methodology, Investigation, Funding acquisition, Conceptualization.

Declaration of competing interest

The authors declare the following financial interests/personal relationships which may be considered as potential competing interests: David Helman reports financial support was provided by Jewish National Fund. If there are other authors, they declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.

Acknowledgments

We thank Itzik Ben-Shabbat from ICD for helping with the drone and flight permits. We also thank the Jewish National Fund (KKL) for

supporting this study via KKL Chief Scientist Grant #2145 (430/21). N. F. thanks KKL for the Appleby Award. Y.Y. is a Ph.D. student, N.F. is an M.Sc. student, both from the Faculty of Agriculture, Food, and Environment, Hebrew University, under the supervision of D.H. Finally, we want to thank two anonymous reviewers for excellent comments and suggestions that helped us improve the quality of this manuscript.

Supplementary materials

Supplementary material associated with this article can be found, in the online version, at [doi:10.1016/j.agrformet.2025.110855](https://doi.org/10.1016/j.agrformet.2025.110855).

Data availability

Data will be made available on requests.

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